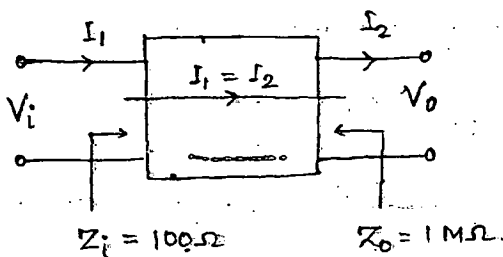


BIPOLAR JUNCTION TRANSISTOR.

Diode Drawbacks :- 1. It can't be amplifier.
2. It can't be inverter.

TWO PORT NETWORK.



$$P_o = I_2^2 Z_o \Rightarrow P_v = \frac{P_o}{P_i}$$

$$P_i = I_1^2 Z_i$$

$$\Rightarrow P_v = \frac{Z_o}{Z_i} = \frac{1 M\Omega}{100\Omega} = 10^4$$

$$\Rightarrow \boxed{P_o > P_i}$$

TRANSISTOR

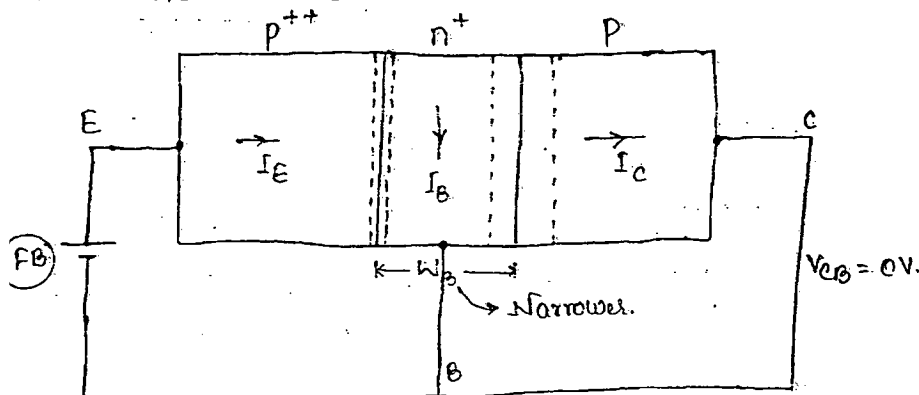
Transfer + resistor

"Transfer of current from one impedance level to other impedance level".

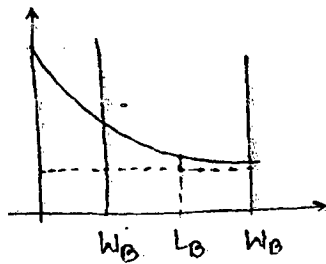
19/10/14.

□ BASIC TRANSISTOR OPERATION.

→ BJT AS A DIODE

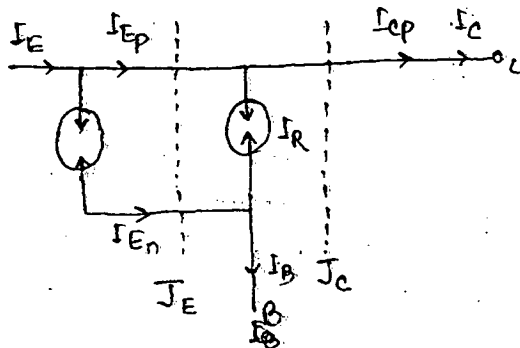


$V_E, V_{EB} = \text{constant}; \frac{W_B}{L_B} \ll 1; V_{CB} = 0.$



$\frac{W_B}{L_B} \ll 1$ (width of the base is narrow).

$$e^{-W_B/L_B} = 1 - \frac{W_B}{L_B} \rightarrow \text{Linear.}$$



I_R = Recombination current.

I_{EP} = diffusion current.

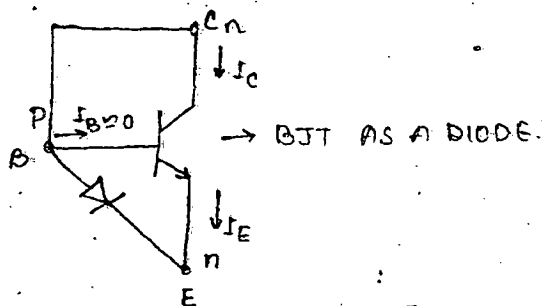
$$I_E \uparrow = I_{EP} \uparrow + I_{EN} (\text{constant})$$

$$I_C \uparrow = I_{CP} \uparrow$$

$$I_B \downarrow = I_R \downarrow + I_{EN} (\text{constant}).$$

$$I_E = I_B + I_C$$

$$I_B \approx 0 \Rightarrow I_E \approx I_C$$



BJT DESIGN PARAMETER.

1. Emitter Injection Efficiency :-

$$\gamma = \frac{I_{EP}}{I_E} \Rightarrow \gamma = \frac{I_{EP}}{I_{EP} + I_{EN}} = \frac{1}{1 + \frac{I_{EN} (\text{constant})}{I_{EP} \uparrow}} \approx 1.$$

$$\gamma \approx 1$$

2. Base Transport Factor (β^*)

$$\beta = \frac{I_{CP}}{I_{EP}}$$

$$\beta = \frac{I_{EP} - I_R}{I_{EP}} = 1 - \frac{I_R \downarrow}{I_{EP} \uparrow} \approx 1$$

$$\beta \approx 1$$

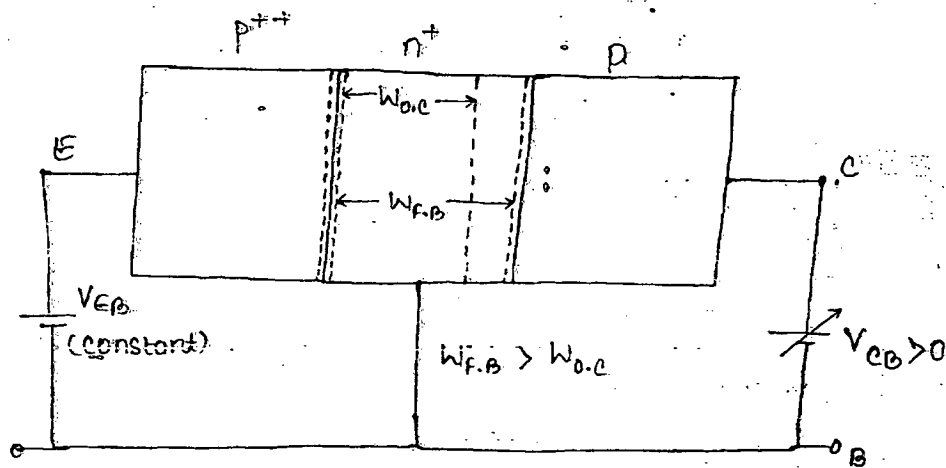
3. current Gain (α)

$$\alpha = \frac{I_C}{I_E}$$

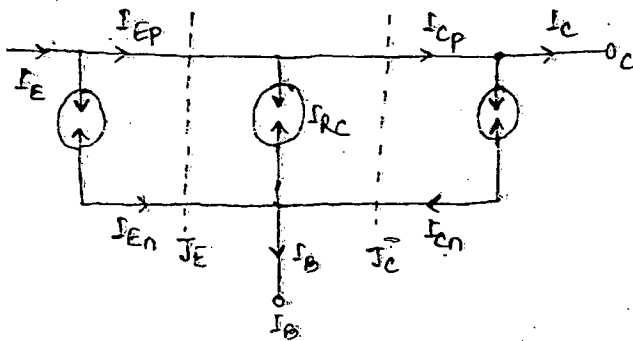
$$\alpha = \frac{I_{CP}}{I_E} = \frac{I_{CP}}{I_{EP}} \cdot \frac{I_{EP}}{I_E} = \beta^* \cdot \gamma$$

$$\alpha = \beta^* \cdot \gamma$$

□ TESTING OF BJT IN SATURATION



$$V_{EB} = \text{constant}; \frac{W_B}{L_B} \ll 1; V_{CB} > 0 \text{ (FB)}$$



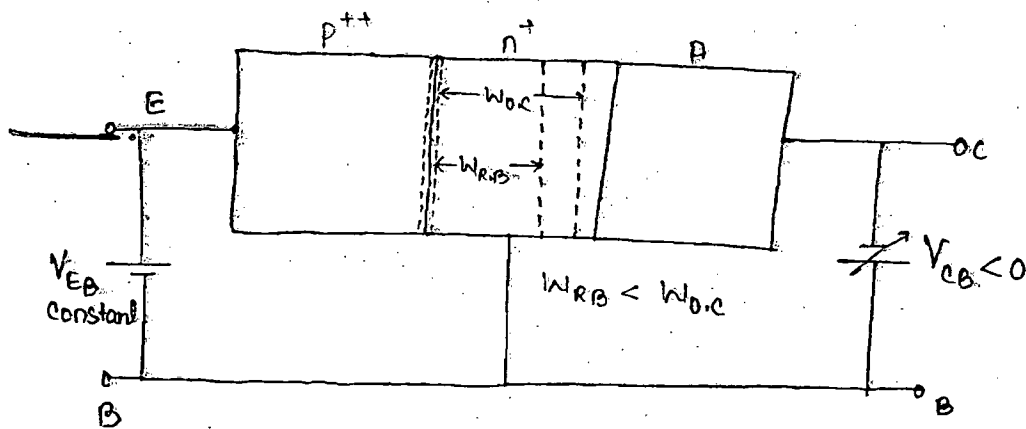
$$I_E \downarrow = I_{EP} \downarrow + I_{EN} \text{ (constant)}$$

$$I_C \downarrow = I_{CP} \downarrow + I_{CN} \uparrow$$

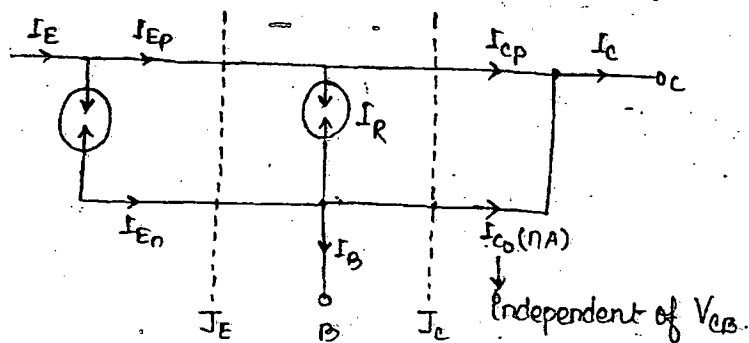
$$I_B \uparrow = I_R \uparrow + I_{CN} \uparrow + I_{EN} \text{ (constant)}$$

BJT is failure in saturation region.

□ TESTING OF BJT IN ACTIVE REGION.



$$V_{EB} = \text{constant} ; \frac{W_B}{L_B} \ll 1 ; V_{CB} < 0 \text{ (RB)}.$$



$$I_E = I_{EP} \uparrow + I_{EN} (\text{constant})$$

$$I_C = I_{CP} \uparrow + I_{C0} (\text{negligible})$$

$$I_B = I_{EN} + I_R \downarrow - I_{C0} (\text{negligible})$$

(const)

$\Rightarrow I_E \approx I_{CP} \rightarrow$ BJT is good in Active Region.

□ DESIGN CONDITION IN BJT.

1. Doping Level :- $\left. \begin{array}{l} N_E \gg N_B \\ N_B > N_C \end{array} \right\}$ Integrated BJT.

$\left. \begin{array}{l} N_E \gg N_B \\ N_B \approx N_C \end{array} \right\}$ Discrete BJT.
(Normal transistor)

2. $\frac{W_B}{L_B} \ll 1 \therefore$

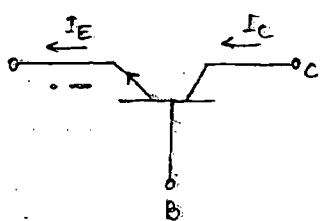
Width of Base should be narrow.

3. Area collector > Area Emitter > Area Base $\therefore$

Power loss across collector > Power loss across Emitter.

BJT CONFIGURATION.

1. COMMON BASE (CB)

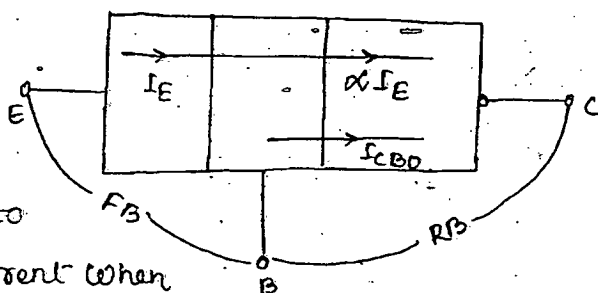


$$\alpha = \frac{I_C}{I_E}$$

$$I_C = \alpha \cdot I_E$$

$$\alpha = 0.9 \text{ to } 0.99$$

Magnitude Analysis :-



Where I_{CBO} = collector to Base leakage current when i/p is open (Emitter)

$$I_C = \alpha I_E + I_{CBO}$$

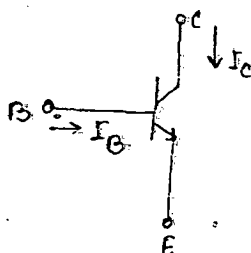
$$I_E = I_B + I_C$$

$$I_C = \alpha (I_B + I_C) + I_{CBO}$$

$$I_C (1 - \alpha) = \alpha I_B + I_{CBO}$$

$$\Rightarrow I_C = \frac{\alpha}{1 - \alpha} I_B + \frac{1}{1 - \alpha} \cdot I_{CBO}$$

2. COMMON EMITTER (CE)



$$\beta = \frac{I_C}{I_B}$$

$$\beta = 20 \text{ to } 500$$

$$\beta = 20 \text{ to } 50 \text{ (Power Amplifier)}$$

$$\beta = 50 \text{ to } 150 \text{ (Voltage Amplifier)}$$

$$\beta = 15 \text{ to } 500 \text{ (Integrated Amplifier OPAMP)}$$

$$\Rightarrow \boxed{\beta = \frac{\alpha}{1-\alpha}} \quad \boxed{\alpha = \frac{\beta}{1+\beta}} \quad \boxed{\frac{1}{1-\alpha} = 1 + \beta}$$

$$I_c = \frac{\alpha}{1-\alpha} \cdot I_B + \frac{1}{1-\alpha} \cdot I_{CBO}$$

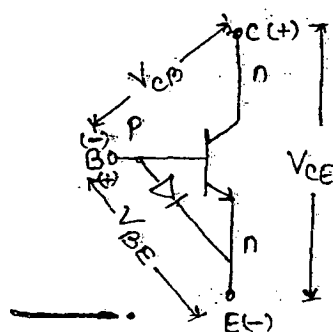
$$I_C = \beta I_B + (1 + \beta) \cdot I_{CBO} \rightarrow CB$$

$$\gamma = \frac{I_E}{I_B}$$

$$\Rightarrow \gamma \approx \beta$$

$$\begin{aligned} Y &= \frac{I_E}{I_B} : \\ &= \frac{I_E}{I_E - I_C} = \frac{1}{1 - \frac{I_C}{I_E}} \\ &= \frac{1}{1 - \alpha} = 1 + \beta \end{aligned}$$

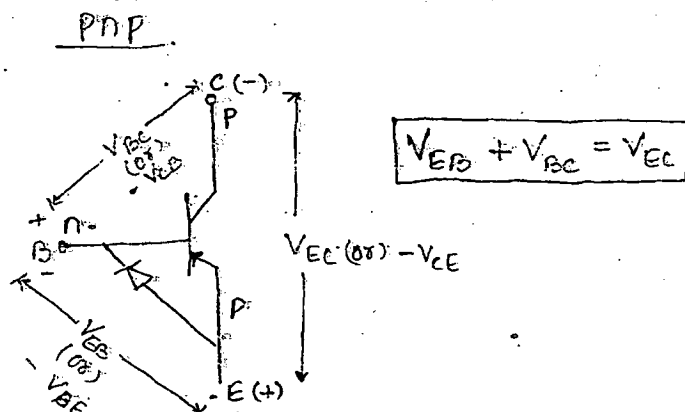
n p n



$$V_{BE} + V_{CB} = V_{CE}$$

iii) V_{BE} & V_{CB}

V_{CE} → Lower
↓
higher
↓
(+)

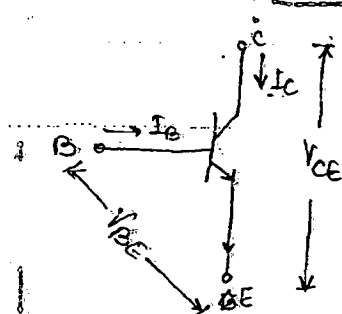


□ BJT OPERATING REGIONS.

REGION	I_E	I_C	
Active Region	FB	RB	Amplifier
Saturation Region	FB	FB	} Switching (NOT)
Cut off Region	RB	RB	
Reverse active region	RB	FB	(X) Attenuator

□ GRAPHICAL ANALYSIS OF BJT.

1. COMMON EMMITER (CE).



Input parameter :- V_{BE} , I_B

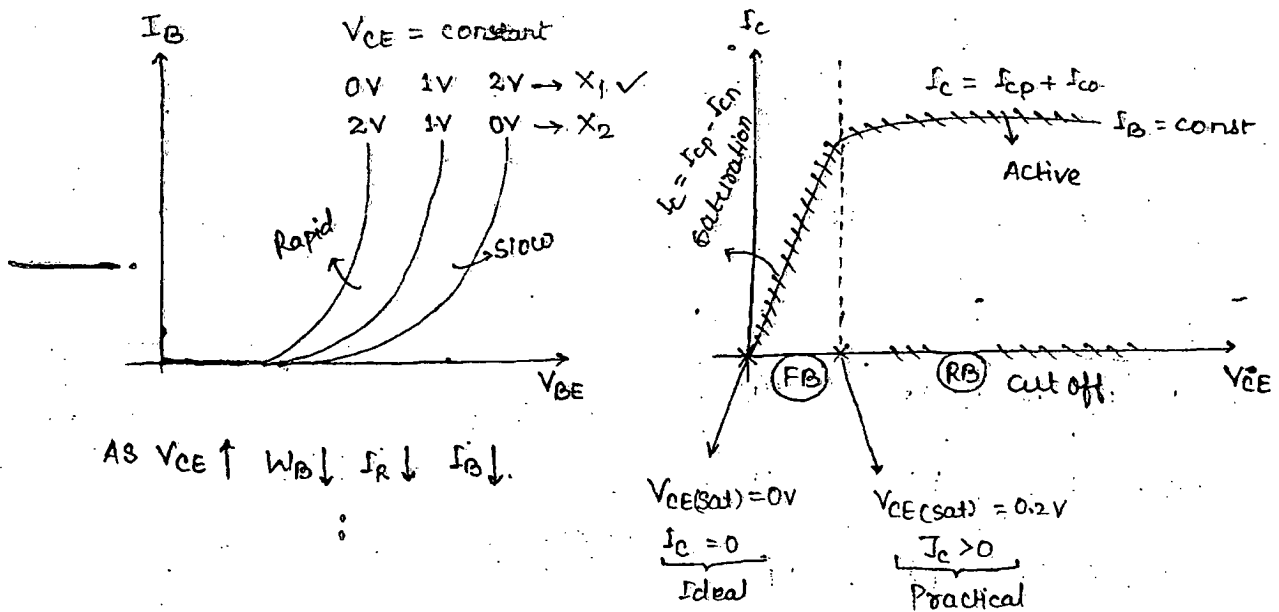
Output parameter :- V_{CE} , I_C

NOTE:- 1. To get the i/p characteristics of BJT o/p voltage should be constant (width of base can change)

2. o/p current can't change i/p current because BJT is a unilateral device.

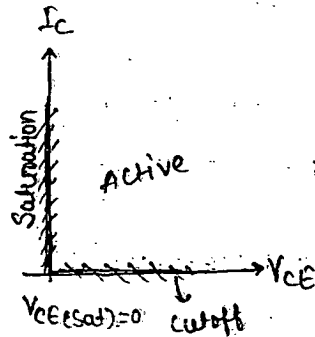
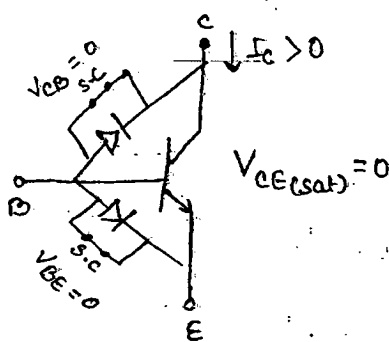
2. To get the o/p characteristics of BJT i/p current should be constant because BJT is a current controlled device.

$\therefore$ i/p impedance is low $\therefore$ ~~here~~ short ckted $\therefore$ current controlled.

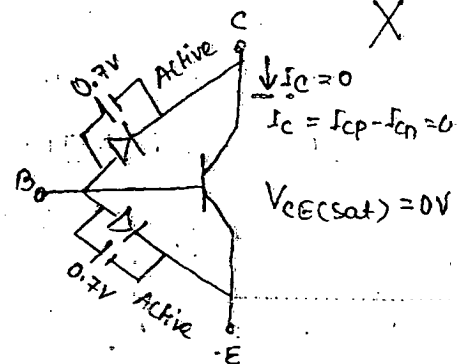


As $V_{CE} \uparrow$ $W_B \downarrow$ $I_R \downarrow$ $I_B \downarrow$.

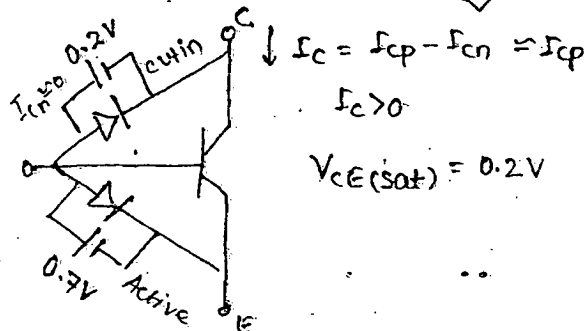
Ideal (Saturation)



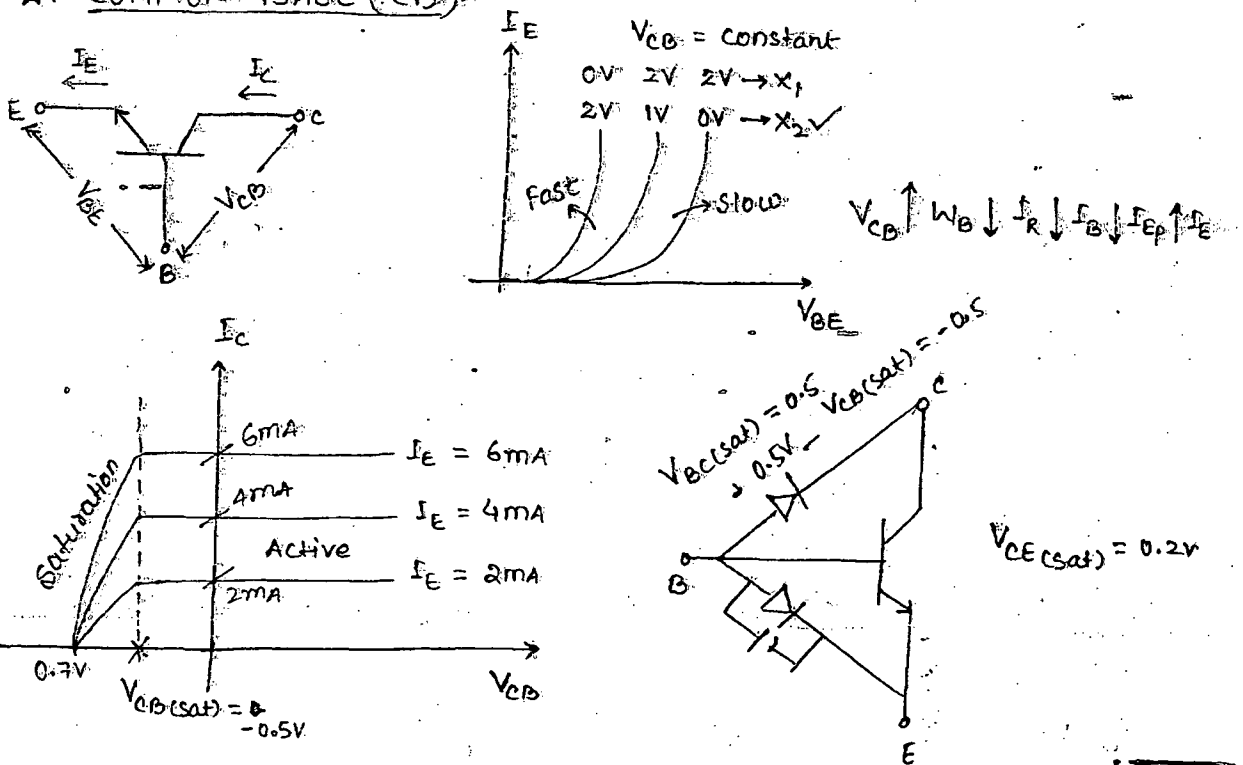
Practical (Saturation)



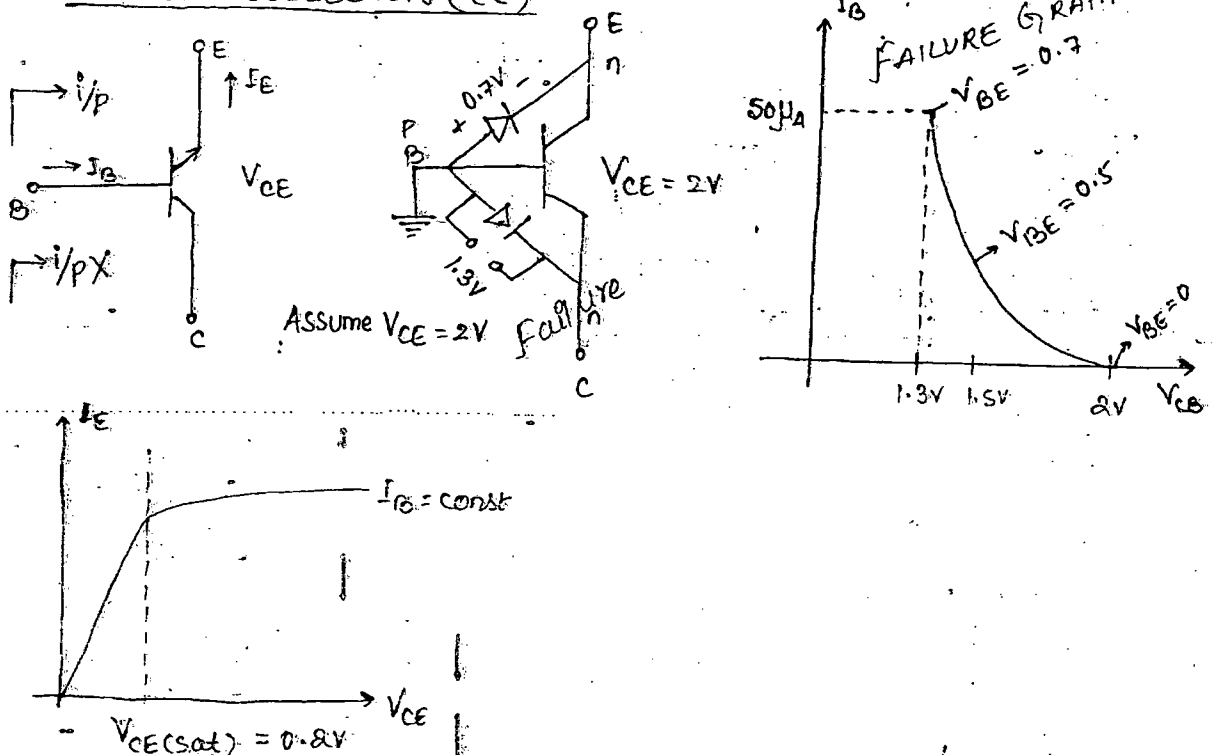
Saturation (Practical) ✓



2. COMMON BASE (CB)

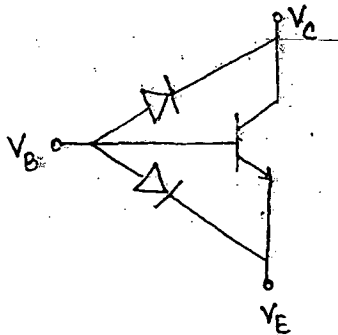


3. COMMON COLLECTOR (CC)



□ TESTING OF BJT IN DIFFERENT OPERATING REGION.

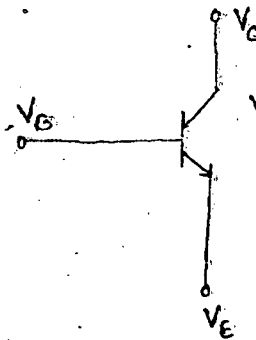
TEST-1



$$\left. \begin{array}{l} V_B > V_E \\ V_B > V_C \end{array} \right\} \text{Saturation}$$

$$\left. \begin{array}{l} V_B > V_E \\ V_B < V_C \end{array} \right\} \text{Active.}$$

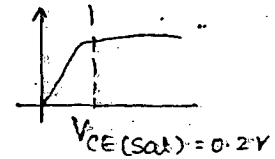
TEST-2



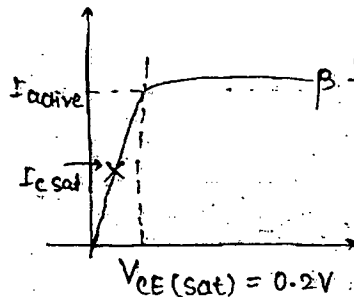
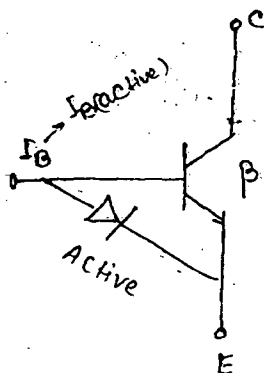
$$V_{CE} = V_C - V_E$$

$$\text{If } V_{CE} > V_{CE(sat)} \rightarrow \text{Active}$$

$$V_{CE} < V_{CE(sat)} \rightarrow \text{Saturation.}$$



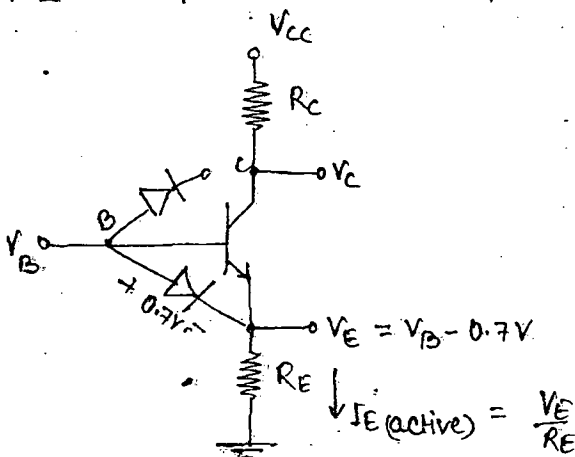
TEST-3



$$I_C = \beta I_B \rightarrow \text{Active}$$

$$I_C < \beta I_B \rightarrow \text{Saturation}$$

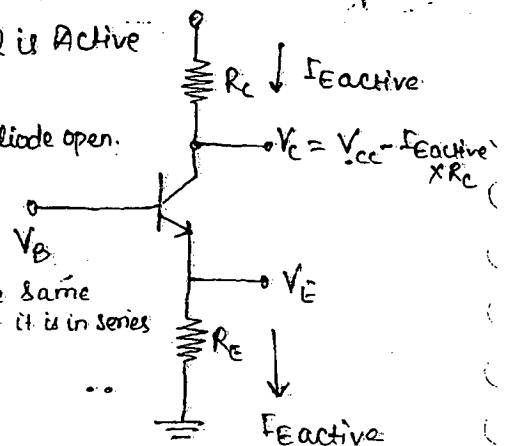
□ WAY OF SOLVING PROBLEM.



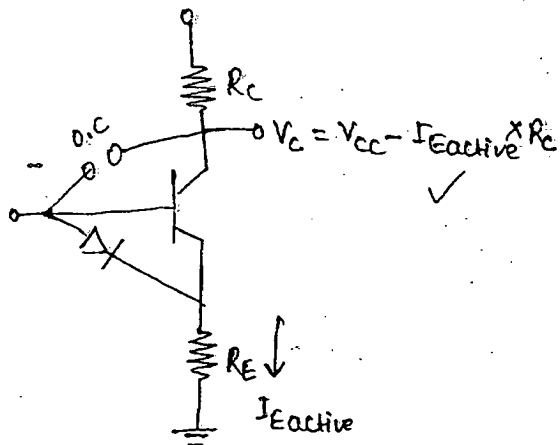
Assume Q is Active

Assume BC diode open.

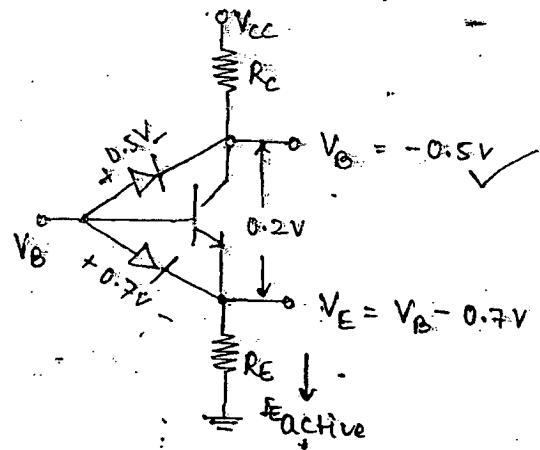
$I_{C(active)}$ will be same because it is in series



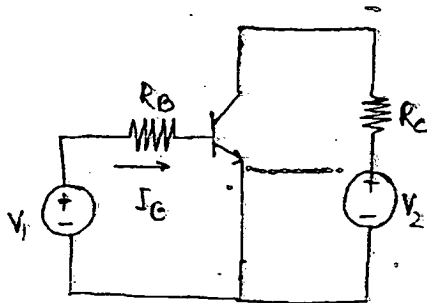
Case I

 $V_C > V_B$ (Active)

Case II

 $V_C < V_B$ (Saturation)

□ DUAL BATTERY DESIGN.



$$V_1 = I_B R_B + V_{BE}$$

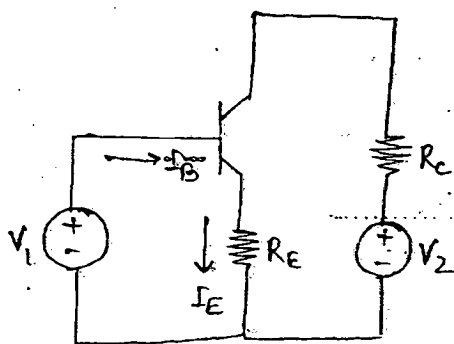
(or)

$$V_1 = I_E \cdot \frac{R_B}{1+\beta} + V_{BE}$$

$$I_E = I_B + I_C$$

$$I_E = I_B + \beta I_B$$

$$I_E = (1+\beta) I_B$$



$$V_1 = I_E R_E + V_{BE}$$

(or)

$$V_1 = I_B (1+\beta) R_E + V_{BE}$$

Ch-4

Q1. I_Q current come from diode.

$$V_E = V_B - 0.7 = 0 - 0.7 = -0.7$$

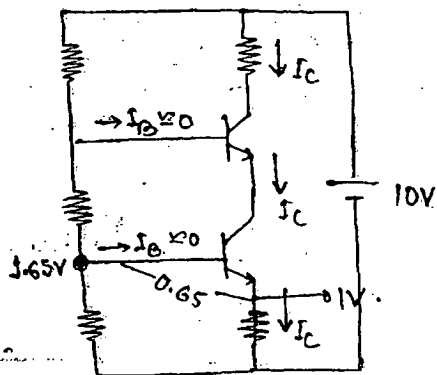
 V_B is grounded

$$\therefore I_Q = 8 \text{ mA}$$

NOTE :- Testing & operating Region depends on two Parameters $\rightarrow$ (1) Vp Battery
(2) Collector Resistor R_c .

ch-4.

Q2.



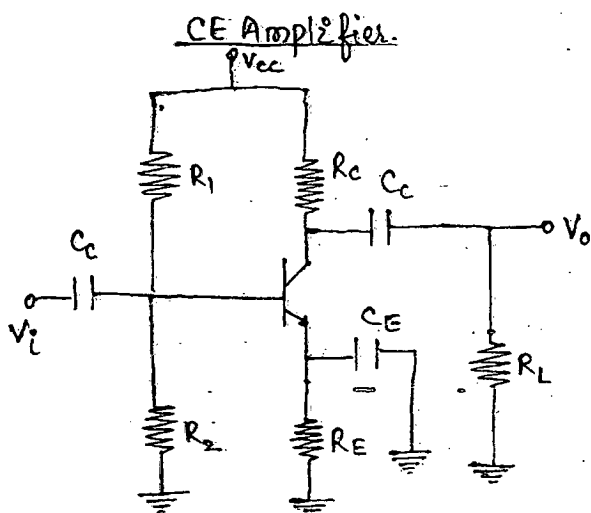
$$V_{BE} = 0.65V$$

$$\beta \text{ is large.} \Rightarrow \beta \uparrow = \frac{I_C}{I_B} \downarrow$$

$$\therefore I_B \approx 0$$

□ BJT BIASING:

$\rightarrow$ DC LOAD LINE AND OPERATING POINT Q.

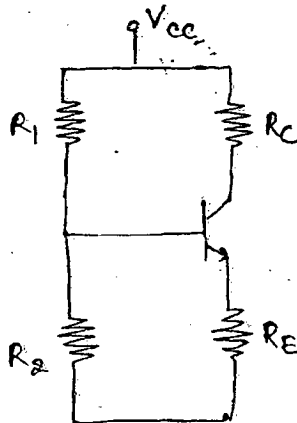


DC Analysis

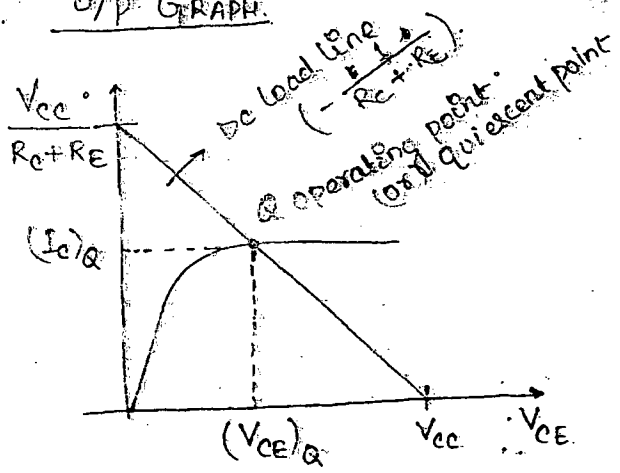
(1) Ac should be grounded.

$$(2) X_C \propto \frac{1}{f} \rightarrow \infty (\text{D.C})$$

DC Model



O/p GRAPH



O/p Loop Equation ($\therefore$ o/p resist in a loop)

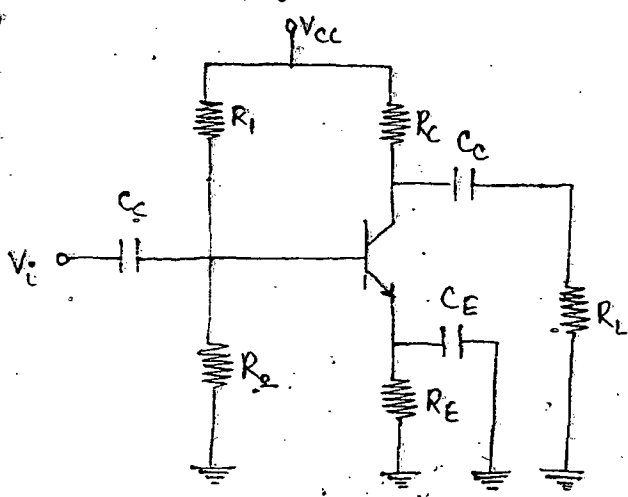
$$V_{CC} = I_C (R_C + R_E) + V_{CE}$$

$$I_C = \left[-\frac{1}{R_C + R_E} \right] V_{CE} + \frac{V_{CC}}{R_C + R_E}$$

$\downarrow$ $\downarrow$ $\downarrow$
 Y M X C

AC LOAD LINE

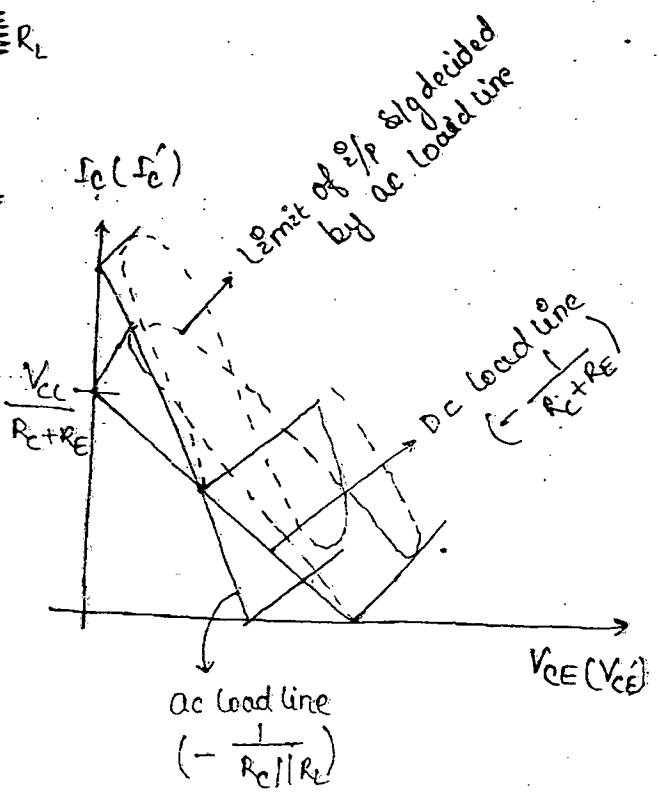
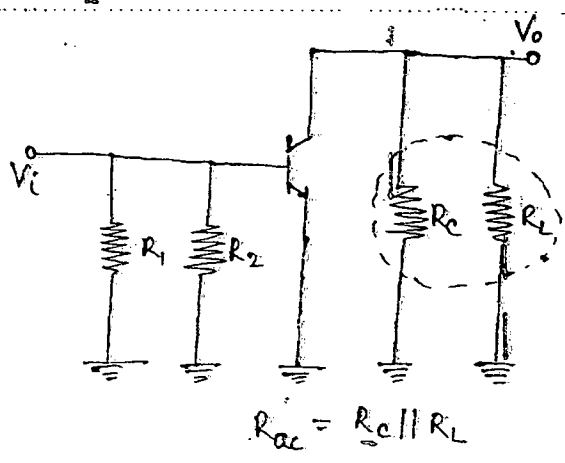
CE Amplifier



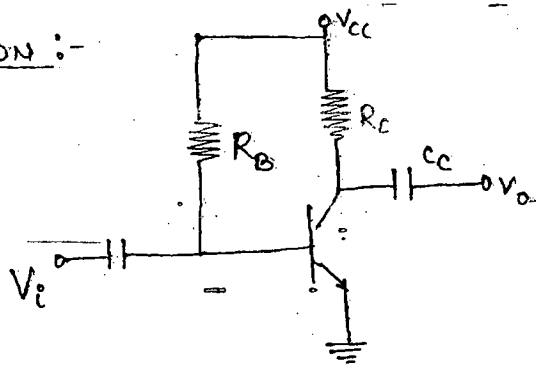
AC Analysis

- (1) DC should be grounded.
- (2) $X_C \propto \frac{1}{f} \rightarrow 0 (s-c)$

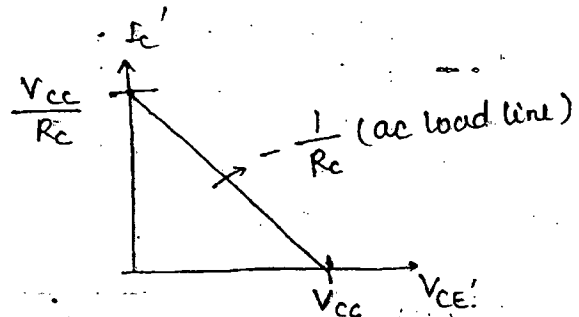
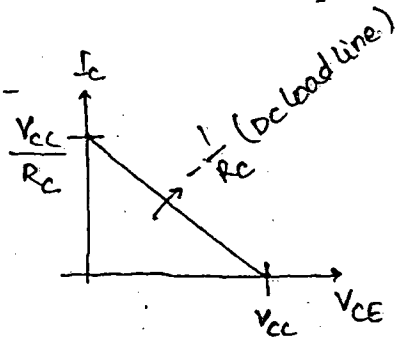
AC Model



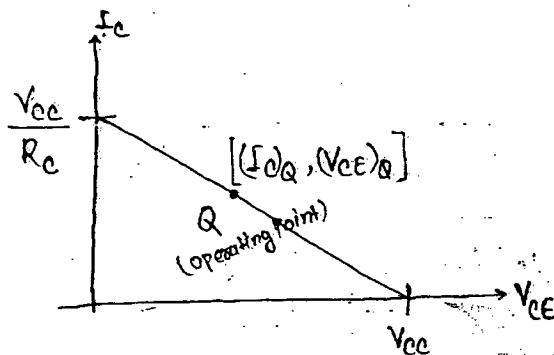
QUESTION :-



SOLUTION :-



→ TEMPERATURE DEPENDENCE ON BJT PARAMETER:



∴ Q is unstable.

$(I_c)_Q$ depends upon :-

(1) I_{CO} ; $I_E = \beta I_B + (1 + \beta) I_{CO}$

(2) V_{BE} ; $I_C = I_0 e^{V_{BE}/V_T}$

(3) $I_C = \beta I_B$

$I_E = \frac{I_0 e^{V_{BE}/V_T}}{\text{diode eqn}}$

→ BIASING.

It is a technique of circuit which makes the operating point stable w.r.t temperature variation.

1. I_{CO} VS TEMPERATURE.

I_{CO} increases by 7% for every $^{\circ}C$ rise in temperature.
'OR'

I_C doubles for every $10^{\circ}C$ rise in temperature.

2. V_{BE} VS TEMPERATURE.

$$\frac{dV_{BE}}{dT} = -2.5 \text{ mV}/^{\circ}C. \quad T \uparrow ; V_{BE} \downarrow ; I_C \downarrow.$$

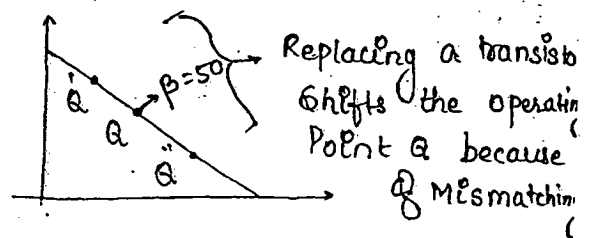
3. β VS TEMPERATURE

(a) β VS Temperature

$$\beta = \frac{I_C}{I_B}$$

$T \uparrow \quad I_{CO} \uparrow \quad I_C \uparrow \quad \beta \uparrow$
(Neglected)

(b) β Replacement Problem.



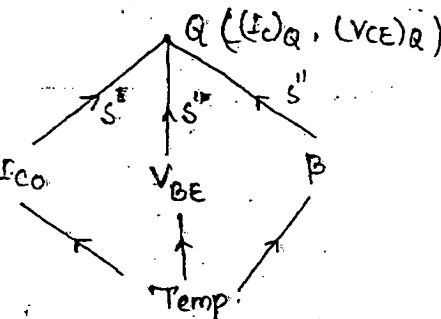
4. STABILITY FACTOR. (S)

It is measure of variation of Q-point with respect to temperature.

$$S' = \left. \frac{\partial I_C}{\partial I_{CO}} \right|_{V_{BE}, \beta \text{ const}}$$

$$S' = \left. \frac{\partial I_C}{\partial V_{BE}} \right|_{I_{CO}, \beta \text{ const}}$$

$$S'' = \left. \frac{\partial I_C}{\partial \beta} \right|_{I_{CO}, V_{BE} \text{ const}}$$



S Factor :- $I_C = \beta I_B + (1 + \beta) I_{CO}$
d. w.r to I_C

$$\Rightarrow 1 = \beta \frac{\partial I_B}{\partial I_C} + (1 + \beta) \left(\frac{\partial I_{CO}}{\partial I_C} \right) \frac{1}{S}$$

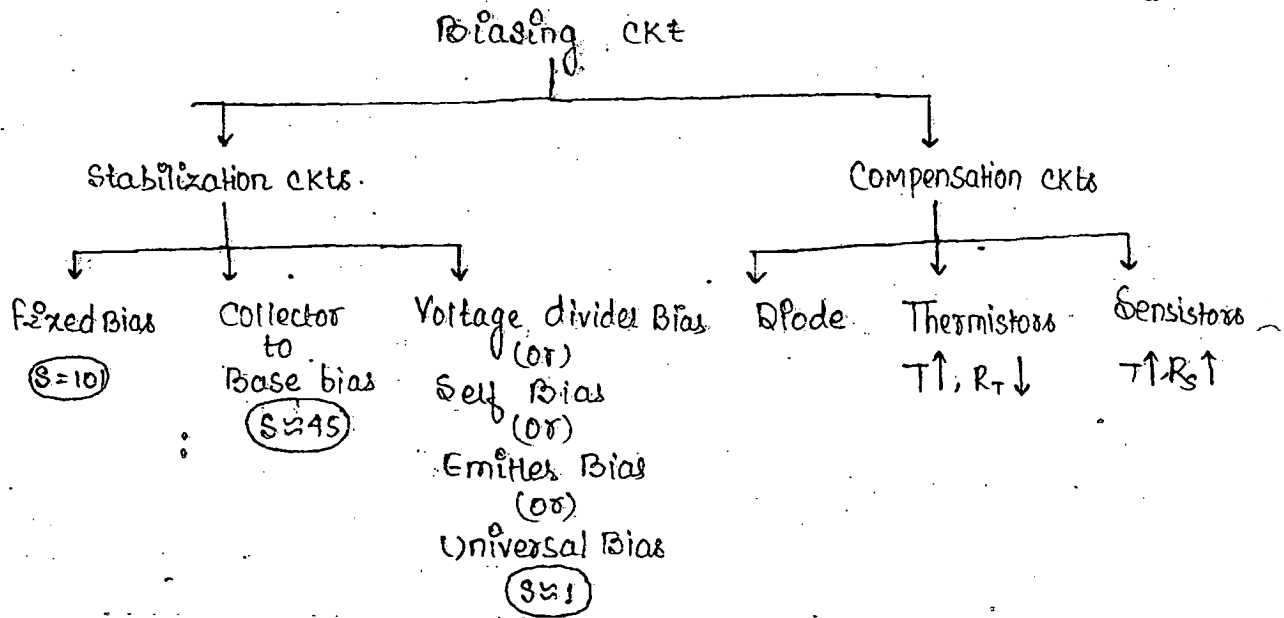
$$S = \frac{1 + \beta}{1 - \beta \frac{\partial I_B}{\partial I_C}}$$

conclusion:- 1. The most dominate parameter w.r.t temp

is I_{co} .

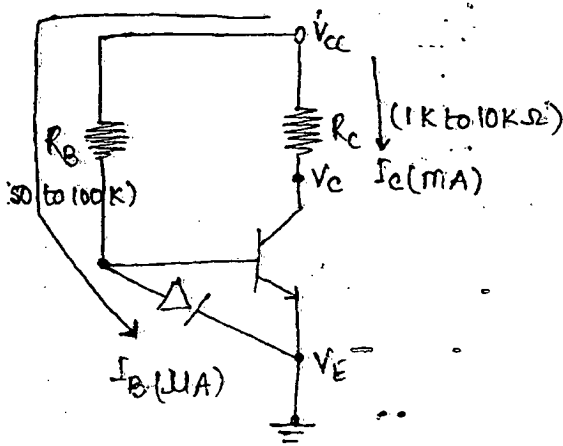
2. Ideally the Stability Factor should be zero.

Practically it should be minimum in value.



1. FIXED BIAS

Single Supply Design

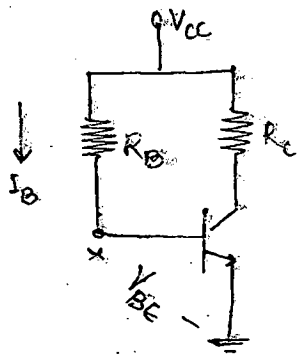


$$\frac{R_B}{R_C} \gg 1$$

$$(V_{CE})_Q = \frac{V_{CC}}{2}$$

$$V_B > V_E$$

$$V_C > V_B \rightarrow \text{Active Region.}$$



I/P Loop

$$V_{CC} = I_B R_B + V_{BE}$$

$$I_B = \frac{V_{CC} - V_{BE}}{R_B} \rightarrow \text{Fixed.}$$

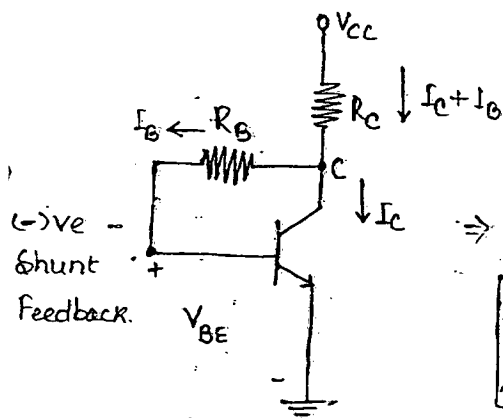
fixed

$$I_C = \beta I_B \rightarrow \text{Fixed}$$

S Factor :- $S = \frac{1 + \beta}{1 - \beta \frac{\partial I_B}{\partial I_C}} \Rightarrow I_B = \frac{V_{CC} - V_{BE}}{R_B} \Rightarrow \text{d.w.r. to } I_C$

$$\frac{\partial I_B}{\partial I_C} = 0 \Rightarrow S = 1 + \beta$$

2. COLLECTOR TO BASE BIAS.



I/P Loop

$$V_{CC} = (I_B + I_C) R_C + I_B R_B + V_{BE}$$

$$\Rightarrow V_{CC} = I_B (R_B + R_C) + I_C R_C + V_{BE}$$

$$I_B = \frac{V_{CC} - I_C R_C - V_{BE}}{R_B + R_C}$$

O/P Loop

$$\Rightarrow V_{CC} = R_C (I_C + I_B) + V_{BE}$$

$$\Rightarrow V_{CC} - I_C R_C = V_{BE} + I_B R_C$$

$$I_B = \frac{V_{CC} - I_C R_C - V_{BE}}{R_B + R_C}$$

Stabilization.

$$T \uparrow; I_{CO} \uparrow; I_C \uparrow; (I_C + I_B) R_C \uparrow; V_{CE} \downarrow; I_B \downarrow; I_C \downarrow$$

$$I_B \propto V_{CE}$$

S-factor.

$$V_{CC} = I_B(R_B + R_C) + I_C R_C + V_{BE} \rightarrow \text{i/p loop.}$$

d. w.r. to I_C

$$\Rightarrow 0 = \frac{\partial I_B}{\partial I_C} (R_B + R_C) + R_C + 0$$

$$\Rightarrow \frac{\partial I_B}{\partial I_C} = - \frac{R_C}{R_B + R_C}$$

$$S = \frac{1 + \beta}{1 + \beta \cdot \frac{R_C}{R_B + R_C}}$$

$$S = \frac{(1 + \beta) \cdot (R_B + R_C)}{R_B + (1 + \beta) R_C}$$

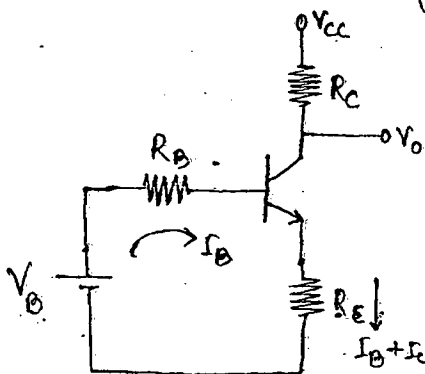
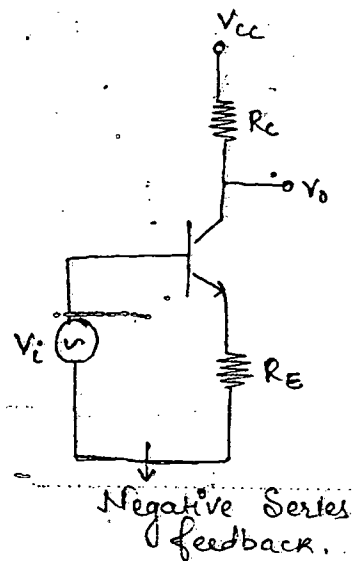
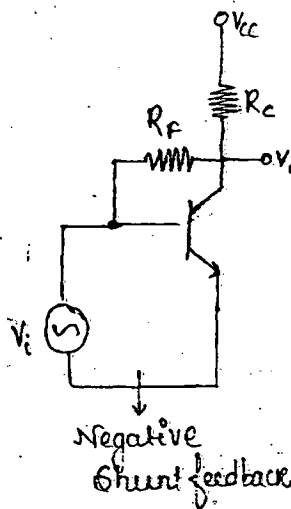
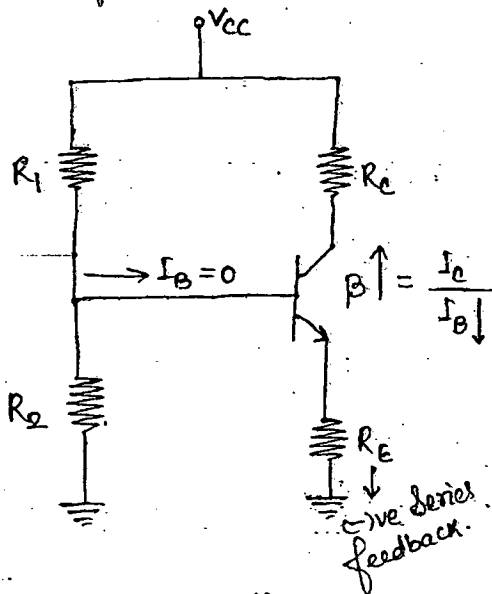
$$\Rightarrow S = \frac{(1 + \beta) \cdot R_C \left[1 + \frac{R_B}{R_C} \right]}{R_C \left[1 + \beta + \frac{R_B}{R_C} \right]}$$

$$\Rightarrow \frac{R_B}{R_C} \ll 1$$

$$S \approx 1$$

Against assumption $\therefore$ Failure.

3. VOLTAGE DIVIDER BIAS.



$$V_B = \frac{V_{CC} \times R_2}{R_1 + R_2}$$

$$R_B = R_1 \parallel R_2$$

i/p Loop.

$$V_B = I_B R_B + V_{BE} + (I_B + I_C) R_E$$

$$V_B = I_B (R_B + R_E) + I_C R_E + V_{BE}$$

d. w.r I_C

$$\Rightarrow 0 = \frac{\partial I_B}{\partial I_C} (R_B + R_E) + R_E + 0$$

$$\frac{\partial I_B}{\partial I_C} = \frac{-R_E}{R_B + R_E}$$

$$\Rightarrow S = \frac{(1+\beta)(1 + \frac{R_B}{R_E})}{1 + \beta + \frac{R_B}{R_E}}$$

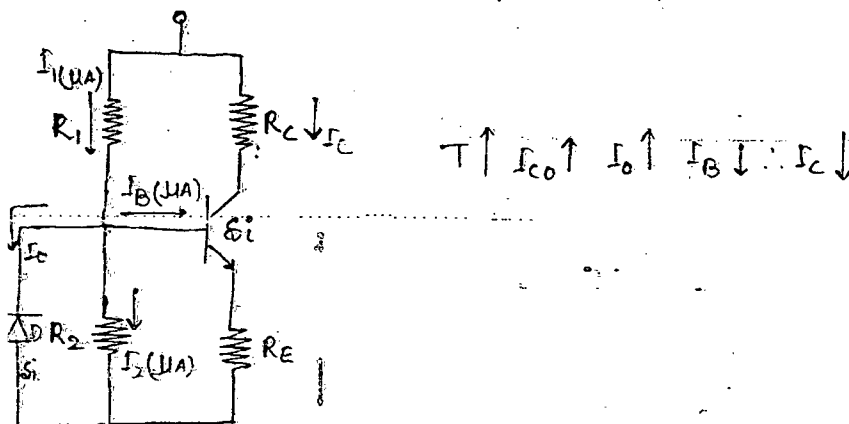
$$\Rightarrow \boxed{\frac{R_B}{R_E} \ll 1} \quad ; \quad \boxed{S \approx 1}$$

DESIGN CONDITIONS.

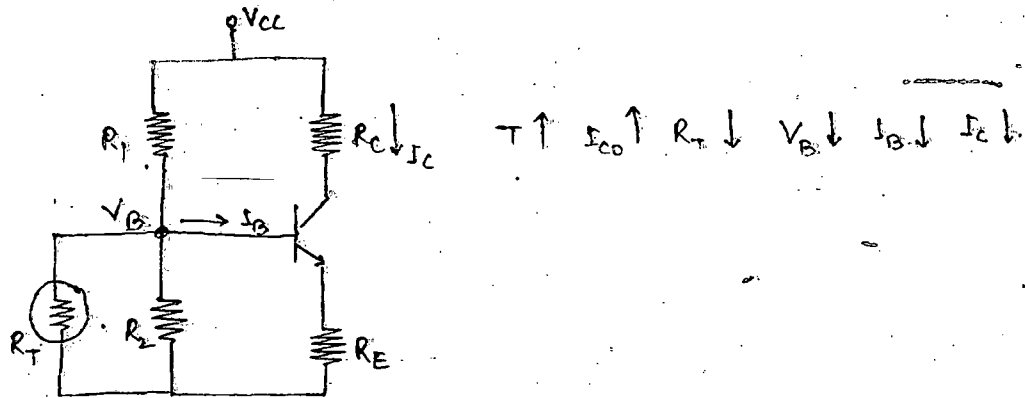
1. If $\frac{R_B}{R_E} \ll 1$; the stability factor is nearer to unity.
2. To get R_B value less take a condⁿ $R_1 > R_2$.
3. If R_E increases (-)ve feedback in the ckt increases which will affect the S/g gain in a.c analysis.
To solve this problem take a capacitor in parallel to feedback resistor R_E .

$$4. \frac{R_B}{(1+\beta)R_E} \ll 1 \quad ; \quad \boxed{R_B \ll (1+\beta)R_E}$$

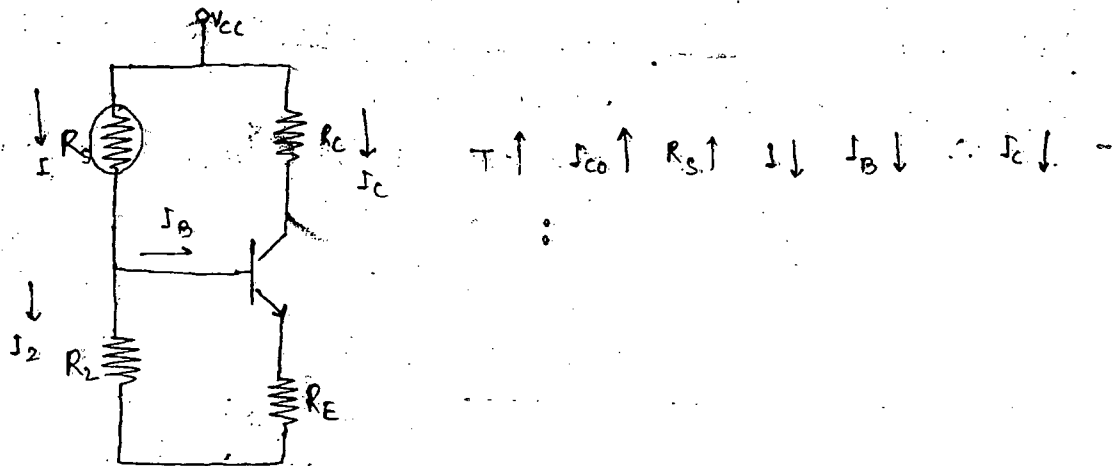
□ COMPENSATION THROUGH DIODE.



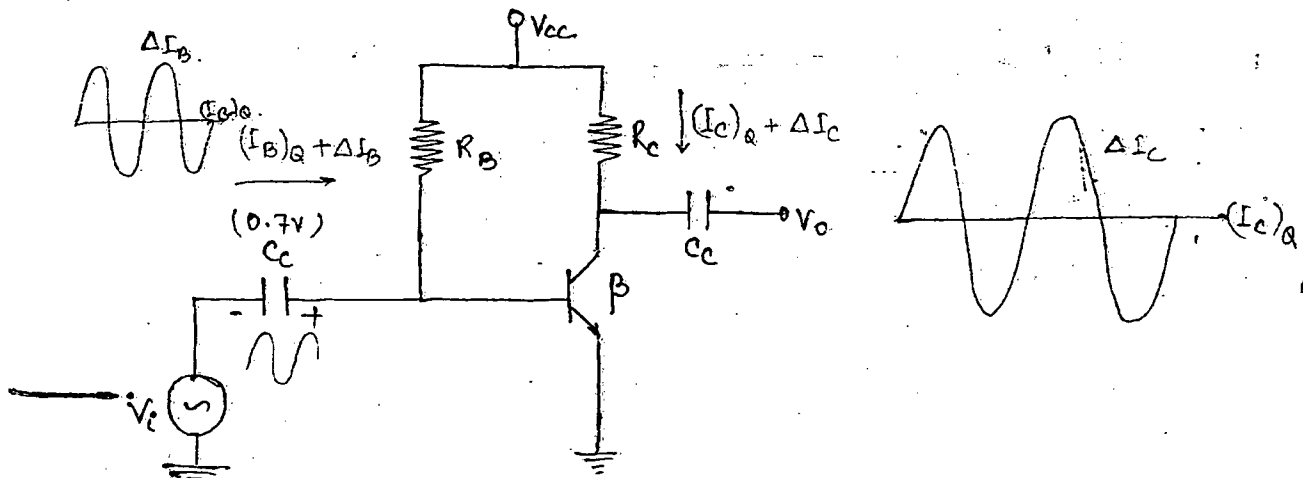
2. COMPENSATION THROUGH THERMISTOR.

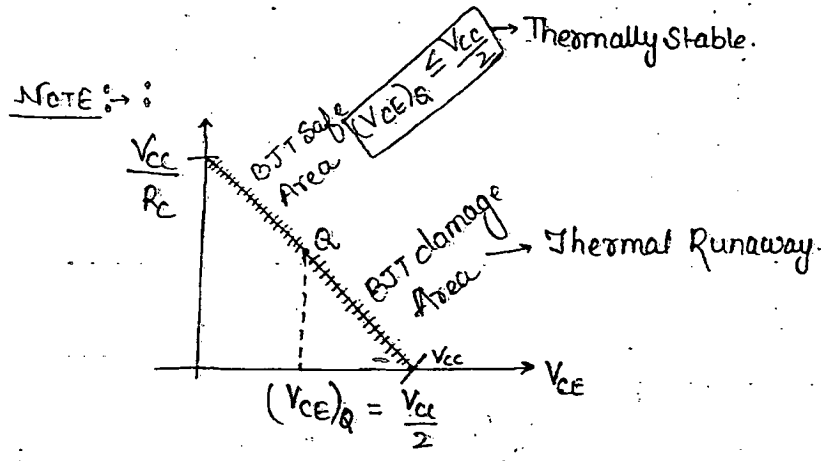
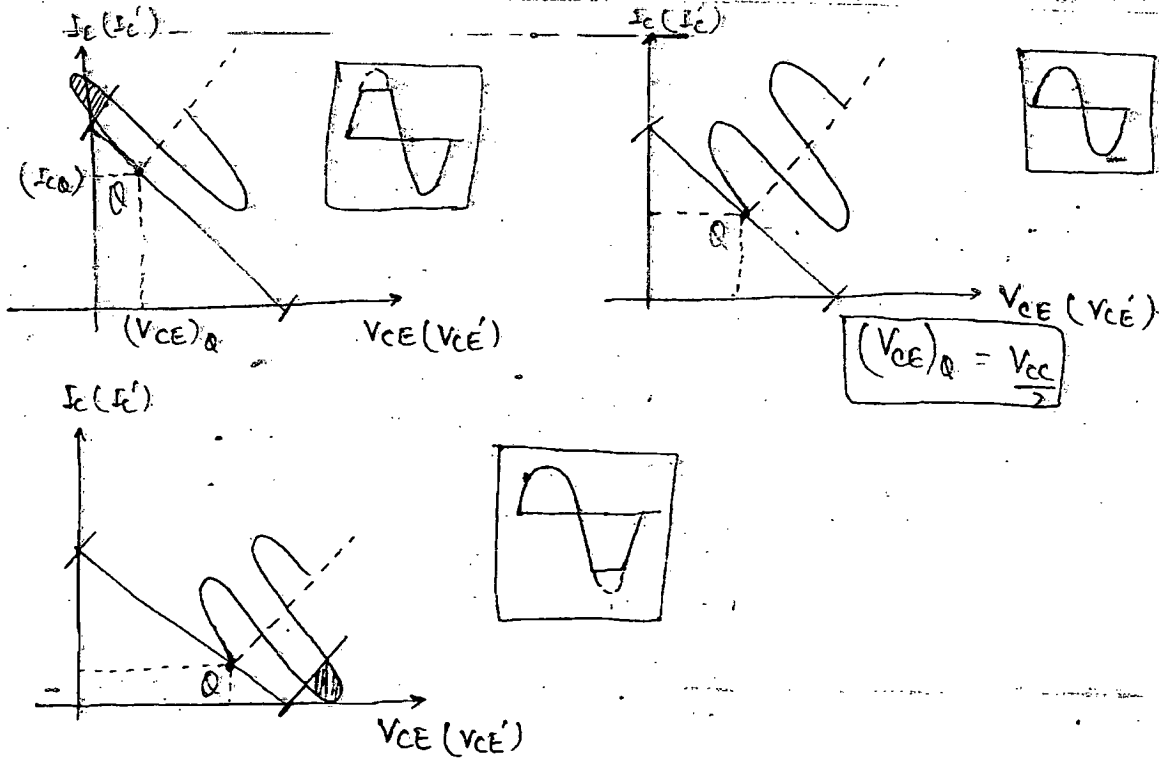


3. COMPENSATION THROUGH SEMISTOR.

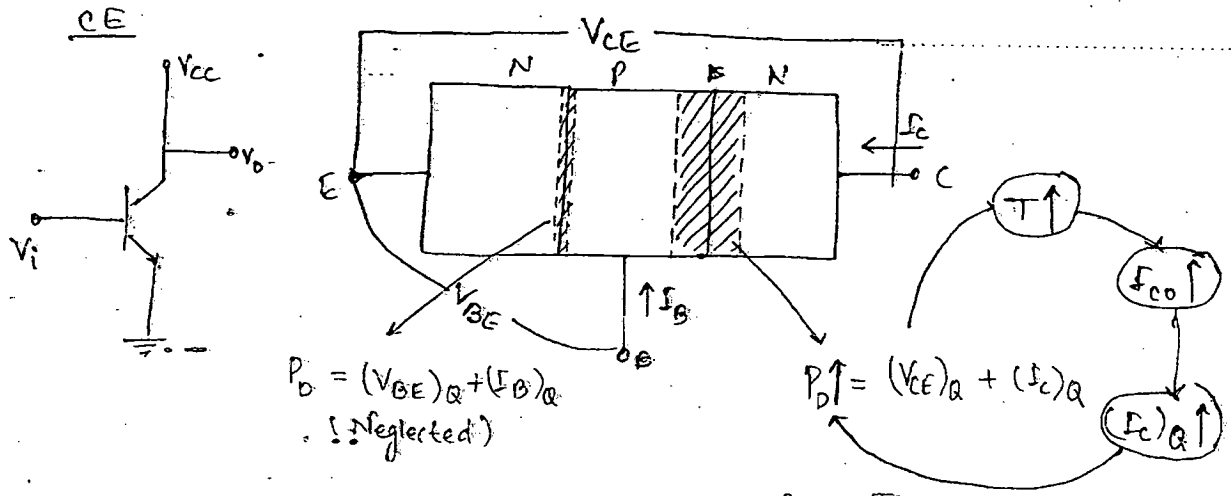


4. POSITION OF OPERATING POINT ON DC LOAD LINE.

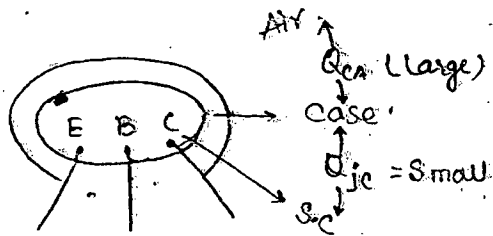




□ THERMAL RUNAWAY IN BJT.



□ PRACTICAL VOLTAGE TRANSISTOR DESIGN.



$$T_j - T_A = \theta P_D$$

$$T_j - T_A = \theta P_D$$

Where : T_j = Junction Temperature.

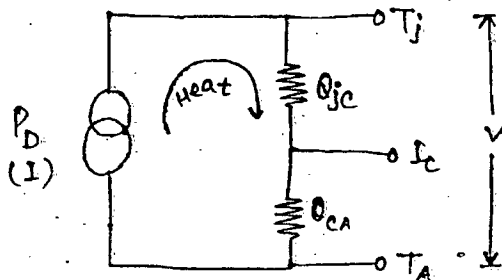
T_A = Ambient Temperature.

P_D = Power Dissipation

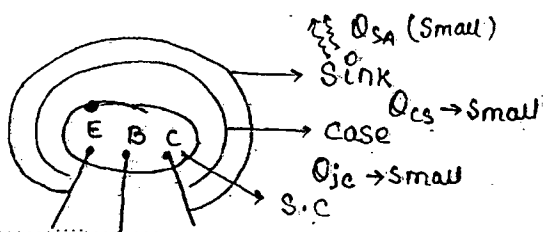
θ = Thermal Resistance

$$P_D = \frac{T_j - T_A}{\theta} \text{ mW}$$

$\theta_{jc} + \theta_{ca} \text{ (large)}$



□ POWER TRANSISTOR DESIGN

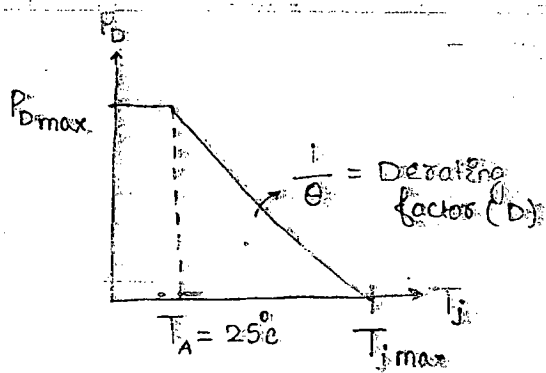


$$P_D = \frac{T_j - T_A}{\theta} \text{ Watt}$$

$\theta_{jc} + \theta_{cs} + \theta_{sa}$
Small

QUESTION :- Design a voltage transistor with a max^m power dissipation $P_{D \max} = 100 \text{ mW}$ and Temp $T_{j \max} = 200^\circ \text{C (sc)}$

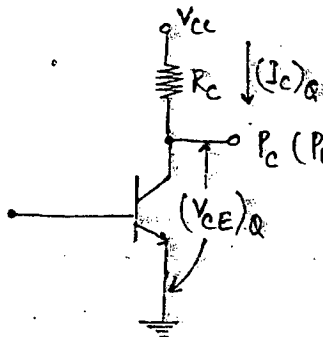
SOLUTION :-



$$\theta = \frac{T_J - T_A}{P_D} \quad ^\circ C/mW$$

$$\Rightarrow \frac{1}{\theta} = D = mW/^\circ C$$

Power Dissipation P_D



P_C (Power generated at collector) = $V_{CC}(I_C)_Q - (I_C)_Q^2 R_C$

$$= (I_C)_Q \{ V_{CC} - (I_C)_Q R_C \}$$

$$= (V_{CE})_Q \times (I_C)_Q = P_D$$

$$\frac{\partial P_C}{\partial T_J} < \frac{1}{\theta} \rightarrow \text{Thermal Stability}$$

$$\frac{\partial P_C}{\partial T_J} > \frac{1}{\theta} \rightarrow \text{Thermal Runaway}$$

□ CONDITION FOR THERMAL STABILITY.

$$\frac{\partial P_C}{\partial T_J} < \frac{1}{\theta} \Rightarrow \frac{\partial P_C}{\partial T_J} = \frac{\partial P_C}{\partial I_C} \cdot \frac{\partial I_C}{\partial I_{CO}} \cdot \frac{\partial I_{CO}}{\partial T_J}$$

1. $P_C = V_{CC} I_C - I_C^2 R_C$
d.w.r. to I_C

2. $\frac{\partial I_C}{\partial I_{CO}} = S$

3. $\frac{\partial I_{CO}}{\partial T_J} = 0.07 I_{CO}$

$$\frac{\partial P_C}{\partial I_C} = V_{CC} - 2 I_C R_C$$

$$(V_{CC} - 2 I_C R_C) \times S \times 0.07 I_{CO} < \frac{1}{\theta}$$

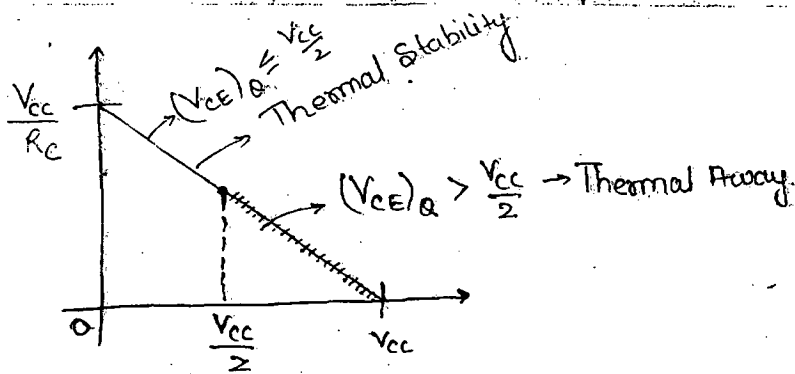
$\downarrow$ (-)ve $\downarrow$ Temp $\downarrow$ (+)ve

$$V_{CE} = V_{CC} - I_C R_C$$

$$2 V_{CE} = 2 V_{CC} - 2 I_C R_C$$

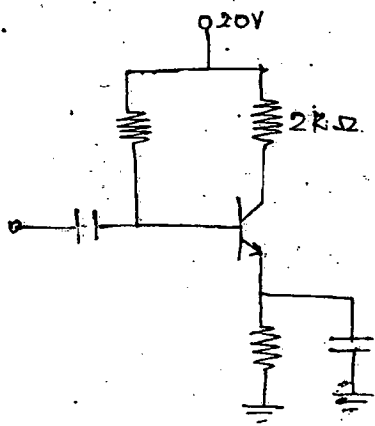
$$2 V_{CE} = V_{CC} = V_{CC} - 2 I_C R_C$$

$$\Rightarrow (2(V_{CE})_Q - V_{CC}) \times S \times 0.07 I_{CO} < \frac{1}{\theta}$$



Ch-5

Q9.



If Notation is in capital letters then it is DC.

$$I_C = I_B = \frac{20 - 0.7}{430K + (1+50)1K}$$

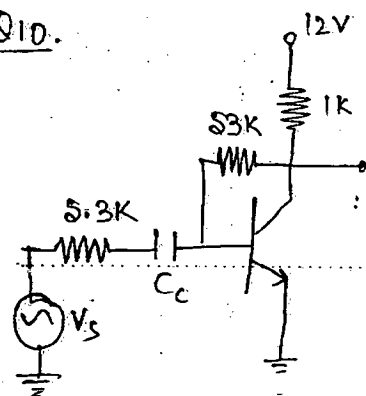
$$I_B = 40 \mu A.$$

$$I_C = \beta I_B.$$

$$\Rightarrow I_C = 50 \times 40 = 2 mA.$$

$\therefore V_C = 16V$

Q10.



$V_{CE} \rightarrow$ capital letters $\rightarrow$ DC

$(h_{ie} \rightarrow \infty, h_{fe} \rightarrow \infty) \rightarrow AC \rightarrow$ No use.

$$I_B = \frac{12 - 0.7}{53K + (1+60)1K}$$

$$I_B = 99 \mu A.$$

$$I_C + I_B = 6 \mu A$$

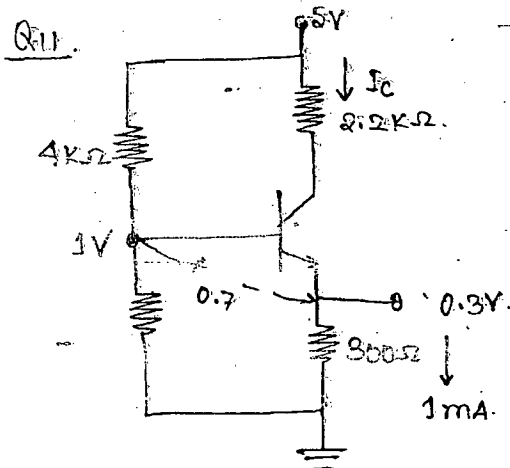
$$\Rightarrow V_{CE} = 6V.$$

$$\Rightarrow I_B = \frac{12 - 0.7}{53K + (1+60)1K}$$

$$I_B = 99 \mu A.$$

$$I_C + I_B = 6 \mu A$$

$$\Rightarrow V_{CE} = 6V.$$



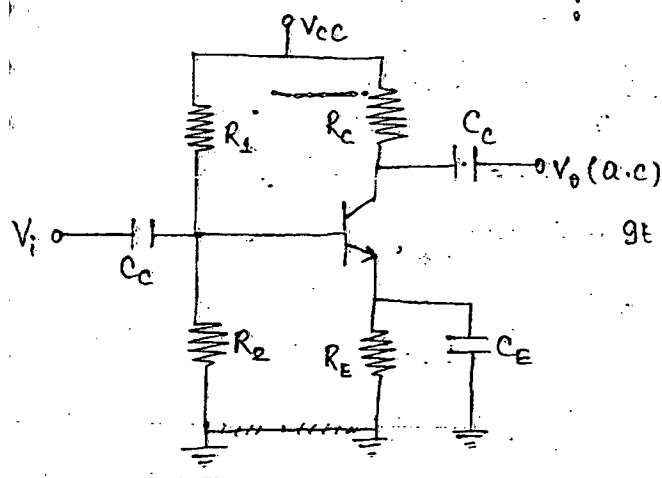
$\therefore \beta$ is very large.
 $\therefore I_B \approx 0$.

$$V_{CE} = 2.5V$$

□ APPLICATIONS OF BJT.

1. COMMON EMITTER.

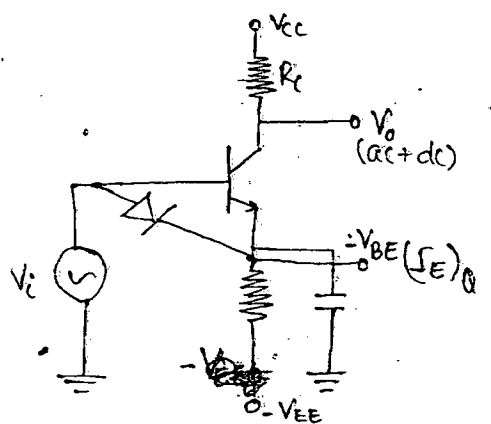
RC COUPLED / SMALL SIGNAL / VOLTAGE AMPLIFIER / AC AMPLIFIER.



Require single battery.

It is used in noise amplification.

DIRECT COUPLED / DC AMPLIFIER / INTEGRATED AMPLIFIER.

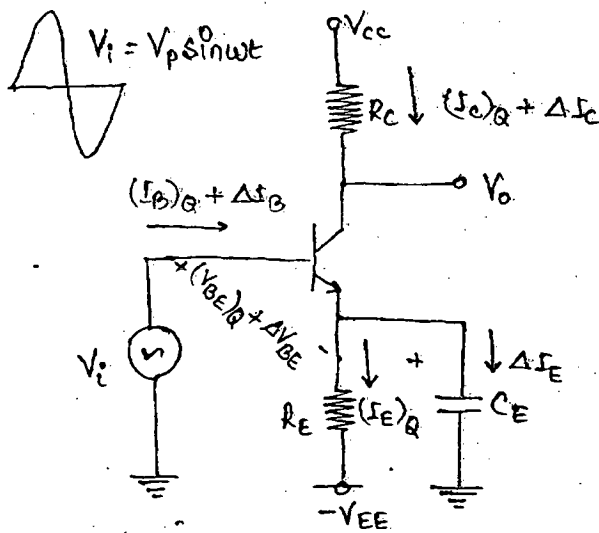


Require two battery.

It gives high Gain.

$$V_{BE}(I_E) = \frac{V_{EE} - V_{BE}}{R_E}$$

COMMON EMITTER AMPLIFIER ANALYSIS.



$$(I_C)_Q + \Delta I_C = I'_C$$

$$(I_E)_Q + \Delta I_E = I'_E$$

$$(V_{BE})_Q + \Delta V_{BE} = V'_{BE}$$

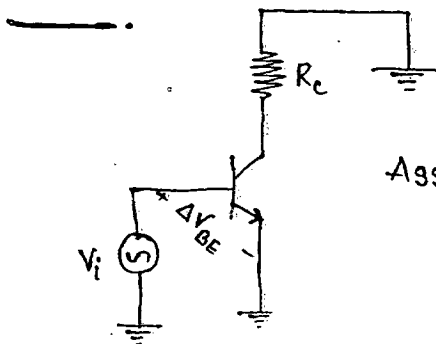
$$(I_B)_Q + \Delta I_B = I'_B$$

$$(I_E)_Q = I_0 \cdot e^{(V_{BE})_Q / V_T} \rightarrow \text{diode current}$$

$$(I_E)_Q + \Delta I_E = I_0 \cdot e^{(V_{BE})_Q + \Delta V_{BE} / V_T}$$

$$\Rightarrow \frac{(I_E)_Q}{(I_E)_Q} \Rightarrow I'_E = \frac{I_0 \cdot e^{(V_{BE})_Q / V_T} \cdot e^{\Delta V_{BE} / V_T}}{(I_E)_Q} \Rightarrow \boxed{I'_E = (I_E)_Q \cdot e^{\Delta V_{BE} / V_T}}$$

AC Model.



$$I'_E = (I_E)_Q e^{V_i / V_T} \rightarrow \text{Non linear device.}$$

Assume :- $V_i = V_p \sin \omega t$

$$I'_E = (I_E)_Q e^{V_p \sin \omega t / V_T}$$

$$\Rightarrow I'_E = (I_E)_Q \left[1 + \frac{V_p \sin \omega t}{V_T} + \frac{1}{2!} \cdot \frac{V_p^2}{V_T^2} \sin^2 \omega t + \dots \right]$$

$$= (I_E)_Q \left[1 + \frac{V_p}{V_T} \sin \omega t + \frac{1}{2!} \cdot \frac{V_p^2}{V_T^2} \left(\frac{1 - \cos 2\omega t}{2} \right) + \dots \right]$$

$$\Rightarrow I'_E = \underbrace{(I_E)_Q \left[1 + \frac{V_p^2}{4V_T^2} \right]}_{\text{offset unwanted}} + \underbrace{(I_E)_Q \cdot \frac{V_p}{V_T} \sin \omega t}_{\text{1st harmonic}} - \underbrace{\frac{V_p^2}{4V_T^2} (I_E)_Q \cos 2\omega t}_{\text{2nd harmonic}} + \dots$$

$$\% \text{ Distortion} = \frac{|B_2|}{|B_1|} = \frac{(I_E)_Q \cdot \frac{V_p^2}{4V_T^2}}{(I_E)_Q \cdot \frac{V_p}{V_T}} = \frac{V_p}{4V_T}$$

$$\% \text{ Distortion} = \frac{V_p}{4V_T}$$

$$\% \text{ Distortion} = \frac{V_p}{100 \text{ mV}}$$

Best testing s/g $V_p = 1 \text{ mV} \sin \omega t$.

$$V_p \ll 4V_T \Rightarrow I_E' = (I_E)_Q + \frac{(I_E)_Q}{V_T} \cdot V_p \sin \omega t$$

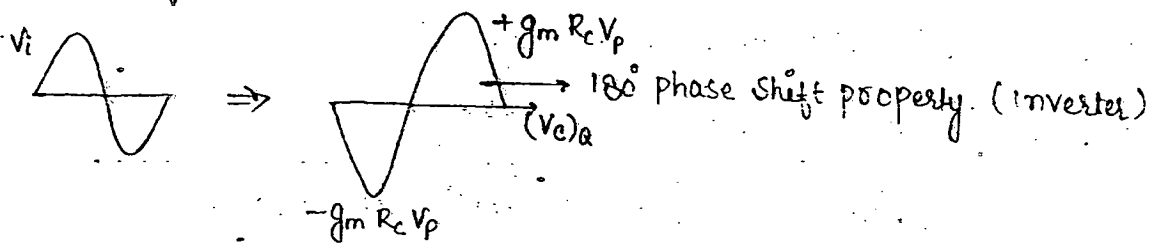
$$I_C' = \alpha I_E'$$

$$I_C' = \alpha (I_E)_Q \cdot \left[1 + \frac{V_p}{V_T} \sin \omega t \right]$$

$$V_o = V_{cc} - I_C' R_c$$

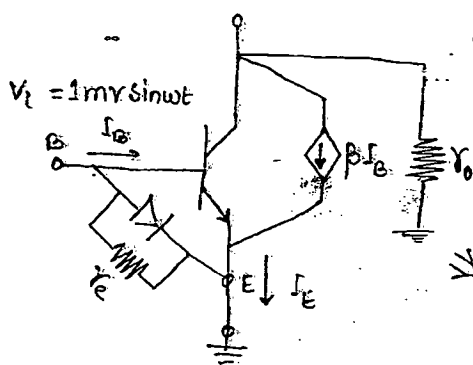
$$= \underbrace{V_{cc} - \alpha (I_E)_Q R_c}_{(V_C)_Q} - \underbrace{\frac{(I_C)_Q}{V_T} R_c}_{\frac{1}{g_m R_c} = A_v} \cdot \underbrace{V_p \sin \omega t}_{V_i}$$

$$V_o = (V_C)_Q - g_m R_c V_p \sin \omega t$$

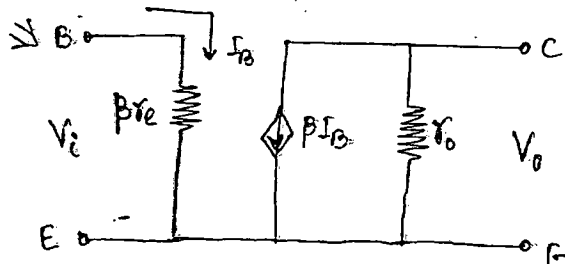


CHARACTERISTICS OF COMMON EMITTER AMPLIFIER.

Small Signal Theory.



$$\begin{aligned} I_E &\Rightarrow r_e = \frac{V_T}{I_E} \\ I_B &\Rightarrow (1 + \beta) r_e = \frac{V_T}{I_B} \end{aligned}$$



$$1. Z_i = \frac{V_i}{I_i}$$

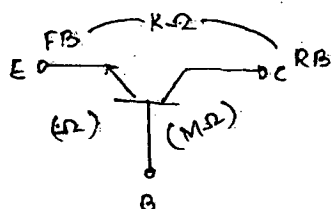
$$Z_i = \beta r_e$$

Assume; $r_e = 10\Omega$ (1Ω to 25Ω)

$$\beta = 100 \text{ (50 to 150)}$$

$$Z_i = 1k\Omega$$

$$2. Z_o = r_o = 80k\Omega$$



3.

$$V_o = -\beta I_B r_o$$

$$= -\beta \cdot \frac{V_i}{\beta r_e} \cdot r_o$$

$$\frac{V_o}{V_i} = -\frac{r_o}{r_e} \Rightarrow \left| \frac{V_o}{V_i} \right| > 1$$

4.

$$A_I = \beta > 1$$

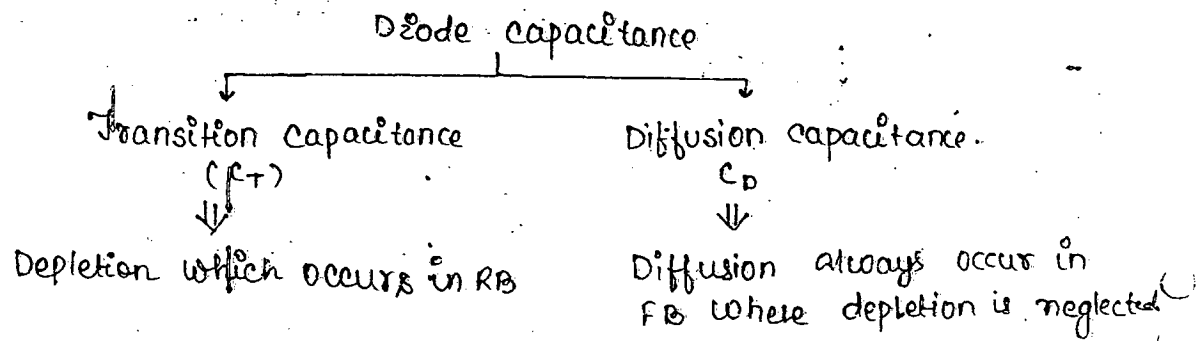
→ PROPERTIES OF COMMON EMITTER AMPLIFIER.

1. The i/p Impedance is Moderate.
2. The o/p impedance is also moderate.
3. The voltage gain is greater than 1.
4. current gain is also greater than 1.

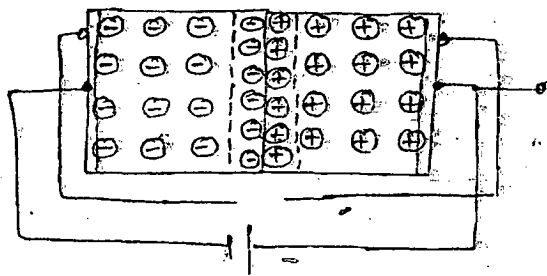
NOTE:- In most of the practical applⁿ CE amplifier is used because the power gain is high.

2. COMMON BASE AMPLIFIER.

→ Diode capacitance :-



1. Transition capacitance (C_T) :- (Typically $C_T = 3 \text{ pf}$)



"The rate of change of charge w.r.t Voltage" $\rightarrow$ Capacitance

"The rate of change of immobile charge in the depletion region w.r.t reverse bias Voltage" $\rightarrow C_T$

$$C_{||} = \frac{\epsilon A}{d} \quad (\text{or}) \quad C_T = \frac{\epsilon A}{W} \Rightarrow W \propto \sqrt{V_j} \quad (\text{Alloy type})$$

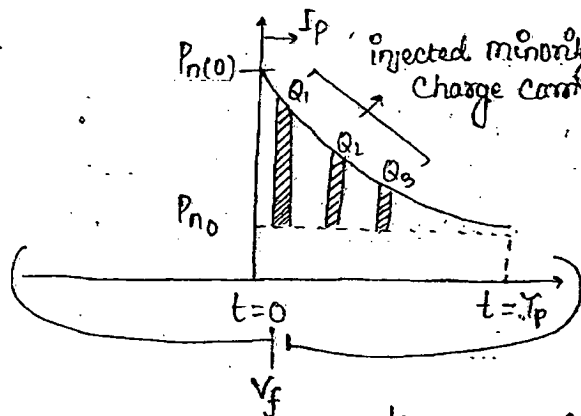
$$\left. \begin{array}{l} W \propto \sqrt{V_j + V_R} \\ W \propto \sqrt[3]{V_j + V_R} \end{array} \right\} \text{RB.} \quad C_T \propto \frac{1}{\sqrt{V_j + V_R}} \rightarrow \text{Alloy type.} \quad W \propto \sqrt[3]{V_j} \quad (\text{Grown Jn})$$

$$C_T \propto \frac{1}{\sqrt[3]{V_j + V_R}} \rightarrow \text{Grown Junction}$$

$$C_T \propto \frac{1}{(V_R)^n} \quad \text{where } n = \frac{1}{2} \rightarrow \text{alloy type.}$$

$$n = \frac{1}{3} \rightarrow \text{Grown Jn.}$$

2. Diffusion capacitance (C_D) :- (Typically $C_D = 100 \text{ pf}$)



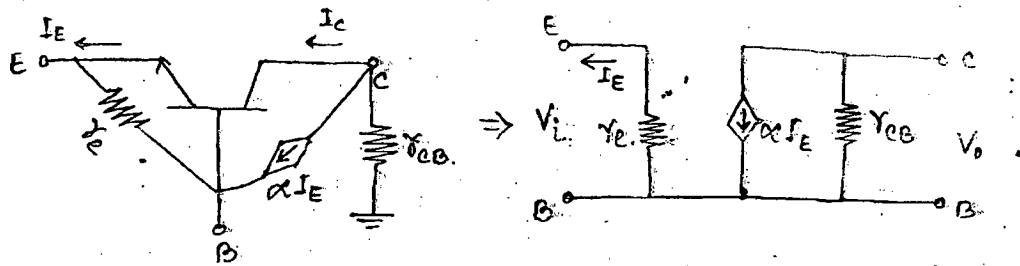
"The rate of change of charge w.r.t Voltage" $\rightarrow$ Capacitance.

"The rate of change of injected minority carrier charge w.r.t forward bias Voltage" $\rightarrow C_D$

$$Q = I_P \cdot T_P \quad ; \quad C_D = \frac{dQ}{dV} = T_P \cdot \frac{\partial I_P}{\partial V} = T_P \cdot \frac{I_P(\text{DC})}{V_T}$$

$$C_D = T_P \cdot \frac{I_P}{V_T}$$

→ CHARACTERISTICS OF COMMON BASE AMPLIFIER.



1. $Z_i = \frac{V_i}{I_E} = r_e$

$Z_i = 1\Omega \text{ to } 25\Omega$

2. $Z_o = r_{cb} = 4M\Omega$

3. $V_o = -\alpha I_E r_{cb}$

$V_o = -\alpha \left(-\frac{V_i}{r_e} \right) r_{cb}$

$\frac{V_o}{V_i} = \frac{r_{cb}}{r_e} > 1$

4. $A_I = \alpha \approx 1$

Current Buffer

$P_{CB} = A_v \cdot A_I$

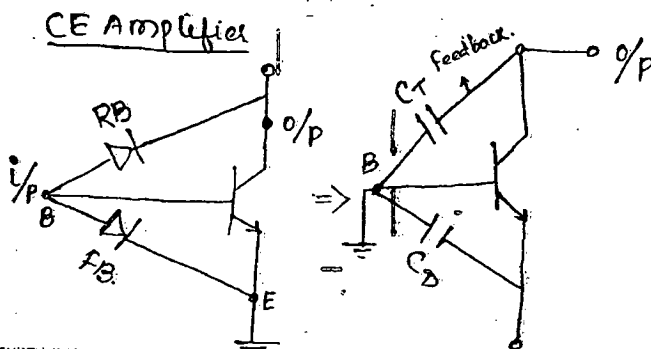
$P_{CB} = A_v$

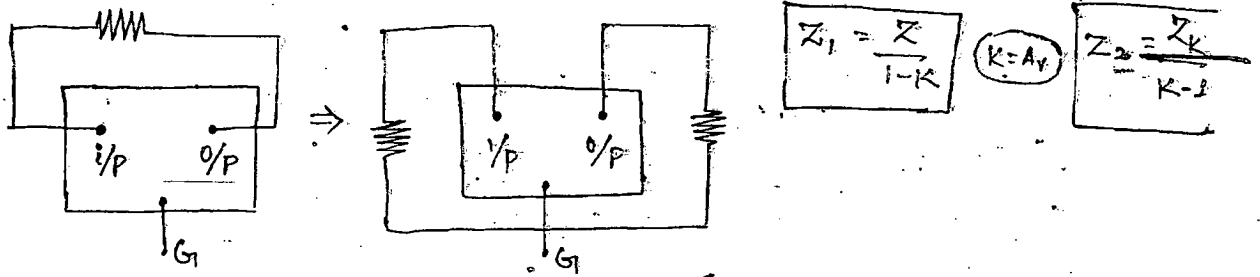
→ PROPERTIES IN COMMON BASE AMPLIFIER.

1. The i/p impedance is low.
2. The o/p impedance is high.
3. The voltage gain is greater than 1.
4. The current gain is nearly unity (current Buffer)

NOTE → In practical applⁿ CB amplifier is used whenever high bandwidth is required.

→ COMMON BASE AMPLIFIER IN HIGH FREQUENCY.



Miller's Theorem $\rightarrow$ 

Proof:-

Input port: i/p, Output port: o/p

Input voltage: V_i , Output voltage: V_o

Input current: I_i

Miller capacitance: C_T

$$Z_1 = \frac{V_i}{I_i}$$

$$I_i = \frac{V_i - V_o}{Z}$$

$$= \frac{V_i \left[1 - \frac{V_o}{V_i} \right]}{Z}$$

$$Z_1 = \frac{V_i}{I_i} = \frac{Z}{1 - \left(\frac{V_o}{V_i} \right) \rightarrow K}$$

$$Z_1 = \frac{Z}{1 - A_v}$$

$$Z_2 = \frac{Z \cdot A_v}{A_v - 1}$$

$$\frac{1}{C_{T1}} = \frac{1}{C_T} \cdot \frac{1}{1 - A_v}$$

$$A_v \gg 1 \text{ (open loop gain)}$$

$$Z_2 \approx Z$$

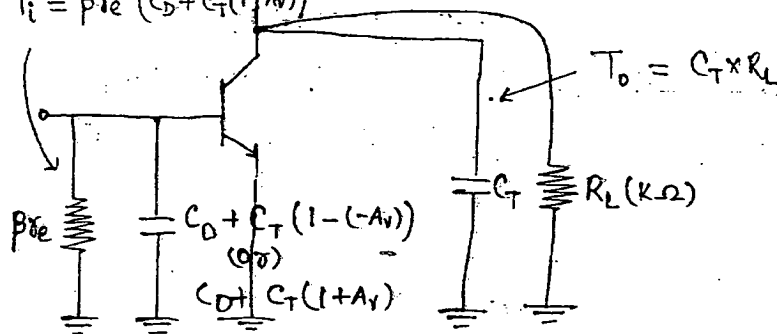
$$C_{T1} = C_T (1 - A_v)$$

$$\frac{1}{C_{T2}} = \frac{1}{C_T} \Rightarrow C_{T2} \approx C_T$$

CE Amplifier

Miller capacitive effect

$$T_i = \beta R_E (C_D + C_T (1 + A_v))$$



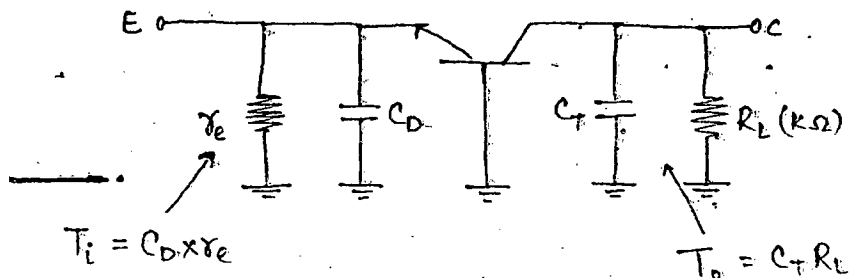
$$\omega_{B.W} = \frac{1}{T}$$

$$T = T_i + T_o$$

$$T_i \gg T_o$$

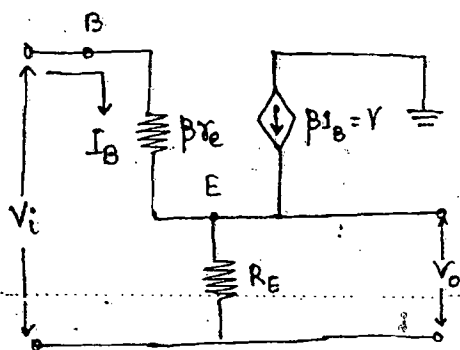
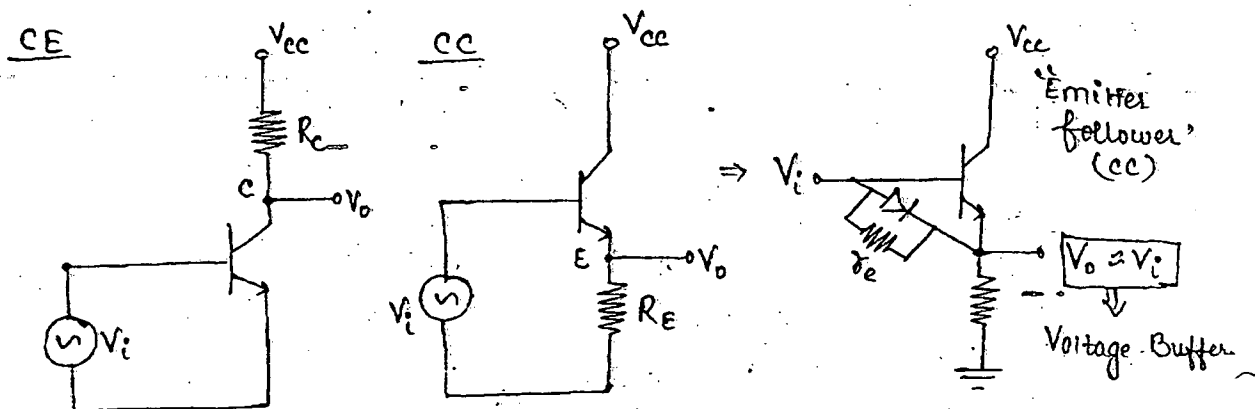
$$\omega_{B.W} \downarrow = \frac{1}{T_i \uparrow}$$

Common Base Amplifier



$$\omega_{B.W} \uparrow = \frac{1}{T_L}$$

3. COMMON COLLECTOR AMPLIFIER.



$$Z_i = \frac{V_i}{I_B}$$

$$Z_i = \beta r_e + (1 + \beta) R_E$$

$$\text{Assume } \beta = 100; r_e = 10 \Omega; R_E = 10 K \Omega$$

$$Z_i = 1 K \Omega + 1 M \Omega \Rightarrow Z_i = 1 M \Omega$$

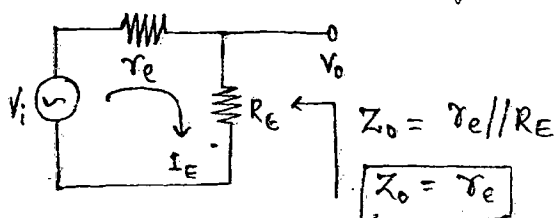
$$2. Z_o = \frac{V_o}{-I_E}$$

$$3. A_v = \frac{V_o}{V_i} = \frac{R_E}{r_e + R_E}$$

$$R_E \gg r_e$$

$$P_{cc} = A_v \cdot A_i$$

$$P_{cc} = A_i$$



$$4. A_i = Y = 1 + \beta > 1$$

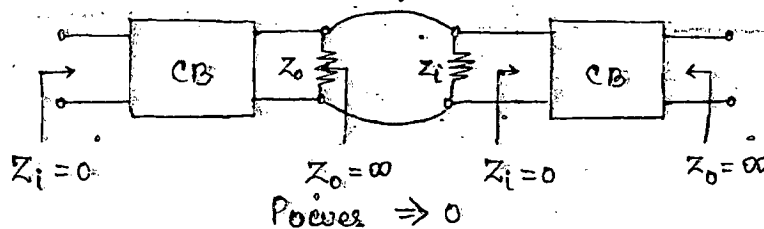
Impedance matching property.

→ PROPERTIES IN COMMON COLLECTOR AMPLIFIER

1. The i/p impedance is high.
2. The o/p impedance is low (Impedance Matching).
3. The voltage gain is nearly unity.
4. The current gain is greater than 1.

NOTE:- In practical applⁿ CC amplifier is used whenever impedance matching is required.

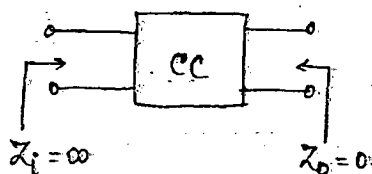
Impedance Matching:-



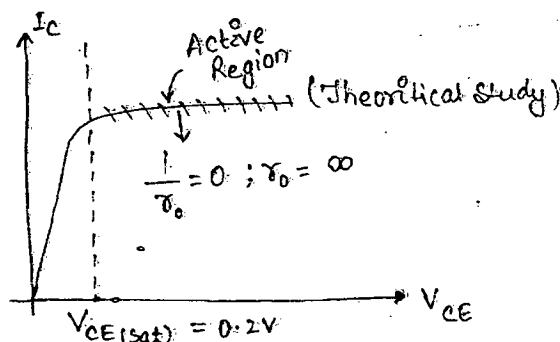
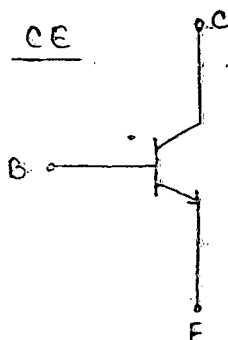
$$A_v = \frac{V_o}{V_i} = \frac{I_o Z_o}{I_i Z_i}$$

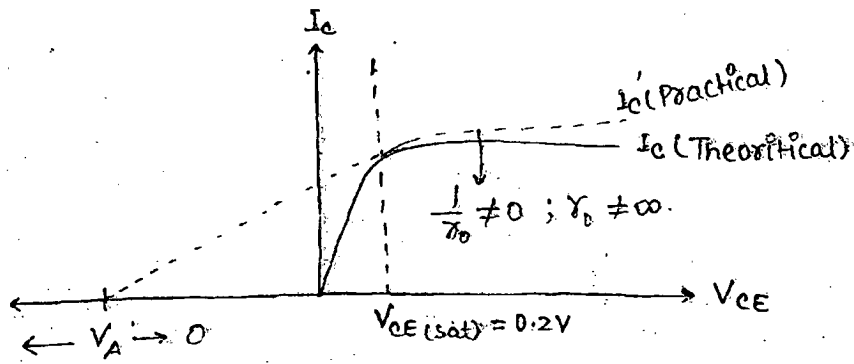
$$A_v = A_i \cdot \frac{Z_o}{Z_i}$$

$$Z_i = Z_o \Rightarrow A_v = A_i$$



□ EARLY EFFECT (OR) BASE WIDTH MODULATION





(Early voltage)

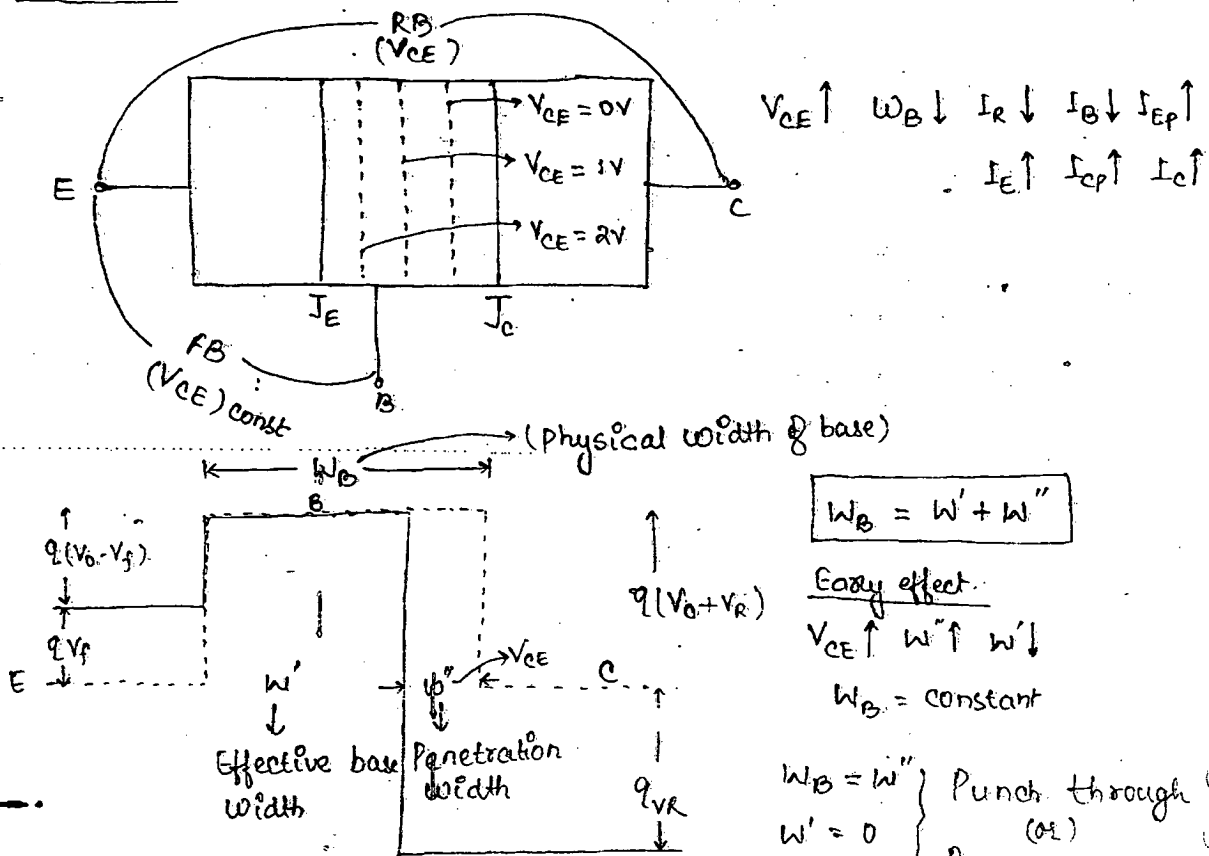
$$I_C = I_0 \cdot e^{V_{BE}/V_T} ; I_C' = I_0 \cdot e^{V_{BE}/V_T} \left[1 + \frac{V_{CE}}{V_A} \right]$$

$$\frac{1}{r_o} = \frac{\partial I_C'}{\partial V_{CE}} = \frac{I_0 e^{V_{BE}/V_T}}{V_A} = \frac{(I_C)_Q}{V_A} \Rightarrow r_o = \frac{V_A}{(I_C)_Q}$$

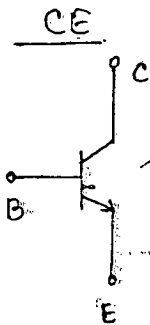
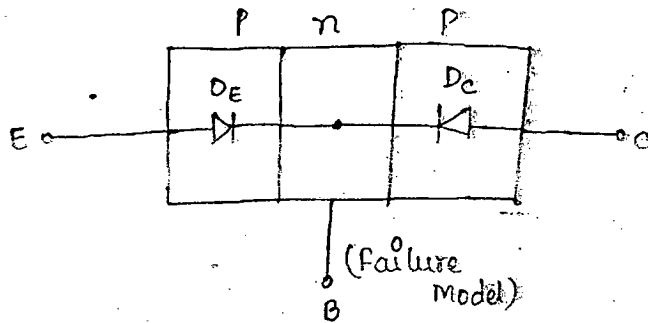
Typically $V_A = 1000$; $(I_C)_Q = 1 \text{ mA}$

$$\therefore r_o = 1 \text{ M}\Omega$$

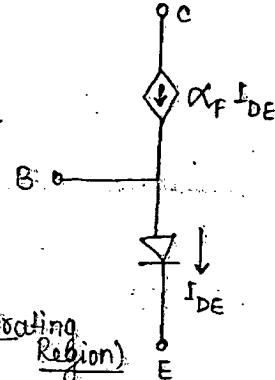
ANALYSIS :-



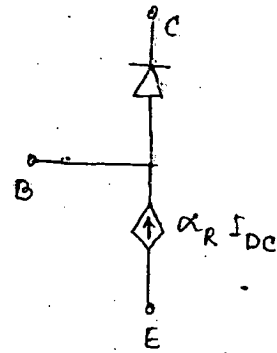
EBBERS MOLL MODEL OF BJT.



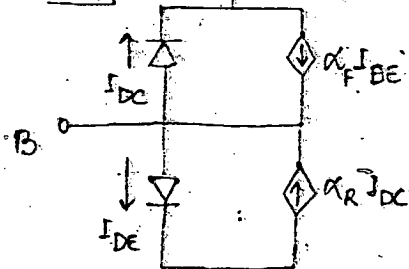
Forward Active Mode.



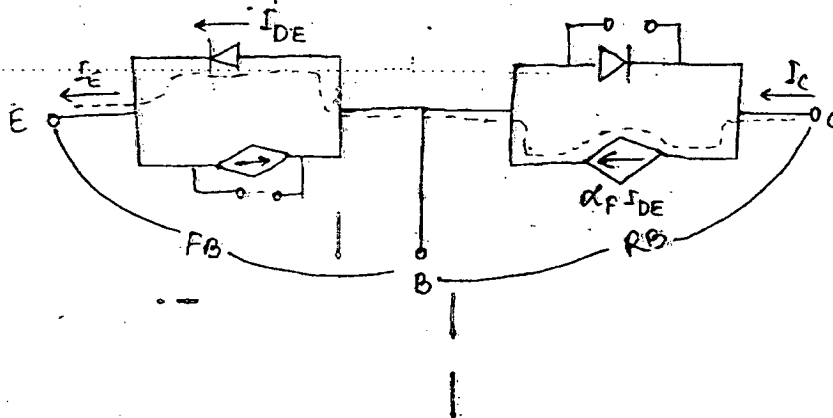
Reverse Active Mode.



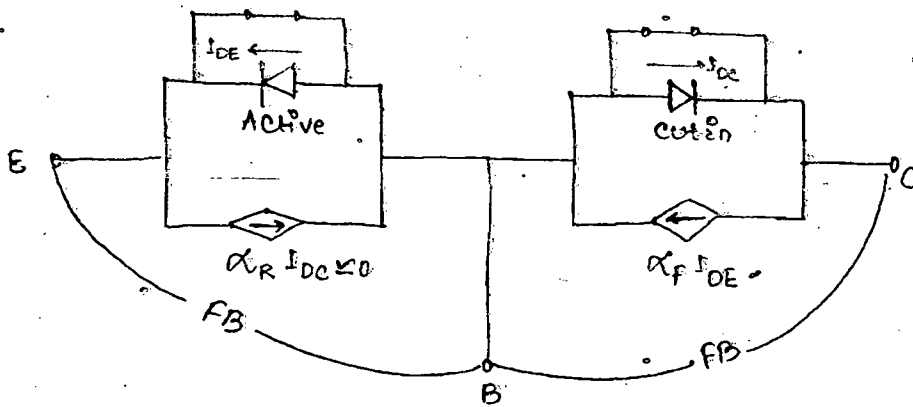
Ebbers Model (Operating Region)



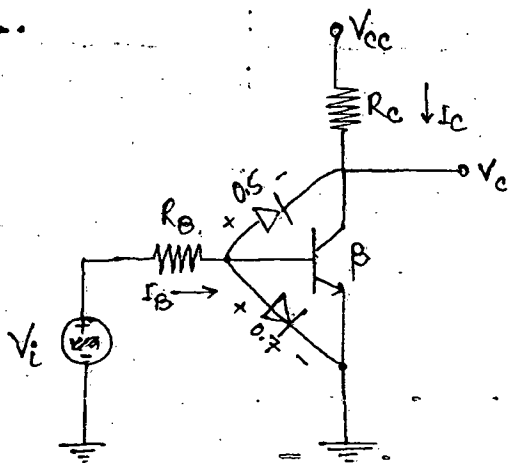
TESTING OF BJT IN ACTIVE REGION.



TESTING OF BJT IN SATURATION REGION.



BJT AS A SWITCH.



Cutoff

$V_i < 0.5V$
Q is in cutoff

$I_B = 0$
 $I_C = \beta I_B = 0$
 $V_C = V_{CC} - I_C R_C$

$$V_C = V_{CC}$$

Active

$V_i = 0.5$ (cut in)
 $I_B \approx 0$

$V_i \geq 0.7$ (active)
 $I_B > 0$

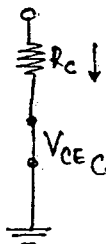
$I_C \uparrow = \beta I_B \uparrow$

$$V_C \downarrow = V_{CC} - I_C \uparrow R_C$$

$$V_C > V_B - 0.5$$

Edge of Saturation (EOS)

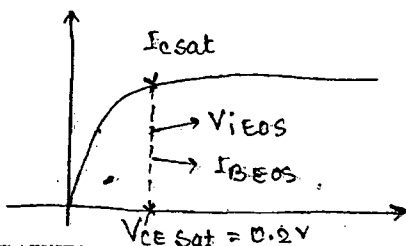
$$V_C = V_B - 0.5V$$



$$I_{CEOS} = \frac{I_{C(sat)}}{\beta} = \frac{V_{CC} - V_{CE(sat)}}{R_C}$$

$$I_{B(EOS)} = \frac{I_{CEOS}}{\beta}$$

$$V_{iEOS} = I_{B(EOS)} \times R_B + V_{BE \text{ active}}$$



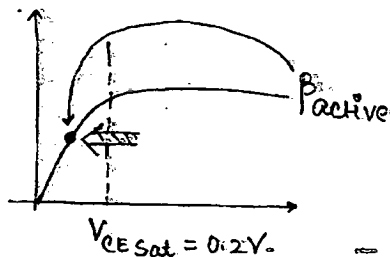
Deep Saturation

$$V_c < V_b - 0.5$$

$$I_{c \text{ sat}} = \frac{V_{cc} - V_{c \text{ sat}}}{R_c}$$

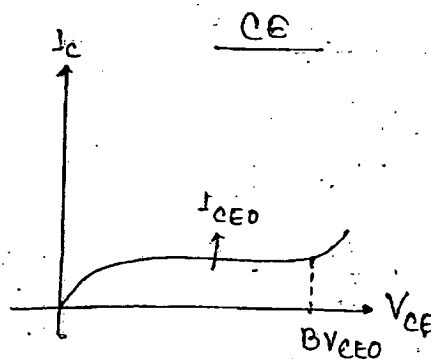
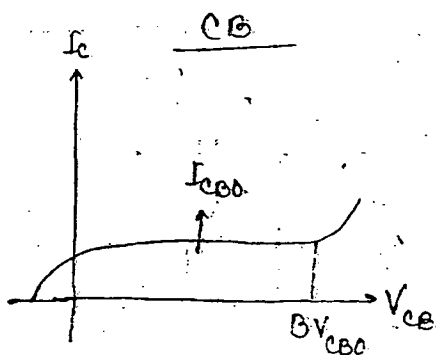
$$= \frac{V_{cc} - 0.2}{R_c}$$

$$\beta_{\text{force}} = \frac{I_{c \text{ sat}}}{I_B > I_{B \text{EOS}}}$$



$$\text{Over drive Factor} = \frac{I_B}{I_{B \text{EOS}}}$$

□ BREAKDOWN IN BJT.



$$BV_{ceo} = \frac{BV_{cbo}}{\sqrt[n]{\beta}}$$

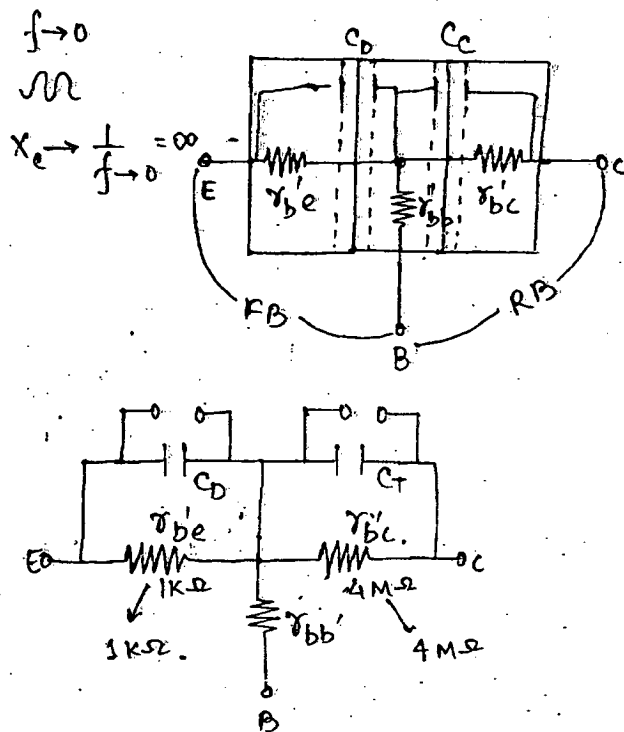
$$BV_{ceo} < \beta BV_{cbo}$$

Where, $\eta > n$ = Avalanche multiplication factor (3 to 6)

β = current gain of CE.

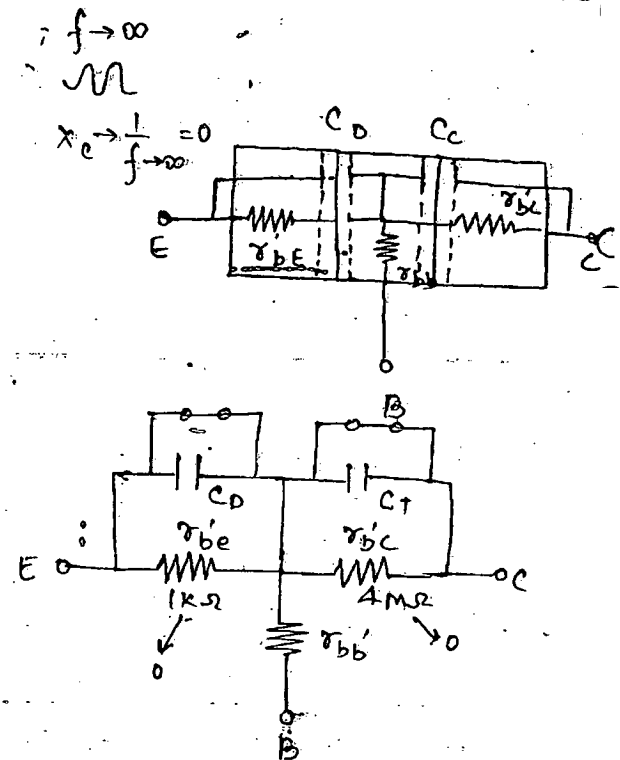
□ SMALL SIGNAL ANALYSIS OF BJT (VOLTAGE AMPLIFIER)

LOW FREQUENCY ANALYSIS



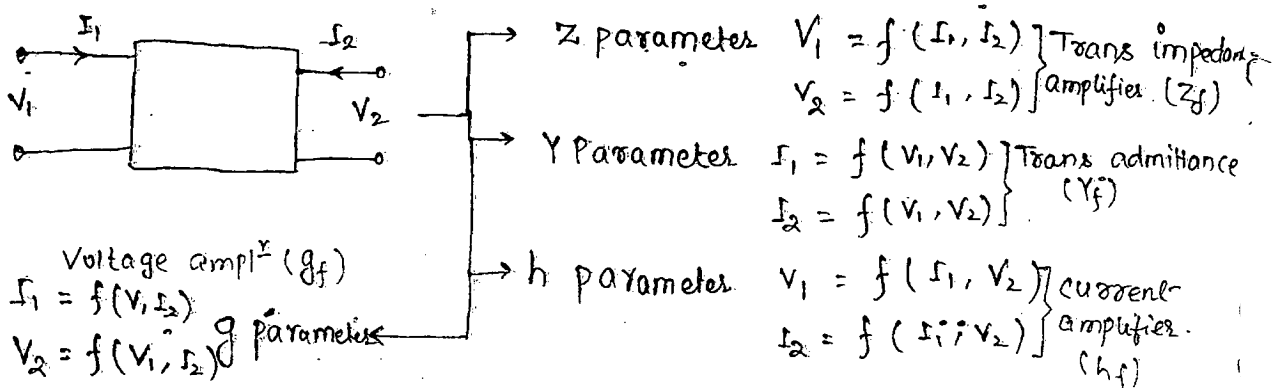
Note:- For low frequency analysis internal capacitor C_D & C_C are neglected

HIGH FREQUENCY ANALYSIS

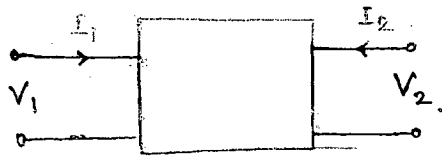


NOTE:- For high frequency analysis internal capacitance C_D & C_C are taken into account.

□ LOW FREQUENCY ANALYSIS OF BJT



□ DESIGN OF AMPLIFIER WITH Z-PARAMETER.



$$V_1 = Z_i I_1 + Z_r I_2$$

$$V_2 = Z_f I_1 + Z_o I_2$$

$$V_1 = f(I_1, I_2)$$

$$V_2 = f(I_1, I_2)$$

$$\begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} Z_i & Z_r \\ Z_f & Z_o \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}$$

Ideal Amplifier

$$\begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ Z_f & 0 \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}$$

$$V_2 = Z_f I_1 \rightarrow \text{ICVS}$$

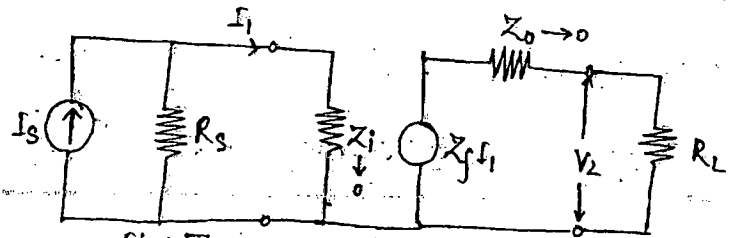
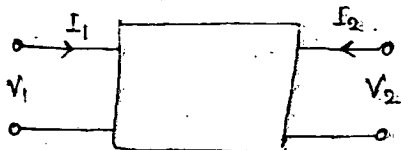


Fig: Trans Impedance Amplifier $\rightarrow Z_i = 0; Z_o = \infty$

Note:- Ideal ampl^r is unilateral device

$$Z_r = 0$$

□ DESIGN OF AMPLIFIER WITH Y-PARAMETER.



$$I_1 = Y_i V_1 + Y_r V_2$$

$$I_2 = Y_f V_1 + Y_o V_2$$

$$I_1 = f(V_1, V_2)$$

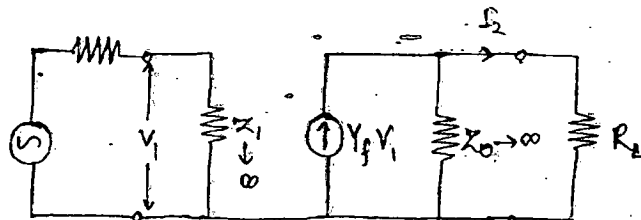
$$I_2 = f(V_1, V_2)$$

$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} Y_i & Y_r \\ Y_f & Y_o \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$

Ideal Amplifier

$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ Y_f & 0 \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$

$$I_2 = Y_f V_1 \rightarrow \text{VCS}$$



Trans admittance amplifier
(or)

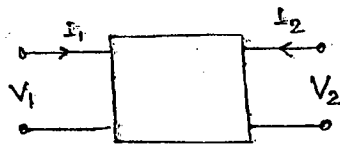
Trans conductance amplifier

$$Z_i = \infty; Z_o = \infty$$

used in FET

Note:- Ideal ampl^r is a unilateral
 $Y_r = 0$

□ DESIGN OF AMPLIFIER WITH H - PARAMETER



$$V_1 = h_i I_1 + h_r V_2$$

$$I_2 = h_f I_1 + h_o V_2$$

$$V_1 = f(I_1, V_2)$$

$$I_2 = f(I_1, V_2)$$

Case-1

$$V_2 = 0$$

$$h_i = \frac{V_1}{I_1} \rightarrow \text{input impedance}$$

$$h_f = \frac{I_2}{I_1} \rightarrow \text{forward current gain}$$

Case-2

$$I_1 = 0$$

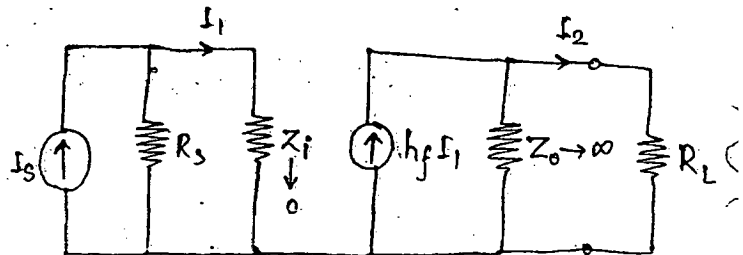
$$h_r = \frac{V_1}{V_2} \rightarrow \text{Reverse voltage gain}$$

$$h_o = \frac{I_2}{V_2} \rightarrow \text{output admittance}$$

Ideal Amplifier

$$\begin{bmatrix} V_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ h_f & 0 \end{bmatrix} \begin{bmatrix} I_1 \\ V_2 \end{bmatrix}$$

$$I_2 = h_f I_1 \rightarrow \text{CCCS}$$



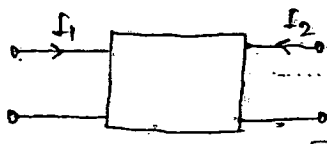
current amplifier

$$Z_i = 0 ; Z_o = \infty$$

Used in BJT

Note:- Ideal amplifier is a unilateral device $h_r = 0$

□ DESIGN OF AMPLIFIER WITH g - PARAMETER



$$I_1 = g_i V_1 + g_r I_2$$

$$V_2 = g_f V_1 + g_o I_2$$

$$I_1 = f(V_1, I_2)$$

$$V_2 = f(V_1, I_2)$$

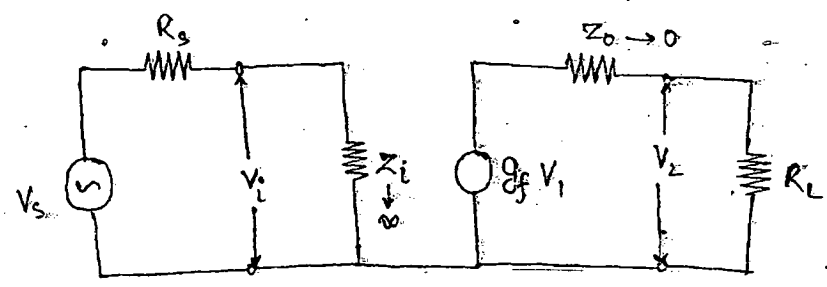
$$\begin{bmatrix} I_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} g_i & g_r \\ g_f & g_o \end{bmatrix} \begin{bmatrix} V_1 \\ I_2 \end{bmatrix}$$

Ideal amplifier

$$\begin{bmatrix} I_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ g_f & 0 \end{bmatrix} \begin{bmatrix} V_1 \\ I_2 \end{bmatrix}$$

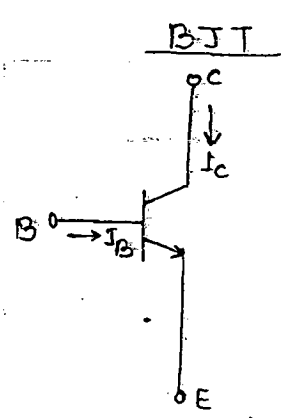
$$V_2 = g_f V_1 \rightarrow \text{VCVS}$$

Note:- Ideal amplifier is a unilateral device $g_r = 0$

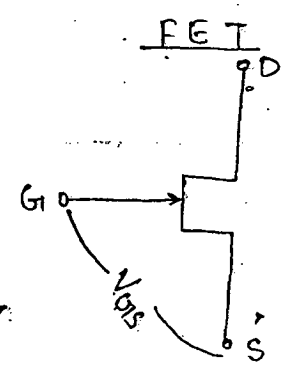


Voltage Amplifier. used in op.amp.
 $Z_i = \infty$; $Z_o = 0$

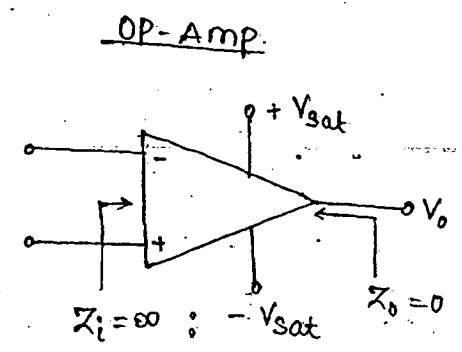
CONCLUSION.



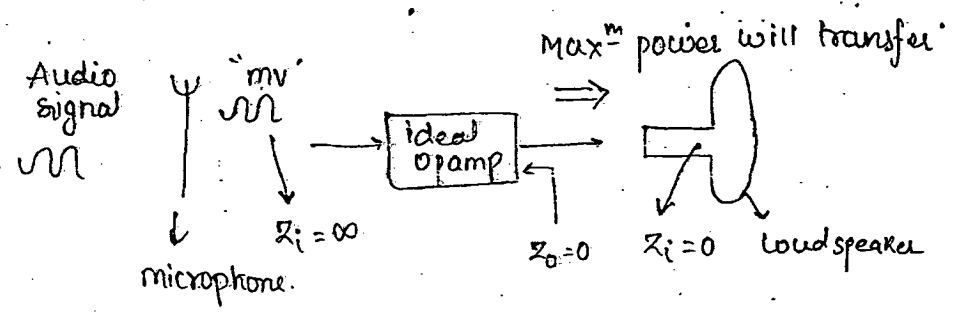
h-parameter
 "CCCS"
 $Z_i = 0$; $Z_o = \infty$



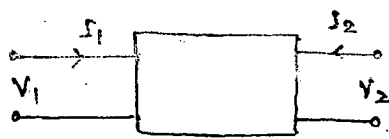
Y-parameter
 "VCIS"
 $Z_i = \infty$; $Z_o = \infty$



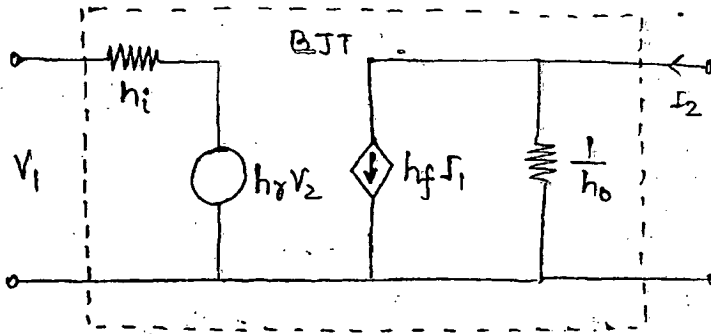
g parameter
 Voltage amplifier (VCVS)
 $Z_i = \infty$; $Z_o = 0$



□ H-PARAMETER MODEL OF BJT.



$$\begin{aligned} V_1 &= f(I_1, V_2) \\ I_2 &= f(I_1, V_2) \end{aligned} \quad \begin{bmatrix} h_i & h_r \\ h_f & h_o \end{bmatrix}$$



□ TYPICAL VALUES OF H-PARAMETER

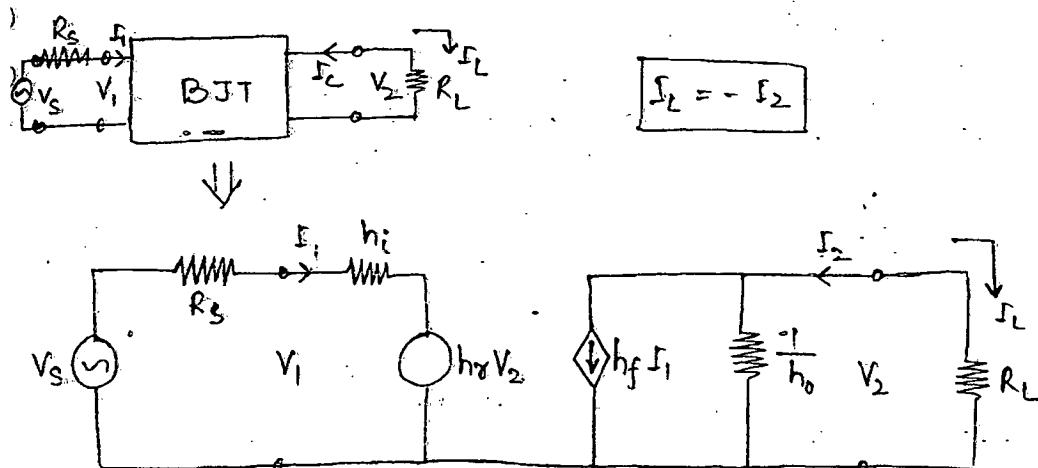
h-parameter	CE	CC	CB
h_i	1100 Ω	1100 Ω	22 Ω
h_f	50	-51	-0.98
h_r	2.4×10^{-4}	≈ 1	2.9×10^{-4}
h_o	$24 \times 10^{-6} \text{ A/V}$	$24 \times 10^{-6} \text{ A/V}$	$0.49 \times 10^{-6} \text{ A/V}$

Neglected

CE to CC

CE to CB	CB to CE	CE to CE
$h_{ib} = \frac{h_{ie}}{1+h_{fe}}$	$h_{ie} = \frac{h_{ib}}{1+h_{fb}}$	$h_{ic} = h_{ie}$
$h_{fb} = \frac{-h_{fe}}{1+h_{fe}}$	$h_{fe} = \frac{-h_{fb}}{1+h_{fb}}$	$h_{fc} = -(1+h_{fe})$
$h_{rb} = \frac{h_{ie} \cdot h_{oe}}{1+h_{fe}} - h_{re}$	$h_{re} = \frac{h_{ib} \cdot h_{ob}}{1+h_{fb}} - h_{rb}$	$h_{rc} \approx 1$
$h_{ob} = \frac{h_{oe}}{1+h_{fe}}$	$h_{oe} = \frac{h_{ob}}{1+h_{fb}}$	$h_{oc} = h_{oe}$

TRANSISTOR AMPLIFIER ANALYSIS (EXACT MODEL)



Characteristics of Amplifier

- | | |
|---|-------|
| (1) Current gain $A_I = \frac{I_2}{I_1}$ | } BJT |
| (2) Input Impedance $Z_i = \frac{V_1}{I_1}$ | |
| (3) Voltage gain $A_v = \frac{V_2}{V_1}$ | |
| (4) o/p Impedance $Z_o = \frac{V_2}{I_2}$ | |

h-parameter.

$$V_1 = h_i I_1 + h_r V_2$$

$$I_2 = h_f I_1 + h_o V_2$$

$$V_2 = I_2 R_L$$

$$= -I_2 R_L$$

$$I_2 = -I_2$$

(1) A_I

$$A_I = \frac{I_2}{I_1} = -\frac{I_2}{I_1}$$

$$I_2 = h_f I_1 + h_o V_2$$

$$I_2 = h_f I_1 - h_o I_2 R_L$$

$$I_2(1 + h_o R_L) = h_f I_1$$

$$A_I = -\frac{I_2}{I_1} = -\frac{h_f}{1 + h_o R_L}$$

(2) Z_i

$$Z_i = \frac{V_1}{I_1} = h_i \frac{I_1}{I_1} + h_r \frac{V_2}{I_1} = h_i + h_r \left(-\frac{I_2}{I_1} \right) \cdot R_L$$

$$Z_i = h_i + h_r A_I R_L$$

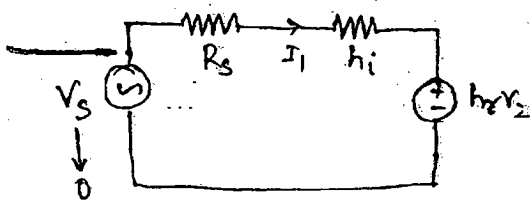
(3) A_V

$$A_V = \frac{V_2}{V_1} = \frac{-\frac{I_2}{I_1} \cdot R_L}{\frac{V_1}{I_1}}$$

$$\Rightarrow A_V = \frac{A_I \cdot R_L}{Z_i}$$

(4) Z_o

$$Z_o = \frac{V_2}{I_2}; Y_o = \frac{I_2}{V_2} = h_f \left| \frac{I_1}{V_2} \right| + h_o \frac{V_2}{V_2}$$

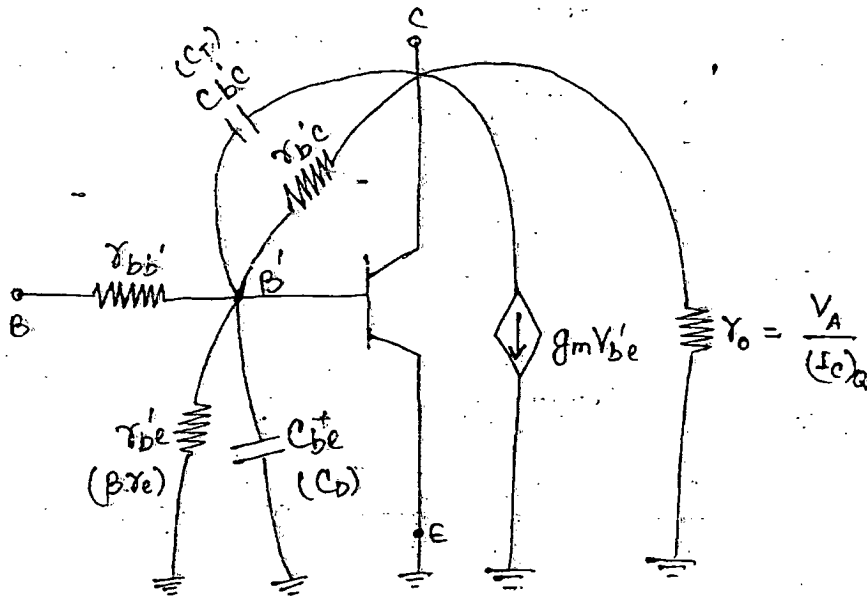
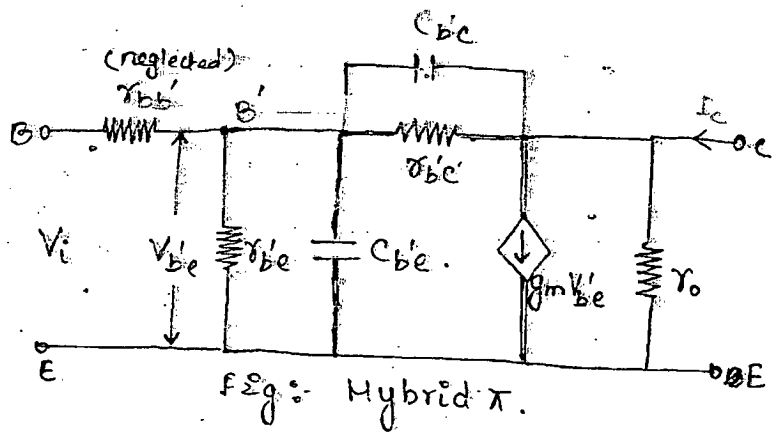
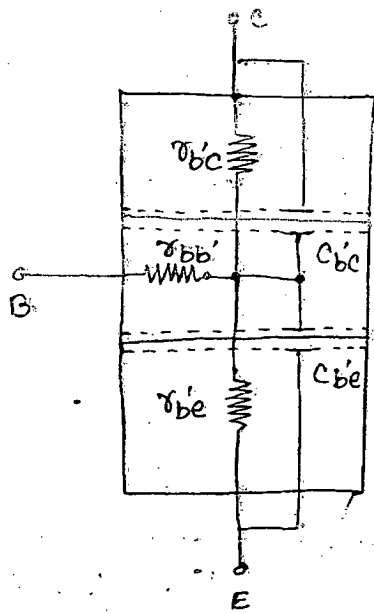


$$\frac{I_1}{V_2} = \frac{-h_r}{h_i + R_s}$$

$$Y_o := h_o - \frac{h_f h_r}{h_i + R_s}$$

$$Z_o = \frac{1}{h_o - \frac{h_f h_r}{h_i + R_s}}$$

□ HIGH FREQUENCY ANALYSIS OF BJT.



Hybrid π Parameter:-

$r'bb'$ → Base Spreading Resistance (100Ω) (S.C)

$r'be$ → Input Resistance ($1k\Omega$) or (r_{π}).

$r'bc$ → Feedback Resistance ($4M\Omega$) (O.C)

$r'ce$ → output Resistance (r_o) ($80k\Omega$).

$C_{be} \rightarrow$ Diffusion capacitance (C_π) (100pf)

$C_{bc} \rightarrow$ Transition capacitance (C_μ) (3pf)

$g_m \rightarrow$ Transconductance ($\frac{50mA}{V}$)

Conclusion :- Hybrid π parameters depends on two important parameters $\rightarrow$ (1) collector current (I_C)
(2) Temperature (T).

EXPRESSIONS FOR HYBRID π PARAMETER.

1. g_m

$$g_m = \frac{(I_C)_Q}{V_{be}} = \frac{(I_C)_Q}{(I_B)_Q \beta_{be}} = \frac{(I_C)_Q}{(I_B)_Q \beta_{dc}}$$

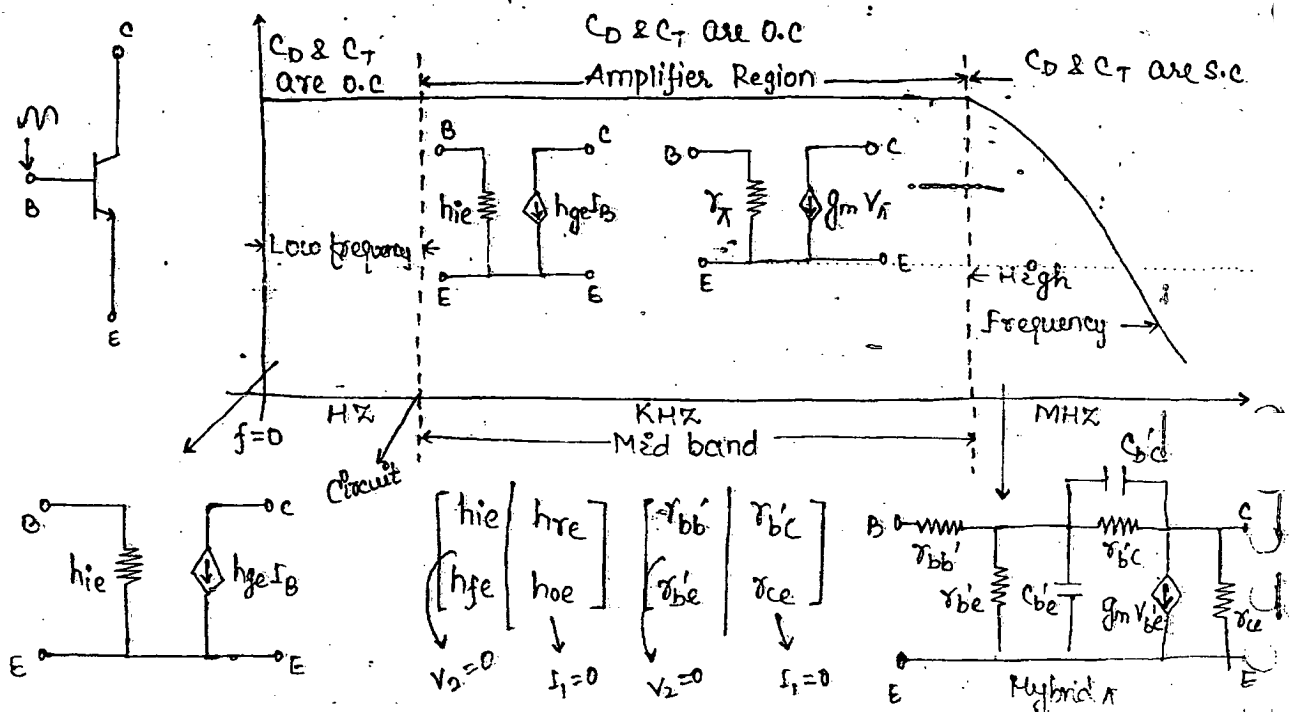
(1) $(I_C)_Q \uparrow \Rightarrow g_m \uparrow \Rightarrow A_v \uparrow$

(2) $T \uparrow \Rightarrow g_m \downarrow \Rightarrow A_v \downarrow$

$$g_m = \frac{1}{r_e} = \frac{(I_C)_Q}{V_T}$$

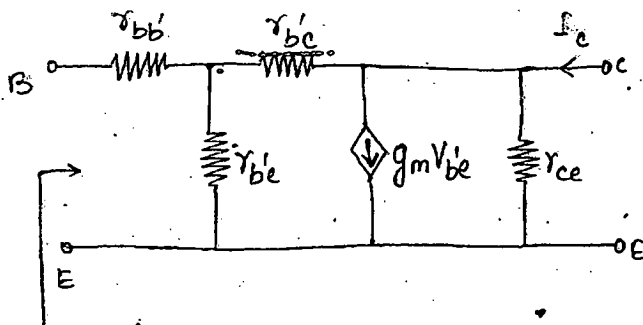
$$g_m = \frac{(I_C)_Q}{T} \times 11,600$$

Concept of Amplifier :-



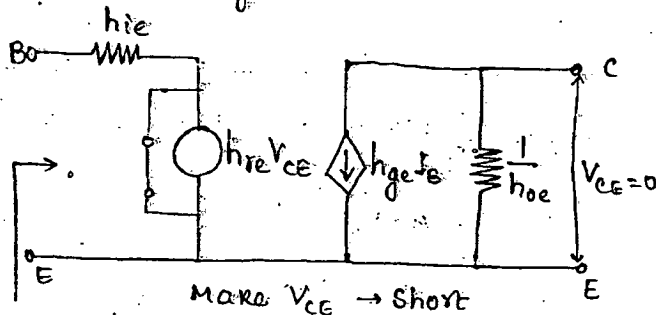
2. $r_{bb'}$ and $r_{b'e}$

Hybrid π (mid point)



$$Z_i = r_{bb'} + r_{b'e}$$

Low frequency (mid band)



$$Z_i = h_{ie}$$

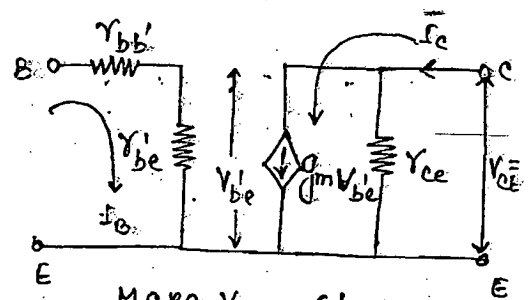
h -parameters

$$I_c = h_{fe} I_B$$

$$r_{bb'} + r_{b'e} = h_{ie}$$

$$\frac{I_c}{I_B} = h_{fe}$$

$$r_{bb'} = h_{ie} - r_{b'e}$$



Make $V_{ce} = \text{Short ckt}$

$\therefore r_{bc} = \text{open}$

Hybrid π

$$I_c = g_m V_{b'e}$$

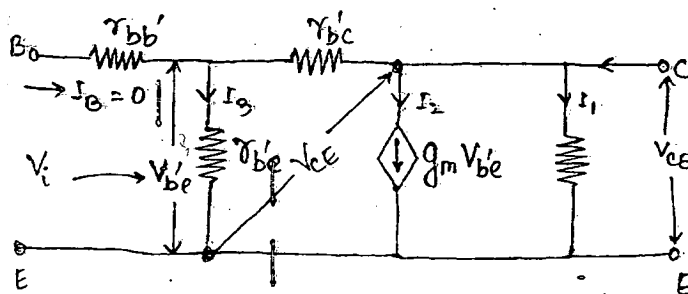
$$I_c = g_m I_B r_{b'e}$$

$$\frac{I_c}{I_B} = g_m r_{b'e}$$

$$r_{b'e} = \frac{h_{fe}}{g_m} = \beta r_e$$

3. r_{bc} and r_{ce}

Hybrid π (Mid band)

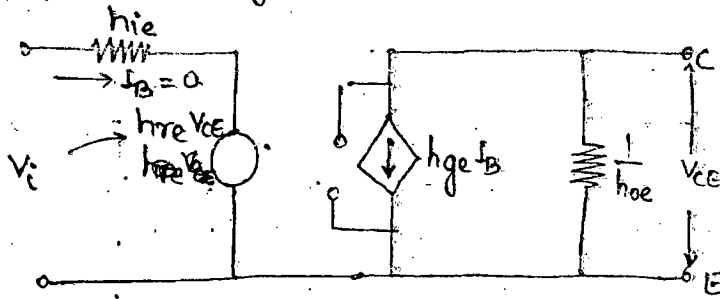


$$V_i = V_{b'e} = \frac{V_{ce} \times r_{b'e}}{r_{b'e} + r_{bc}}$$

$$(r_{bc} \gg r_{b'e}) = \frac{V_{ce} \times r_{b'e}}{r_{bc}} = h_{re} V_{ce}$$

$$r_{bc} = \frac{r_{b'e}}{h_{re}}$$

Low Frequency model (mid band)



$$h_{oe} = \frac{I_c}{V_{ce}}$$

$$I_c = \frac{V_{ce}}{r_{ce}} + g_m V_{be} + \frac{V_{ce}}{r_{be} + r_{bc}}$$

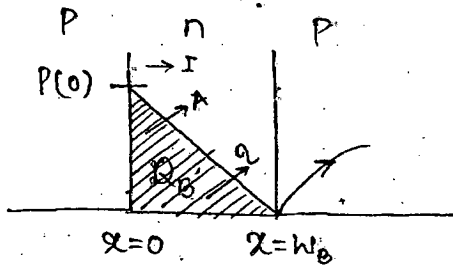
$$I_c = \frac{V_{ce}}{r_{ce}} + g_m \frac{h_{fe}}{r_{be} + r_{bc}} V_{ce} + \frac{V_{ce}}{r_{be} + r_{bc}}$$

$$h_{oe} = \frac{I_c}{V_{ce}} = g_{ce} + h_{fe} h_{fe} g_{bc}$$

$$g_{ce} = h_{oe} - h_{fe} g_{bc}$$

$$r_{ce} = \frac{1}{g_{ce}}$$

→ DIFFUSION CAPACITANCE (C_T)



$$Q = -\frac{1}{2} P(0) \times q \times A \times W_p \quad (1)$$

$$I = -AqD_B \frac{P(0) - 0}{0 - W_p}$$

$$I = + \frac{AqD_B P(0)}{W_p} \quad (2)$$

Putting eqⁿ (2) in (1) we get

$$Q_B = \frac{I}{2D_B} \cdot W_p^2$$

$$C_T = \frac{dQ_B}{dV} = \frac{W_p^2}{2D_B} \cdot \frac{\partial I}{\partial V} \Rightarrow C_T = \frac{W_p^2}{2D_B} \cdot g_m$$

$$C_T = \frac{W_p^2}{2D_B} \cdot \frac{1}{r_e}$$

$$C_T = \frac{W_p^2}{2D_B} \cdot \frac{(I_c)_Q}{V_T}$$

$$C_T = T_B \cdot \frac{(I_c)_Q}{V_T}$$

Where T_B = Base transition time

$$T_B = \frac{W_p^2}{2D_B} \text{ sec}$$

→ TRANSITION CAPACITANCE (C_{μ})

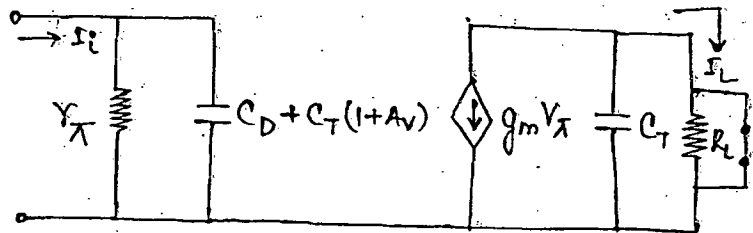
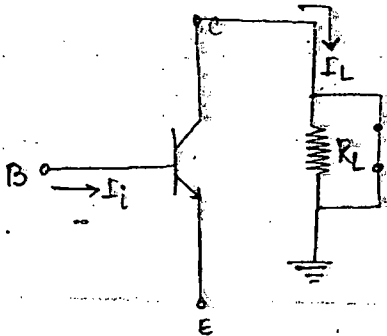
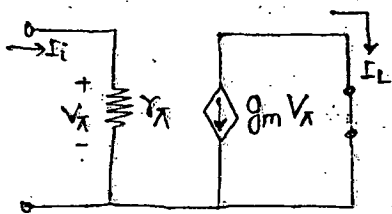
Diode :- $C_T \propto \frac{1}{(V_R)^n}$ $n = \frac{1}{2}$ Alloy type
 $n = \frac{1}{3}$ grown junction

BJT :-

$$C_{\mu} \propto \frac{1}{(V_{CE})^n}$$

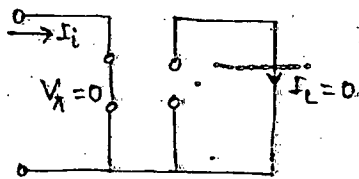
□ FREQUENCY RESPONSE OF BJT AMPLIFIERS.

→ CURRENT GAIN VS. FREQUENCY (BJT).


 $f=0$


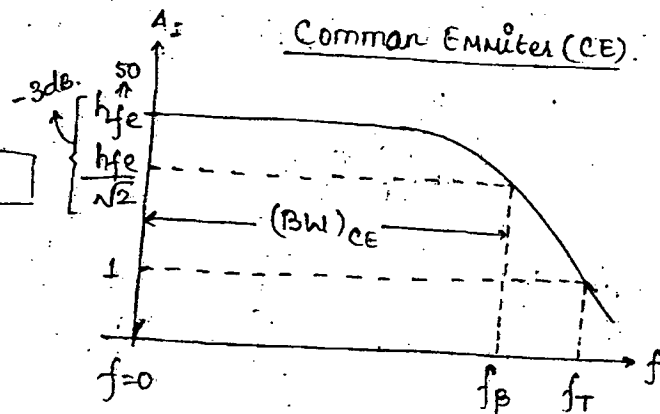
$$A_I = \frac{I_L}{I_i} = \frac{g_m V_{\pi}}{V_{\pi} r_{\pi}} = g_m r_{\pi} = h_{fe}$$

$$A_I = h_{fe}$$

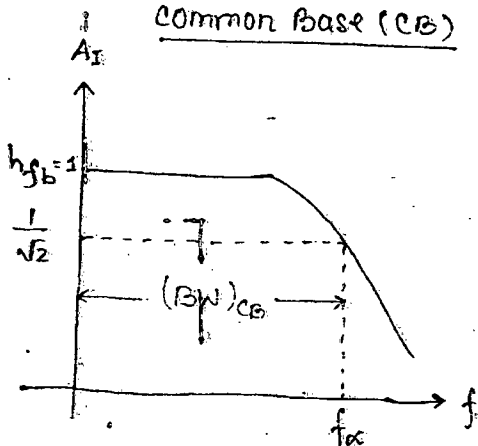
 $f=\infty$


$$A_I = 0$$

Common Emitter (CE).



Common Base (CB)



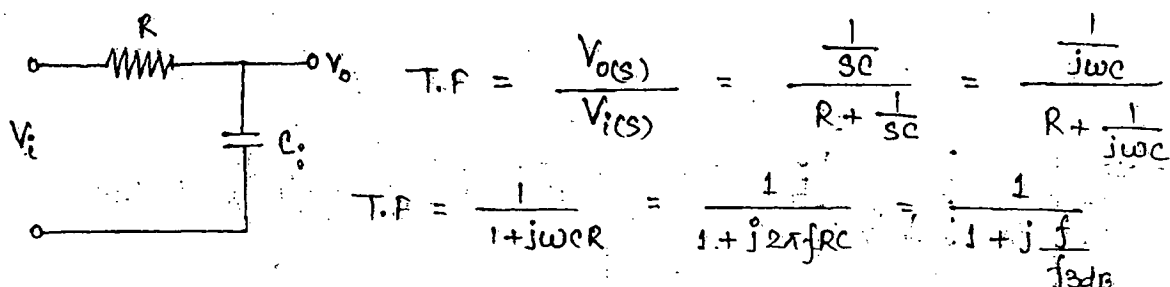
$$f_{\alpha} > f_T > f_p$$

* f_p (β cut off Frequency) :- It is the frequency at which CE short ckt gain reduces by 3dB of its value. -

* f_T (Unity gain Bandwidth Frequency) :- It is the frequency at which CE short ckt current gain reduces to unity.

* f_α (α cut off Frequency) :- It is the frequency at which CB short ckt current gain reduces by 3dB of its value

LOW PASS CIRCUIT.



Where $f_{3dB} = \frac{1}{2\pi RC} \Rightarrow A_I = \frac{h_{fe}}{1 + j\frac{f}{f_\beta}}$

$|A_I| = \frac{h_{fe}}{\sqrt{1 + \left(\frac{f}{f_\beta}\right)^2}}$ When $f \rightarrow f_T \Rightarrow A_I = 1$ $\Rightarrow 1 = \frac{h_{fe}}{\sqrt{1 + \left(\frac{f_T}{f_\beta}\right)^2}}$

$\frac{f_T}{f_\beta} \gg 1 \Rightarrow 1 = \frac{h_{fe}}{f_T/f_\beta} \Rightarrow \boxed{f_T = h_{fe} f_\beta}$

Relation b/w f_p , f_T and C_D & C_T .

$$f_p = \frac{1}{2\pi RC}$$

$$= \frac{1}{2\pi \beta r_e (C_D + C_T(1 + A_V))}$$

$A_V = 0$ (Short ckt load)

$$\boxed{f_p = \frac{1}{2\pi \beta r_e (C_D + C_T)}}$$

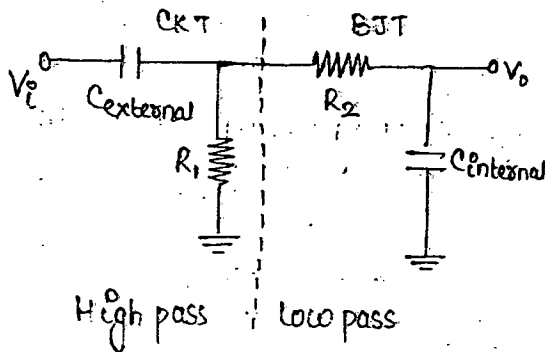
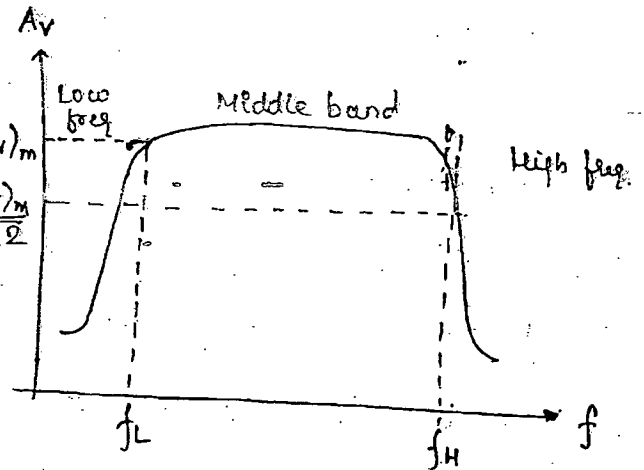
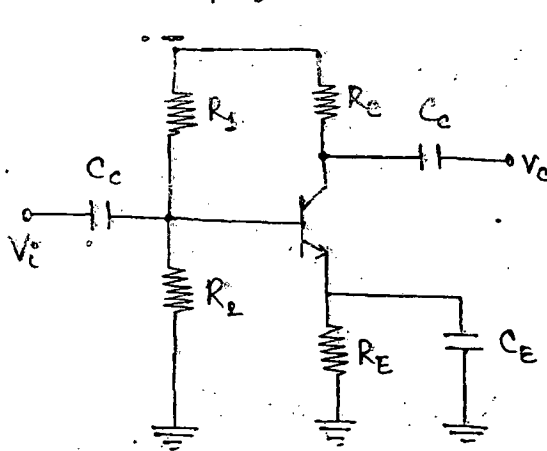
$$\boxed{f_T = \frac{1}{2\pi r_e (C_D + C_T)}}$$

$$\boxed{f_T = \frac{g_m}{2\pi (C_D + C_T)}}$$

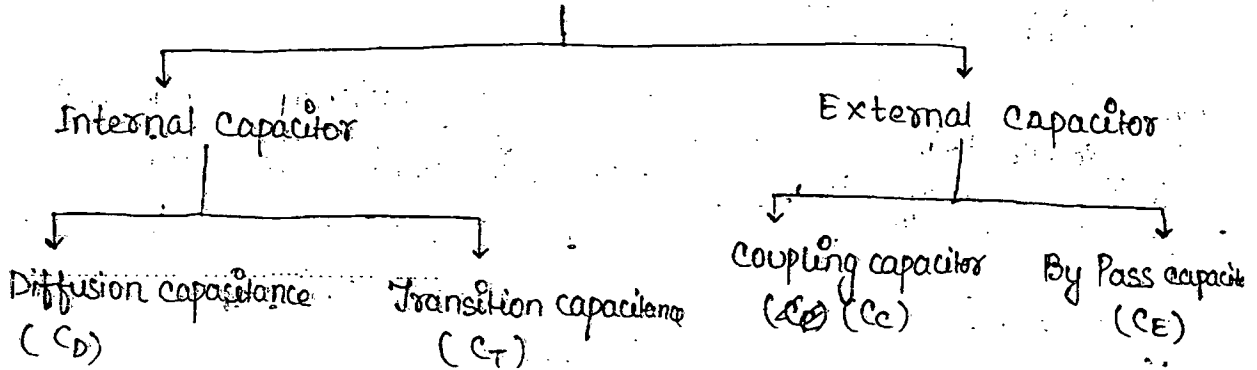
$$\boxed{f_\alpha = (1 + \beta) f_p}$$

Voltage Gain vs frequency

CE Amplifier



CAPACITORS



→ LOW FREQUENCY RANGE

- * At low frequency range Internal capacitor C_D and C_T are neglected because they are open circuit.
- * But when the external capacitors C_c and C_E when they are open ckt they will create a problem for system response.

* The System response at low frequency range is a high pass response.

* T.F of high pass $T.F = \frac{s}{s + \frac{1}{R_1 C_1}} \rightarrow \text{one pole, one zero.}$

→ HIGH FREQUENCY RANGE.

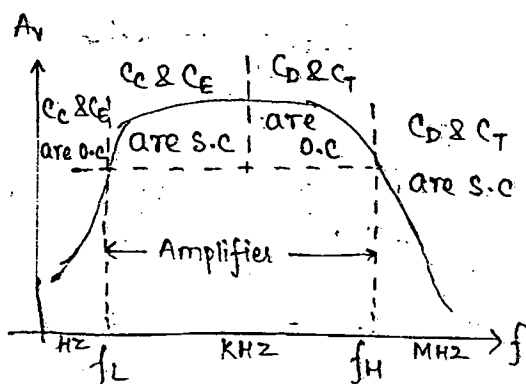
* At high frequency range external capacitor C_c & C_e are neglected because they are s.c.

* But the internal capacitance C_D & C_T when they are assumed to be s.c they will be create a problem for a system response

* The System response at high frequency range is a low pass response.

* T.F of low pass $T.F = \frac{k}{s + \frac{1}{R_2 C_2}} \rightarrow \text{one pole}$

→ MID BAND RANGE.



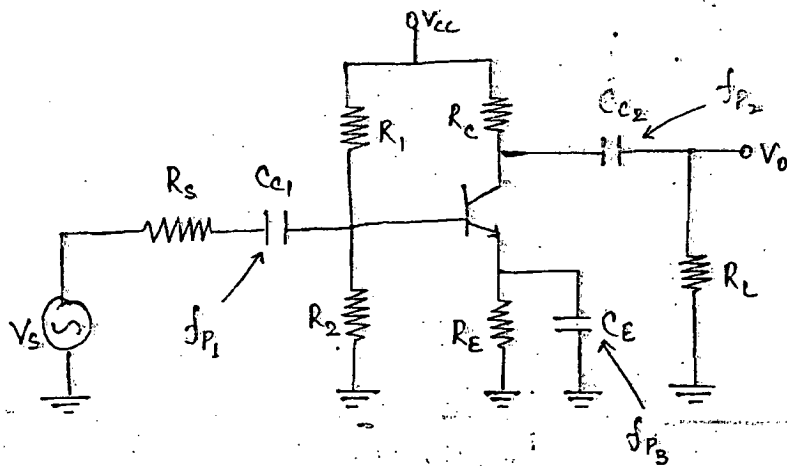
* In low frequency range mid band ^{range} frequency are considered as high frequency. Therefore external capacitor C_c & C_e are assumed to be s.c.

* At high frequency range mid band range frequency are considered as low frequency therefore internal capacitor C_D & C_T are assumed to be open ckted.

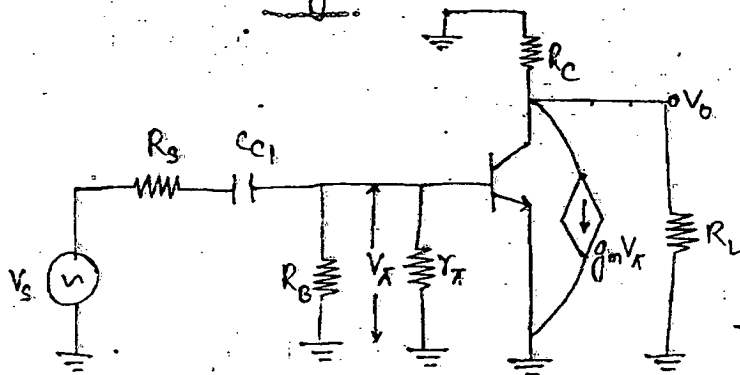
* In the Mid band range all the internal & external

capacitors are neglected. Therefore gain is independent of frequency.

□ LOWER 3dB FREQUENCY DESIGN



→ Pole Frequency across C_{c1}



$$V_o = -g_m V_{\pi} R_C \parallel R_L$$

$$V_{\pi} = \frac{V_s \times R_B \parallel r_{\pi}}{R_B \parallel r_{\pi} + R_s + \frac{1}{sC_{c1}}}$$

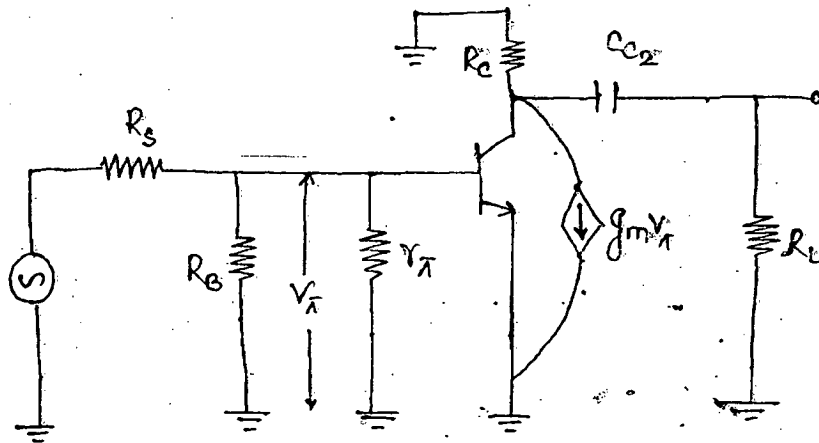
$$\frac{V_o}{V_s} = \frac{-g_m R_C \parallel R_L \cdot R_B \parallel r_{\pi}}{(R_s + R_B \parallel r_{\pi})} \cdot \frac{s}{s + \frac{1}{C_{c1}(R_B \parallel r_{\pi} + R_s)}}$$

$$\frac{V_o}{V_s} = \frac{-g_m R_C \parallel R_L \cdot R_B \parallel r_{\pi}}{(R_s + R_B \parallel r_{\pi})} \cdot \frac{s}{s + \frac{1}{C_{c1}(R_B \parallel r_{\pi} + R_s)}}$$

↓
= $(A_v)_m$

$$\omega_{P1} = \frac{1}{C_{c1}(R_B \parallel r_{\pi} + R_s)}$$

→ Pole frequency across C_{c2} .



$$V_o = I_L \cdot R_L$$

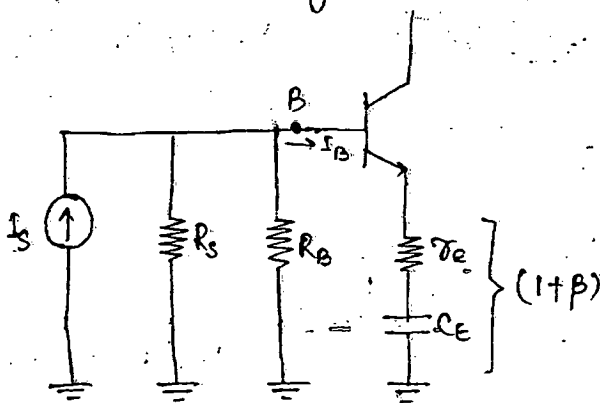
$$V_o = \frac{-g_m V_\pi \times R_c}{R_c + R_L + \frac{1}{sC_{c2}}} \cdot R_L$$

$$V_\pi = \frac{V_s \times R_b // r_\pi}{R_b // r_\pi + R_s}$$

$$\frac{V_o}{V_s} = \underbrace{\left[\frac{-g_m \cdot R_b // r_\pi \cdot R_c \cdot R_L}{R_b // r_\pi + R_s (R_c + R_L)} \right]}_{A_m} \cdot \frac{s}{s + \frac{1}{C_{c2}(R_c + R_L)}}$$

$$\omega_{p2} = \frac{1}{C_{c2}(R_c + R_L)}$$

→ Pole frequency across C_E



$$I_B = \frac{I_s \times R_s // R_b}{R_s // R_b + (1 + \beta) r_e + \frac{(1 + \beta)}{sC_E}}$$

$$(R_s // R_b + (1 + \beta) r_e) \cdot 1 + \frac{1 + \beta}{sC_E (R_s // R_b + (1 + \beta) r_e)}$$

$$s + \frac{1}{C_E \left(\frac{(1 + \beta) r_e}{1 + \beta} + \frac{R_s // R_b}{(1 + \beta)} \right)}$$

Practically

$$R_s \approx 0$$

$$\frac{s}{s + \frac{1}{C_E r_e}}$$

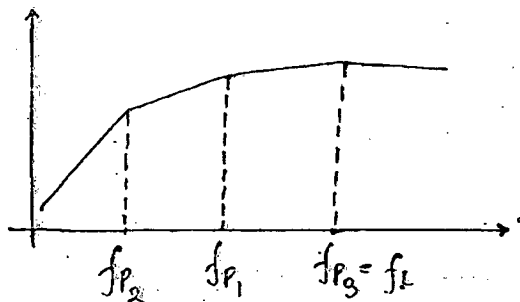
$$\omega_{p3} = \frac{1}{C_E r_e}$$

CONCLUSION:- 1) $f_{P_1}(C_{C_1}) = \frac{1}{2\pi C_{C_1}(R_S + R_B // r_{\pi})}$

2) $f_{P_2}(C_{C_2}) = \frac{1}{2\pi C_2(R_C + R_L)}$

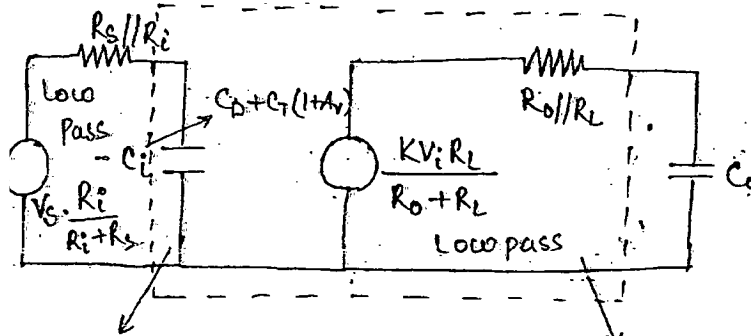
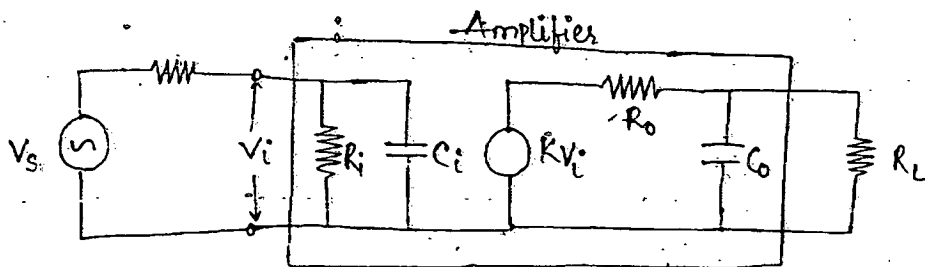
$$f_{P_2} < f_{P_1} < f_{P_3}$$

3) $f_{P_3}(C_E) = \frac{1}{2\pi C_E r_e}$



$$f_L = \frac{1}{2\pi C_E r_e}$$

□ HIGHER 3dB FREQUENCY DESIGN.



T_i = Input time constant

$$T_i = \frac{R_S \cdot R_i}{R_S + R_i} \times C_i$$

T_o = Output time constant

$$T_o = \frac{R_o R_L}{R_o + R_L} \times C_o$$

$$T.F = \frac{K_i}{1 + sT_i}$$

$$K_1 \cdot K_2 = K$$

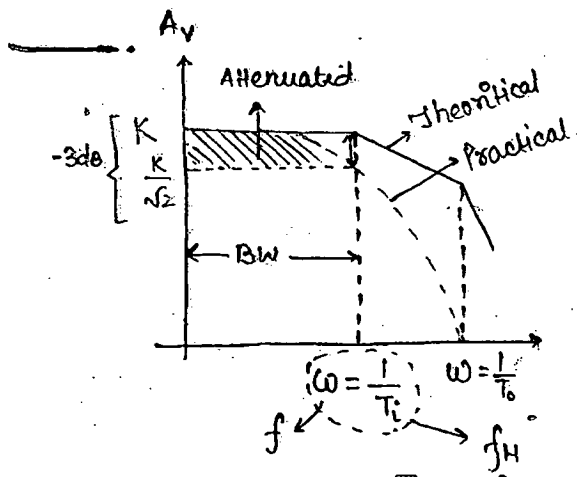
$$T.F = \frac{K_2}{1 + sT_o}$$

$$T.F = \frac{K}{(1 + sT_i)(1 + sT_o)}$$

$$\Rightarrow T.F = \frac{K}{1 + sT_i}$$

$$\Rightarrow |T.F| = \frac{K}{\sqrt{1 + \omega^2 T_i^2}}$$

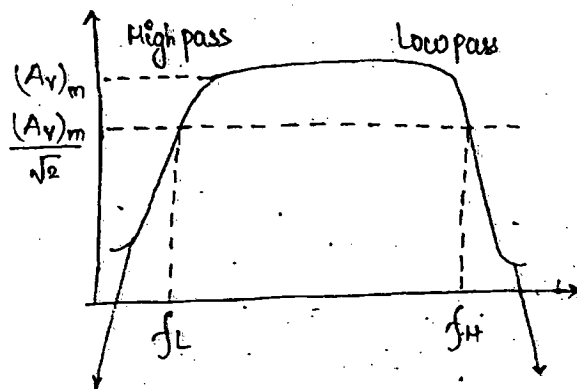
$$T_i \gg T_o$$



$$1.f = \frac{K}{\sqrt{2}}$$

$$f_H = \frac{1}{2\pi \beta R_E (C_D + C_T (1+A_v))}$$

□ PHASE ANALYSIS.



Lower cut off frequency.

$$\theta_L = + \tan^{-1} \left(\frac{f_L}{f} \right)$$

Where $f \rightarrow f_L$

$$\theta_L = \tan^{-1} 1 = 45^\circ$$

$$(A_v)_L = \frac{(A_v)_m}{1 - j \left(\frac{f_L}{f} \right)}$$

$$(A_v)_h = \frac{(A_v)_m}{1 + j \left(\frac{f}{f_H} \right)}$$

Higher cut off frequency.

$$\theta_h = - \tan^{-1} \left(\frac{f}{f_H} \right)$$

where $f \rightarrow f_H$

$$\theta_h = - \tan^{-1} 1 = -45^\circ$$

$$\theta_{LCE} = 180^\circ + \theta_L = 225^\circ$$

$$\theta_{hCE} = 180^\circ + \theta_h = 180^\circ - 45^\circ = 135^\circ$$

□ APPROXIMATE MODEL ANALYSIS IN LOW FREQUENCY. (CE)

Conditions.

1. $h_{oe} R_L \leq 0.1$

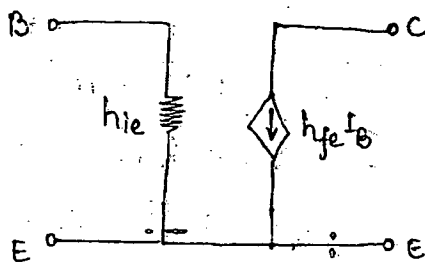
Ex :- $A_I = \frac{-h_{fe}}{1+h_{oe} R_L} = \frac{-h_{fe}}{1+0.1} = -0.91 h_{fe}.$

$R_L \leq 5K$

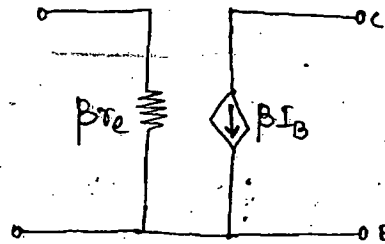
2. h_{re} and h_{oe} are neglected.

3. It is valid only in CE mode.

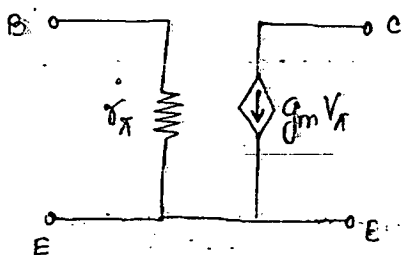
h -parameter model



r_e model



V_{π} Model



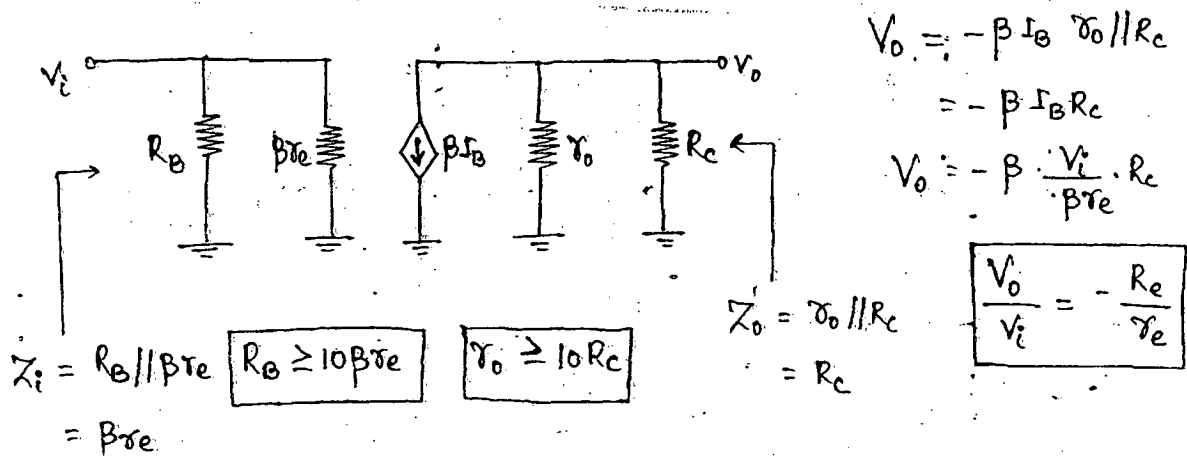
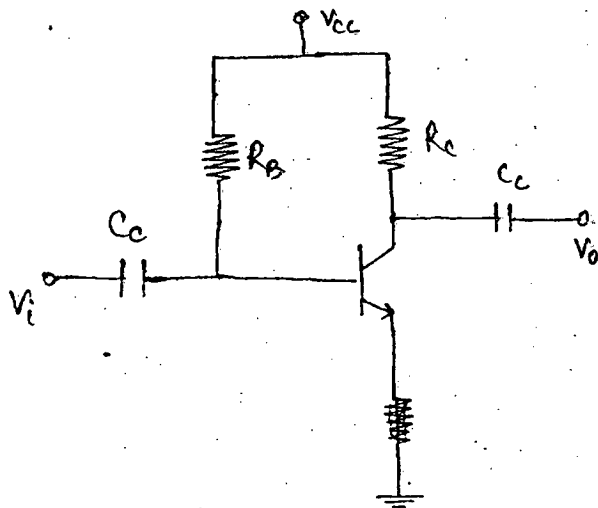
$h_{ie} = \beta r_e = r_{\pi}$

$h_{fe} I_B = \beta I_B = g_m V_{\pi}$

□ AMPLIFIERS MODELS.

1. Common Emitter bypass amplifier
2. Common emitter w/ bypass amplifier
3. Common collector amplifier
4. Common Base amplifier.

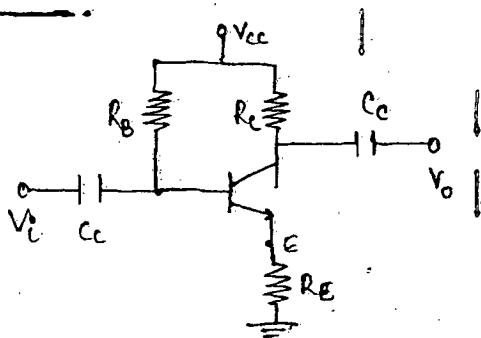
1. CE BY PASS AMPLIFIER

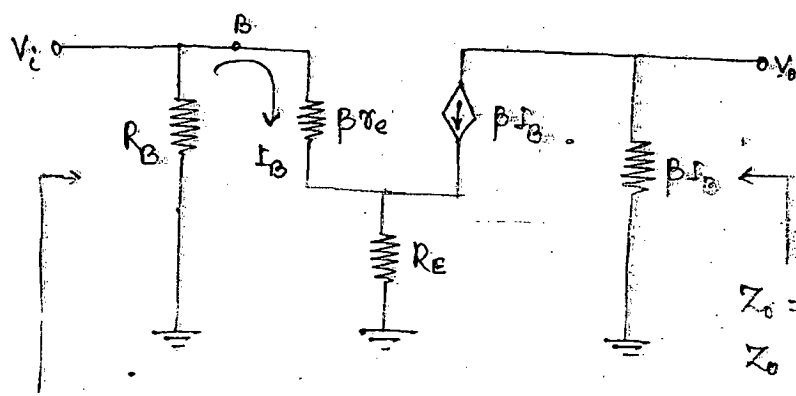


Drawback :- 1. The gain is unstable because of dynamic resistance r_e .

2. The i/p Impedance is low (For ideal ampl^r $Z_i = \infty$).

2. CE UN BY PASS AMPLIFIER.





$$V_o = -\beta I_B r_o \parallel R_C$$

$$= -\beta I_B R_C$$

$$= -\beta \cdot \frac{V_i}{\beta R_E} \cdot R_C$$

$$\frac{V_o}{V_i} = -\frac{R_C}{R_E}$$

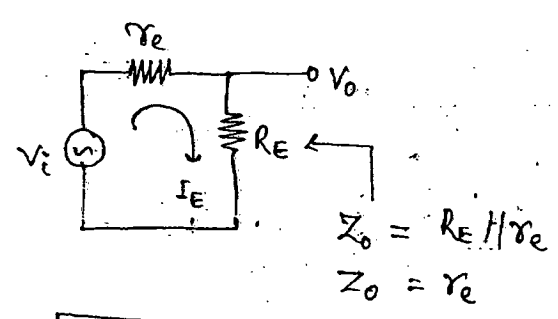
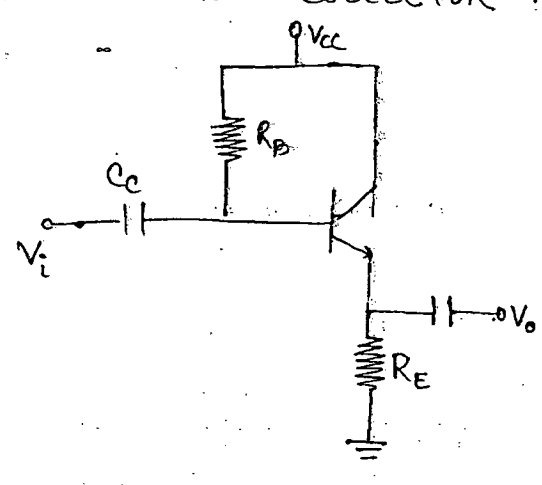
↓
Stability

$$Z_i = R_B \parallel \beta r_e + (1 + \beta) R_E$$

$$Z_i = R_B \parallel \beta R_E \quad \boxed{\beta R_E \geq 10 \beta r_e}$$

↓
high i/p Impedance

8. COMMON COLLECTOR AMPLIFIER.

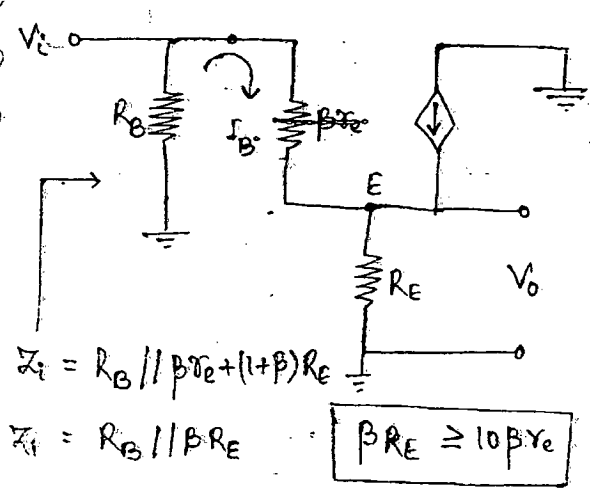


$$A_V = \frac{V_o}{V_i} = \frac{R_E}{R_E + r_e}$$

$$A_V = A_I \frac{Z_L}{Z_i}$$

$$1 = A_I \frac{Z_L}{Z_i} \quad \text{For Buffer } A_V = 1$$

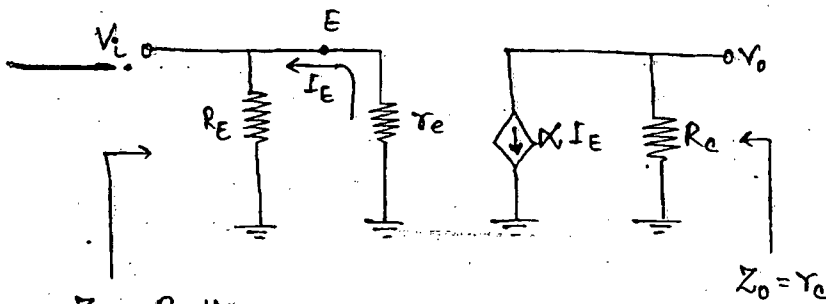
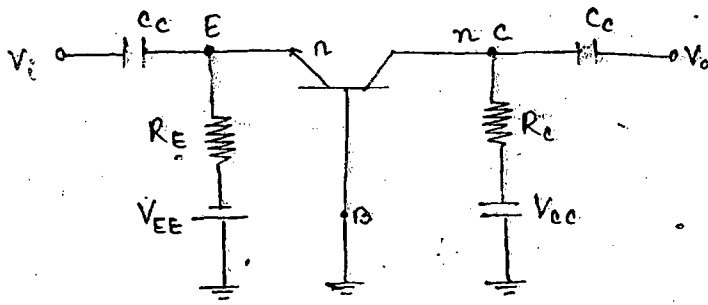
$$\boxed{Z_i = A_I Z_L}$$



$$Z_i = R_B \parallel \beta r_e + (1 + \beta) R_E$$

$$Z_i = R_B \parallel \beta R_E \quad \boxed{\beta R_E \geq 10 \beta r_e}$$

4. COMMON BASE COLLECTOR AMPLIFIER.



$$V_o = -\alpha I_E R_c$$

$$V_o = -\alpha \left(-\frac{V_i}{r_e} \right) R_c$$

$$\boxed{\frac{V_o}{V_i} = \frac{R_c}{r_e}} \quad \alpha \approx 1$$

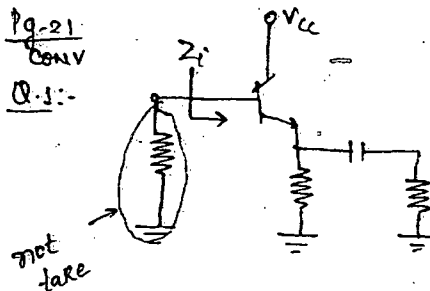
$$Z_i = R_E \parallel r_e$$

$$Z_i = r_e$$

$$Z_o = r_e$$

pg-21
conv

Q.1:-



$$A_v = A_1 \frac{Z_L}{Z_i}$$

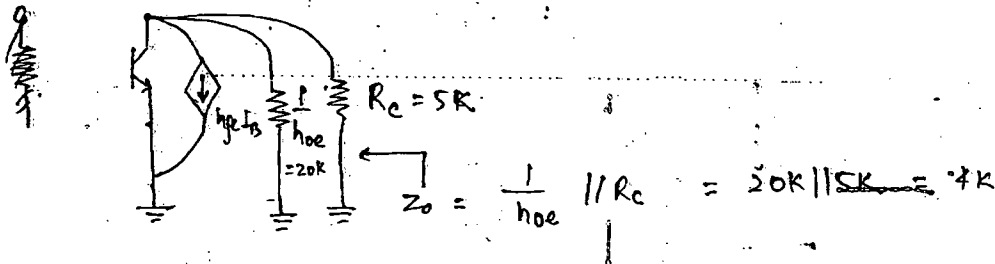
$\Rightarrow$ C becomes short cir.

$$1 = A_1 \frac{Z_L}{Z_i}$$

$$Z_i = A_1 Z_L = \beta R_E \parallel R_L$$

Q2. $h_{fe} = 100$; $h_{ie} = 2k\Omega$; $h_{re} = 0$; $h_{oe} = 0.05m mhos = \frac{1}{0.05}$

$$= 20k\Omega$$

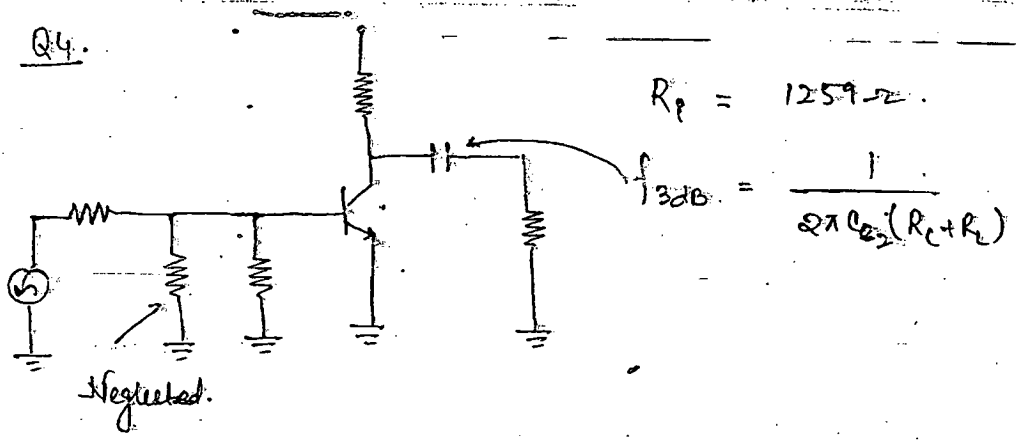


$$Z_o = \frac{1}{h_{oe}} \parallel R_c = 20k \parallel 5k = 4k$$

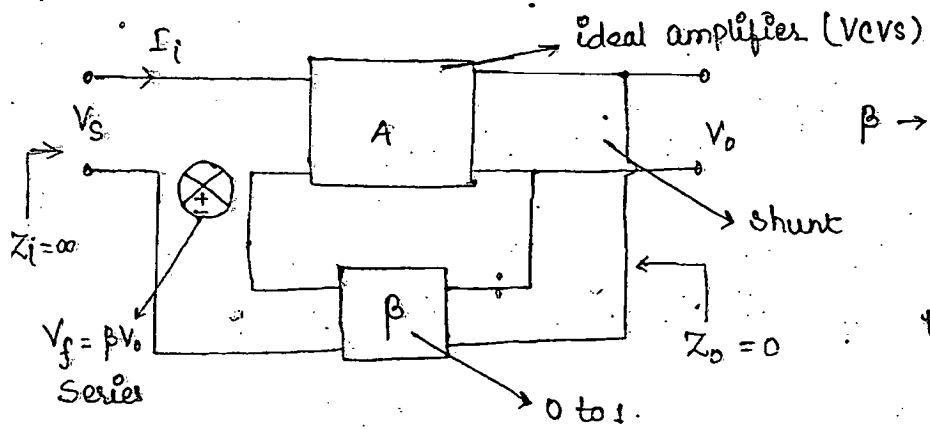
Q3. $\frac{V_o}{V_s} = -\frac{R_c}{r_e} = -\frac{4k}{25mV} \times 1mA \Rightarrow \frac{4000}{25} = -160$
Phase Shift.

$$r_e = \frac{V_i}{(I_E)_Q} = \frac{25mV}{1mA} = 25$$

Q4.



FEEDBACK AMPLIFIER.



$\beta \rightarrow$ Feedback fraction
(or)
Feedback Ratio
(or)
Reverse transmission factor.

Positive feedback

$$V_o = AV_i \quad \boxed{1 - A\beta = 0}$$

$$V_i = V_s + V_f \quad \boxed{A\beta = 1}$$

$$V_o = A(V_s + \beta V_o)$$

$$V_o(1 - A\beta) = AV_s$$

$$\boxed{\frac{V_o}{V_s} = \frac{A}{1 - A\beta}}$$

Negative feedback.

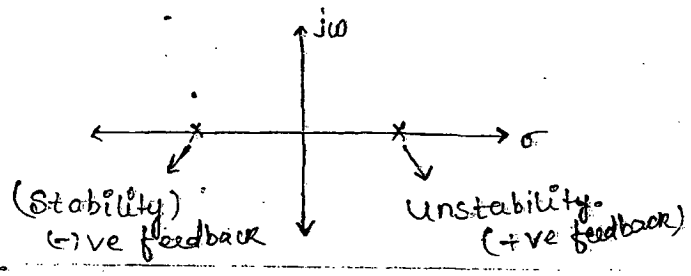
$$V_o = AV_i \quad \boxed{1 + A\beta = 0}$$

$$V_i = V_s - V_f \quad \boxed{A\beta = -1}$$

$$V_o = A(V_s - \beta V_o)$$

$$V_o(1 + A\beta) = AV_s$$

$$\boxed{\frac{V_o}{V_s} = \frac{A}{1 + A\beta}}$$



CONCLUSION:- 1. $A_{pf} > A > A_{nf}$

$$2. A_{nf} = \frac{A}{1 + A\beta}$$

$$A_v = \frac{R_c}{r_e} = \frac{1k\Omega}{1\Omega} = 10^3 \quad A\beta \gg 1$$

$$\beta = 0 \text{ to } 1.$$

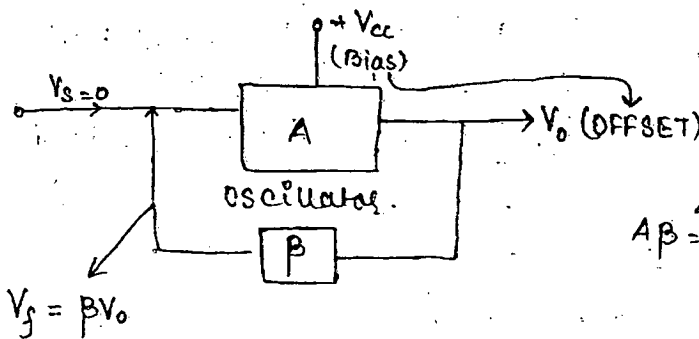
$$A_{nf} = \frac{1}{\beta}$$

↓
Stability Concept.

Negative feedback is always applied for stable system like Amplifiers. (Stable Amplifiers).

$$3. A_{pf} = \frac{A}{1 - A\beta}$$

$$|A\beta| = 1 \quad A_{pf} = \frac{V_o}{V_s} = \frac{A}{0} \quad \boxed{V_s = 0}$$



$$A = \frac{V_o}{V_i} ; \beta = \frac{V_s}{V_o}$$

$$A\beta = 1 \Rightarrow \frac{V_o}{V_i} \cdot \frac{V_f}{V_o} = 1$$

$$\Rightarrow \boxed{V_f = V_i}$$

↓
oscillator.

□ NEGATIVE FEEDBACK AMPLIFIER. ADVANTAGE

ADVANTAGE:-

1. Stability of ac gain:- Suppose there is small change in the internal resistance r_e of an amplifier. Then the fractional change of gain with feedback is $\frac{\partial A_f}{A_f}$

$$A_f = \frac{A}{1 + A\beta}$$

d. w. r. t A

$$\frac{\partial A_f}{\partial A} = \frac{(1 + A\beta) \cdot 1 - A\beta}{(1 + A\beta)^2}$$

$$\frac{\partial A_f}{\partial A} = \frac{1}{(1 + A\beta)^2} \cdot \frac{\partial A}{A_f}$$

$$\frac{\partial A_f}{A_f} = \frac{1}{(1+AB)^2} \cdot \frac{\partial A}{A} \cdot (1+AB)$$

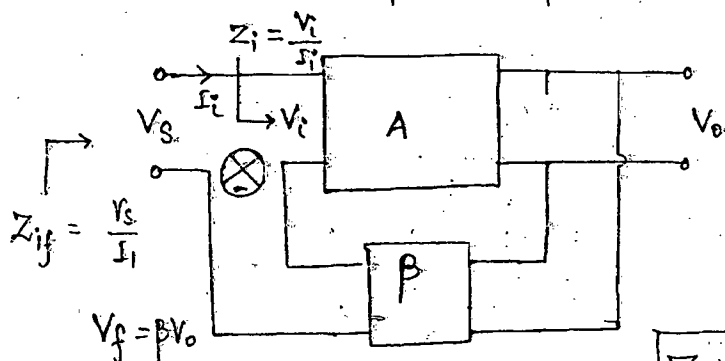
$$\frac{\partial A_f}{A_f} = \frac{1}{(1+AB)} \cdot \frac{\partial A}{A}$$

$$\frac{1}{1+AB} = \text{Sensitivity (S)}$$

$$1+AB = \text{Desensitivity (D)}$$

$$\frac{\partial A_f}{A_f} < \frac{\partial A}{A}$$

2. Increase in Input Impedance with Series fo.



$$V_i = V_s - V_f$$

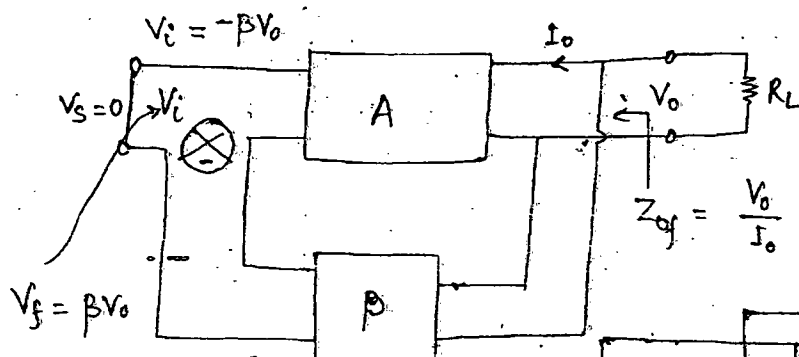
$$= V_s - \beta V_o$$

$$V_i = V_s - ABV_i$$

$$\frac{V_i}{I_i} (1+AB) = \frac{V_s}{I_i}$$

$$Z_{if} = Z_i (1+AB)$$

3. Decrease in o/p Impedance by shunt-feedback.

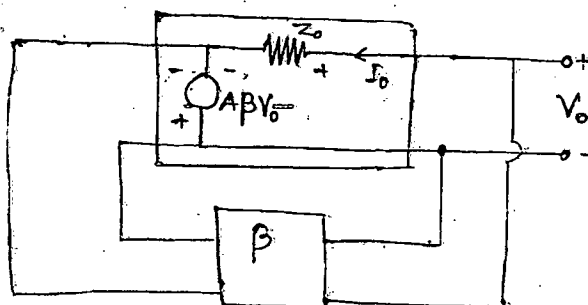


KVL @ o/p loop

$$V_o + ABV_o = I_o Z_o$$

$$V_o (1+AB) = I_o Z_o$$

$$Z_{of} = \frac{V_o}{I_o} = \frac{Z_o}{1+AB}$$



4. Linearity

$$V_i \rightarrow \boxed{A} \rightarrow V_o = V_{\text{offset}} + AV_i + K_1 V_i^2 + K_2 V_i^3 + \dots$$

$$\begin{aligned} E &= V_i - \beta V_o \\ V_i \rightarrow \otimes \rightarrow \boxed{A} \rightarrow V_o &= V_{\text{offset}} + AE + K_1 E^2 + K_2 E^3 + \dots \\ V_f &= \beta V_o \rightarrow \boxed{\beta} \rightarrow \end{aligned}$$

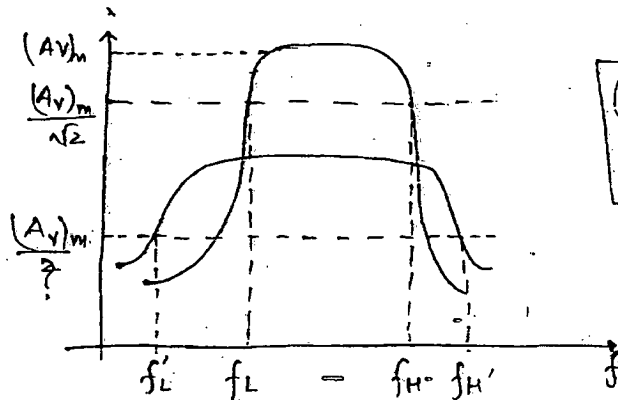
$$= V_{\text{offset}} + A(V_i - \beta V_o) + K_1 E^2 + K_2 E^3 + \dots$$

$$V_o (1 + A\beta) = V_{\text{offset}} + AV_i + K_1 E^2 + K_2 E^3 + \dots$$

$$V_o = \frac{V_{\text{offset}}}{1 + A\beta} + \frac{A}{1 + A\beta} V_i + \frac{K_1 E^2 + K_2 E^3}{1 + A\beta} + \dots$$

$$V_o = \frac{A}{1 + A\beta} V_i \quad A\beta \gg 1 \quad \boxed{V_o = \frac{1}{\beta} V_i}$$

5. Increase in Bandwidth with Negative feedback.



Lower cut off frequency.

$$(A_v)_L = \frac{(A_v)_m}{1 - j\left(\frac{f_L}{f}\right)} \rightarrow \text{without feedback.}$$

$$(A_v)_{Lf} = \frac{(A_v)_L}{1 + (A_v)_L \beta}$$

$$(A_v)_{Lf} = \frac{(A_v)_m}{1 - j\left(\frac{f_L}{f}\right)} \cdot \frac{1}{1 + \frac{(A_v)_m \beta}{1 - j\left(\frac{f_L}{f}\right)}} = \frac{(A_v)_m}{1 + (A_v)_m \beta - j\left(\frac{f_L}{f}\right)}$$

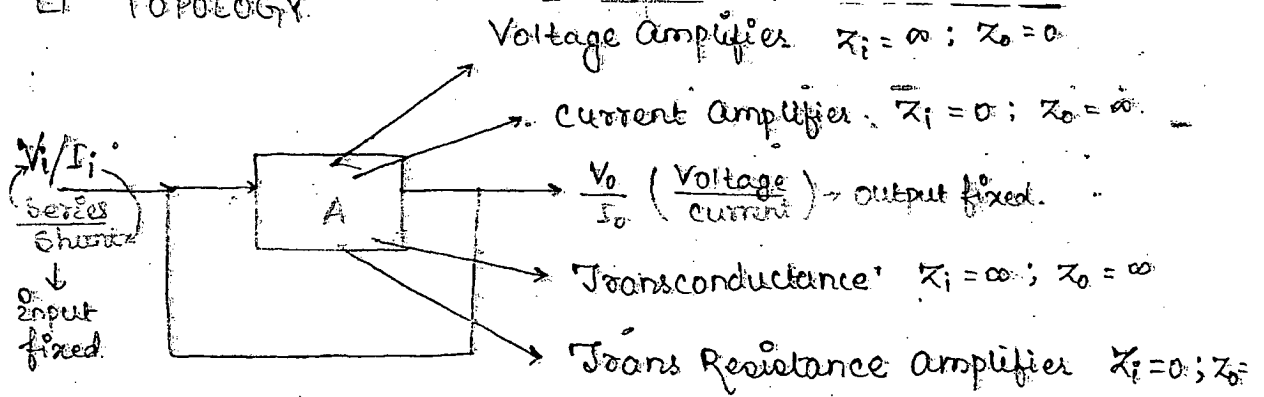
$$(A_v)_{Lf} = \frac{\frac{(A_v)_m}{1 + (A_v)_m \beta}}{1 - j\left(\frac{f_L}{1 + (A_v)_m \beta}\right) \cdot \frac{1}{f}}$$

where $f_L' = \frac{f_L}{1 + (A_v)_m \beta}$

$$f_H' = f_H (1 + (A_v)_m \beta)$$

→ with feedback

□ TOPOLOGY.



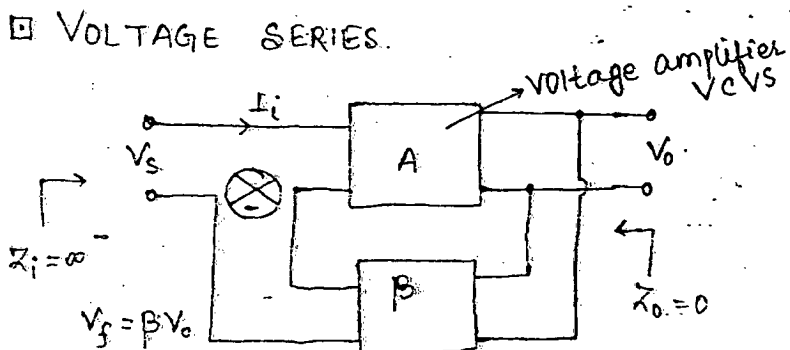
Topology
o/p
Voltage Series
Voltage Shunt
Current Series
Current Shunt

Topology
i/p
Series voltage
Shunt voltage
Series current
Shunt current

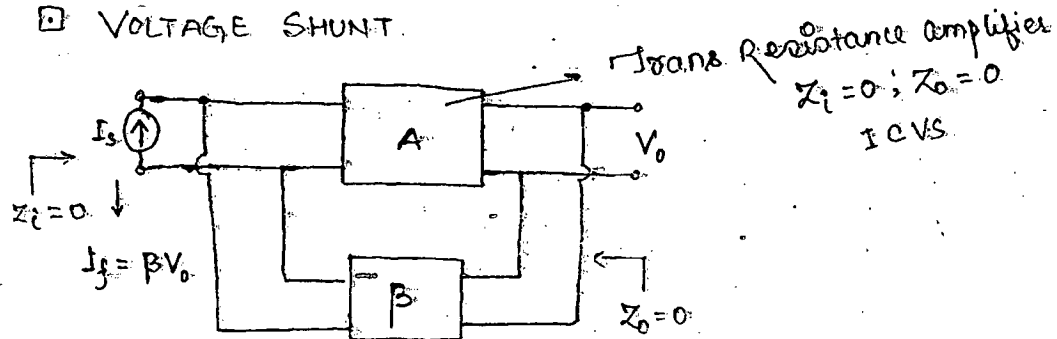
Topology
i/p
Series Shunt
Shunt Series
Series Series
Shunt Series

Topology
o/p
Voltage voltage
Voltage current
current voltage
current current

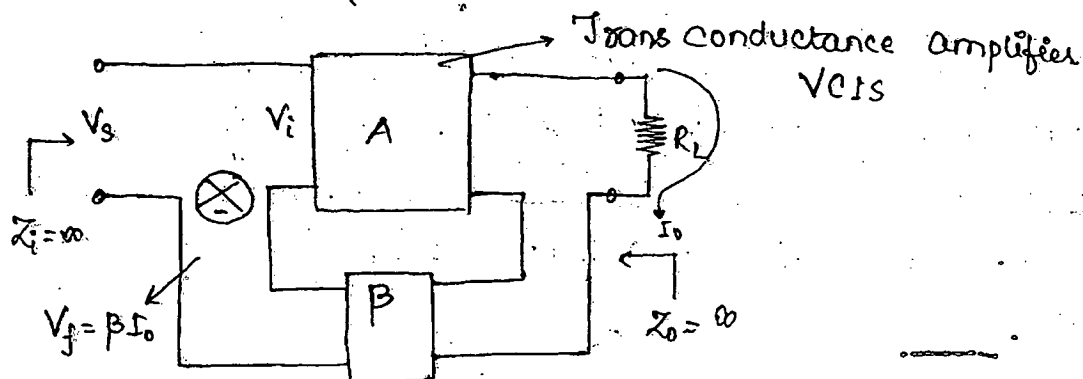
□ VOLTAGE SERIES.



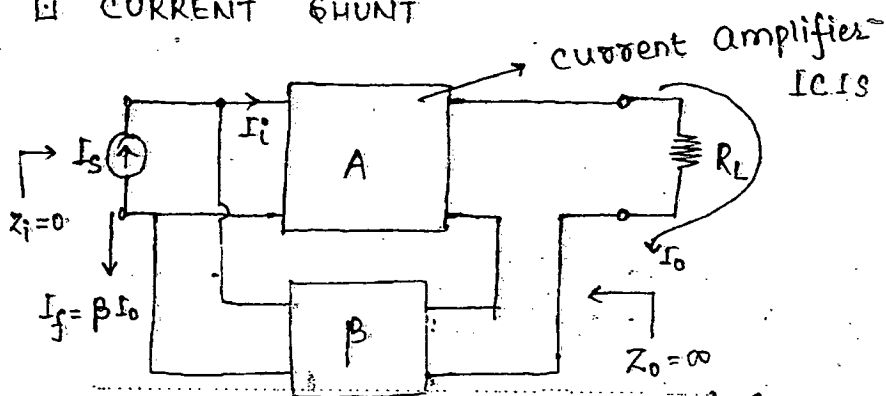
□ VOLTAGE SHUNT



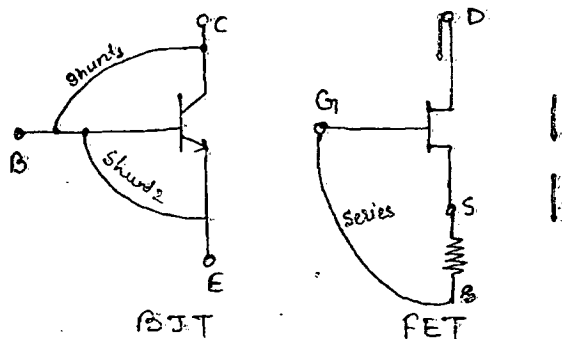
□ CURRENT SERIES

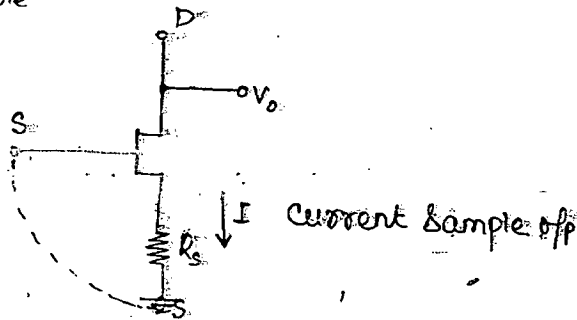
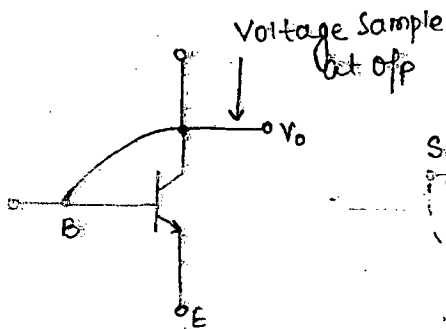


□ CURRENT SHUNT

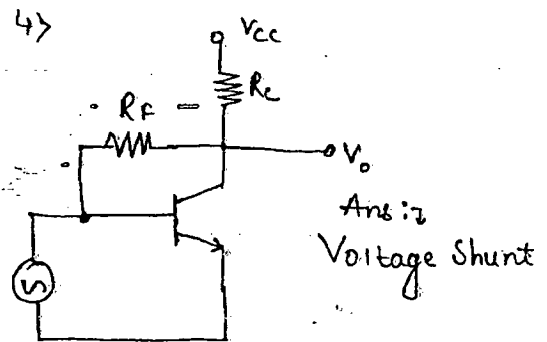
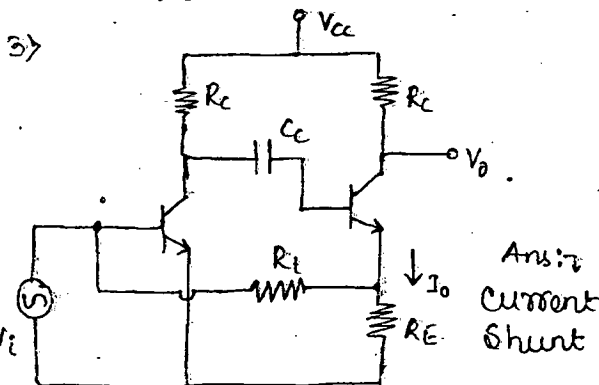
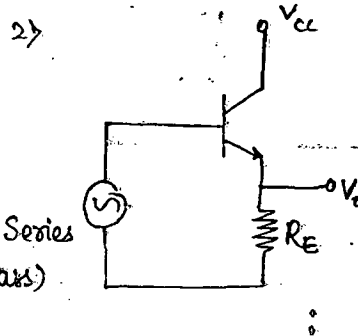
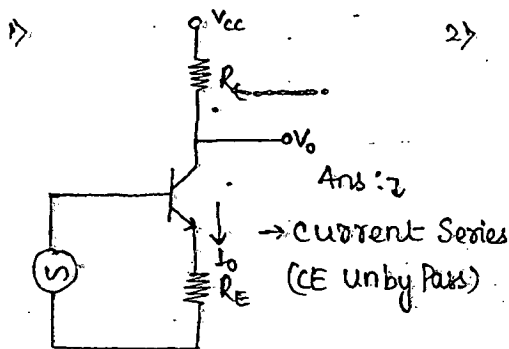


□ FEEDBACK ANALYSIS (BJT AND FET)

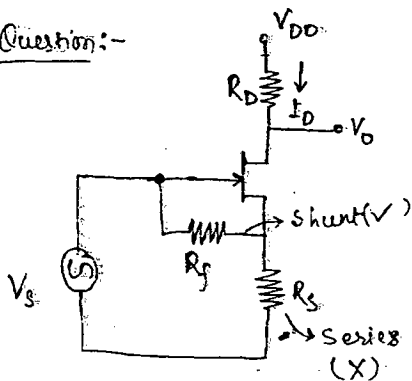




Question:-

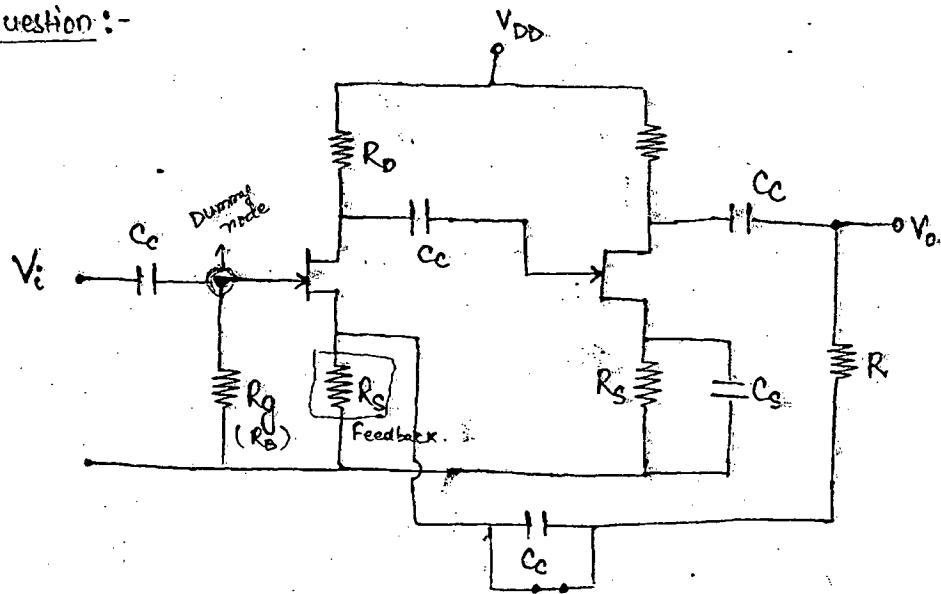


Question:-



Whenever Series & Shunt feedback are connected at a time in the ckt, shunt dominates the series effect.
∴ Voltage Shunt.

Question:-



Ans:~
Voltage series