

Alternating Current

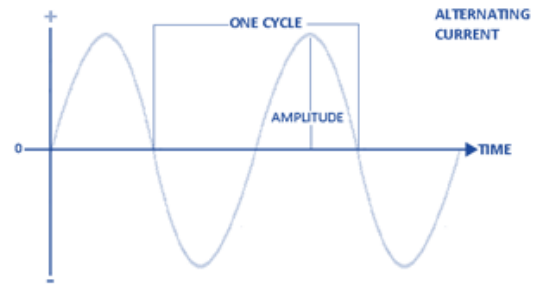
Alternating Current:

An alternating current (a.c.) is a current which continuously, changes in magnitude and periodically reverse in direction'.

$$i = I_0 \sin \omega t = I_0 \sin (2\pi/T) t$$

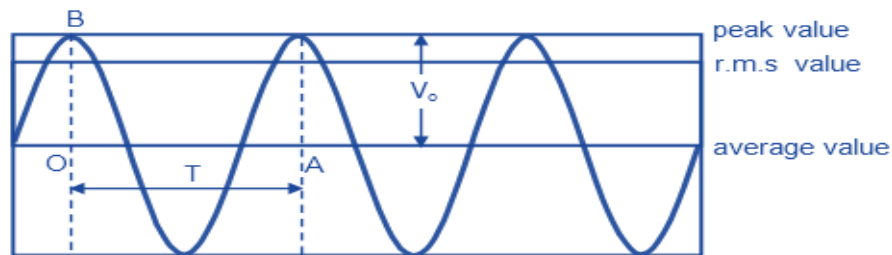
Here I_0 is the peak value of a.c.

- (a) Current, $I = I_0 \sin \omega t$
- (b) Angular frequency, $\omega = 2\pi n$ (n is the frequency of a.c.)
- (c) $I = I_0 \sin 2\pi nt$



- **Mean value of A.C or D.C. value of A.C.:-**

Mean value of a.c. is that value of steady current which sends the same amount of charge, through a circuit, in same time as is done by a.c. in one half-cycle.



$$(I_{av})_{\text{half cycle}} = (2/\pi)I_0$$

Thus, mean value of alternating current is $2/\pi$ times (0.637 times) its peak value.

$$(V_{av})_{\text{half cycle}} = (2/\pi) V_0$$

- **Average value of A.C. over a complete cycle:-**

$$I_{av} = 0$$

The average value of a.c. taken over the complete cycle of a.c. is zero.

- **Root mean square value of a.c. or virtual value of a.c.:-**

Root mean square value of alternating current is defined as that value of steady current which produces same heating effect, in a resistance, in a certain time as is produced by the alternating current in same resistance in same time. The r.m.s value of a.c. is also called its virtual value.

$$I_{rms} = I_0/\sqrt{2}$$

Root mean square value of alternating current is $I/\sqrt{2}$ times (or 0.707 times) the peak value of current.

Similarly, $V_{rms} = V_0/\sqrt{2}$

Here V_0 is the peak value of *e.m.f.*

- **Form Factor:-**

Form Factor = rms value/average value = $(V_0/\sqrt{2}) / (2 V_0/\pi) = \pi/2\sqrt{2}$

- **Current elements:-**

(a) Inductive reactance:- $X_L = \omega L$

Here, $\omega = 2\pi n$, n being frequency of *a.c.*

L is the coefficient of self-inductance of coil.

(b) Capacitive reactance:- $X_C = 1/\omega C$

Here C is the capacity of the condenser

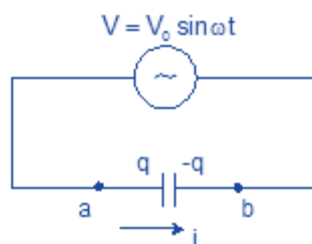
- **Capacitor in AC circuit:-**

$$q = CV_0 \sin \omega t$$

$$I = I_0 \sin(\omega t + \pi/2)$$

$$V_0 = I_0/\omega C$$

$$X_C = 1/\omega C$$



- **Inductor in AC circuit:-**

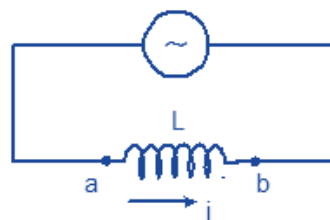
$$V_L = L(di/dt) = LI_0 \omega \cos \omega t$$

$$I = (V_0/\omega L) \sin \omega t$$

$$\text{Here, } I_0 = V_0/\omega L$$

$$X_L = \omega L$$

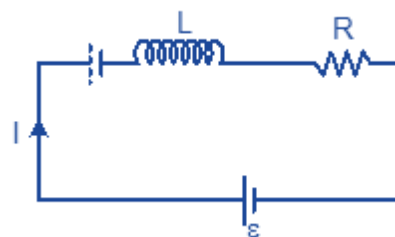
And the maximum current, $I_0 = V_0/X_L$



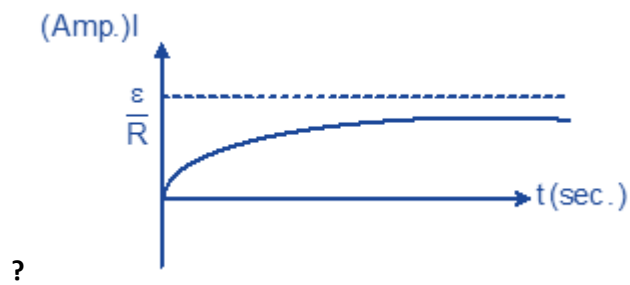
- **R-L circuit:-**

$$? I = \mathcal{E}/R [1 - e^{-Rt/L}]$$

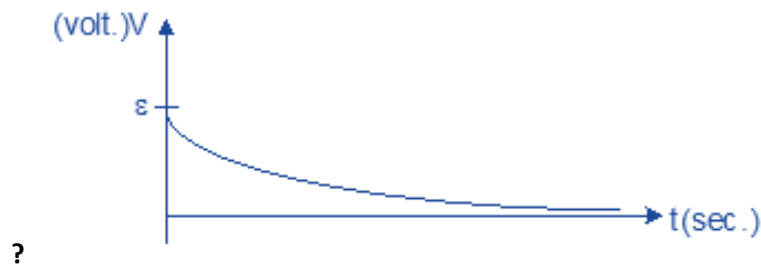
$$V = \mathcal{E} e^{-Rt/L}$$



- Graph between I (amp) and t (sec):-



- Graph between potential difference across inductor and time:-



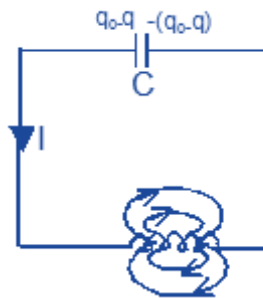
- L-C Circuit:-**

$$f = 1/2\pi\sqrt{LC}$$

$$q = q_0 \sin(\omega t + \phi)$$

$$I = q_0 \omega \sin(\omega t + \phi)$$

$$\omega = 1/\sqrt{LC}$$



- The total energy of the system remains conserved,

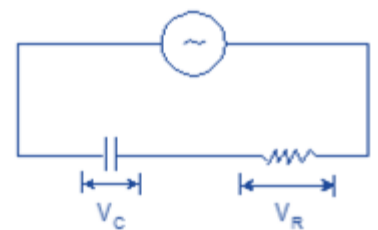
$$\frac{1}{2} CV^2 + \frac{1}{2} Li^2 = \text{constant} = \frac{1}{2} CV_0^2 = \frac{1}{2} Li_0^2$$

- Series in C-R circuit:-**

$$V = IZ$$

$$\text{The modulus of impedance, } |Z| = \sqrt{R^2 + (1/\omega C)^2}$$

$$\text{The potential difference lags the current by an angle, } \phi = \tan^{-1}(1/\omega CR)$$

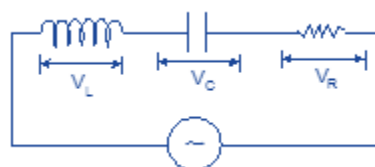


- Series in L-C-R Circuit:**

$$V = IZ$$

$$\text{The modulus of impedance, } |Z| = \sqrt{R^2 + (\omega L - 1/\omega C)^2}$$

$$\text{The potential difference lags the current by an angle, } \phi = \tan^{-1}[(\omega L - 1/\omega C)/R]$$



- **Circuit elements with A.C:-**

| Circuit elements | Amplitude relation | Circuit quantity | Phase of V |
|------------------|--------------------|------------------|-----------------------|
| Resistor | $V_0 = i_0 R$ | R | In phase with i |
| Capacitor | $V_0 = i_0 X_C$ | C | Lags i by 90° |
| Inductor | $V_0 = i_0 X_L$ | $X_L = \omega L$ | Leads i by 90° |

- **Resonance:-**

(a) Resonance frequency:- $f_r = 1/2\pi\sqrt{LC}$

(b) At resonance, $X_L = X_C$, $\phi = 0$, $Z = R$ (minimum), $\cos\phi = 1$, $\sin\phi = 0$ and current is maximum ($=E_0/R$)

- **Half power frequencies:-**

(a) Lower, $f_1 = f_r - R/4\pi L$ or $\omega_1 = \omega_r - R/2L$

(b) Upper, $f_2 = f_r + R/4\pi L$ or $\omega_2 = \omega_r + R/2L$

- **Band width:-** $\Delta f = R/2\pi L$ or $\Delta f = R/L$

- **Quality Factor:-**

(a) $Q = \omega_r/\Delta\omega = \omega_r L/R$

(b) As $\omega = 1/\sqrt{LC}$, So $Q \propto \sqrt{L}$, $Q \propto 1/R$ and $Q \propto 1/\sqrt{C}$

(c) $Q = 1/\omega_r CR$

(d) $Q = X_L/R$ or $Q = X_C/R$

(e) $Q = f_r/\Delta f$

- **At resonance, peak voltages are:-**

(a) $(V_L)_{res} = e_0 Q$

(b) $(V_C)_{res} = e_0 Q$

(c) $(V_R)_{res} = e_0$

- **Conductance, susceptance and admittance:-**

(a) Conductance, $G = 1/R$

(b) Susceptance, $S = 1/X$

(c) $S_L = 1/X_L$ and $S_C = 1/X_C = \omega C$

(d) Admittance, $Y = 1/Z$

(e) Impedance add in series while add in parallel

- **Power in AC circuits:-**

Circuit containing pure resistance:- $P_{av} = (E_0/\sqrt{2}) \times (I_0/\sqrt{2}) = E_v \times I_v$

Here E_v and I_v are the virtual values of *e.m.f* and the current respectively.

Circuit containing impedance (a combination of R,L and C):-

$$P_{av} = (E_0/\sqrt{2}) \times (I_0/\sqrt{2}) \cos \phi = (E_v \times I_v) \cos \phi$$

Here $\cos \phi$ is the power factor.

(a) Circuit containing pure resistance, $P_{av} = E_v I_v$

(b) Circuit containing pure inductance, $P_{av} = 0$

(c) Circuit containing pure capacitance, $P_{av} = 0$

(d) Circuit containing resistance and inductance,

$$Z = \sqrt{R^2 + (\omega L)^2}$$

$$\cos \phi = R/Z = R/\sqrt{R^2 + (\omega L)^2}$$

(e) Circuit containing resistance and capacitance:-

$$Z = \sqrt{R^2 + (1/\omega C)^2}$$

$$\cos \phi = R/Z = R/\sqrt{R^2 + (1/\omega C)^2}$$

(f) Power factor, $\cos \phi = \text{Real power}/\text{Virtual power} = P_{av}/E_{rms} I_{rms}$

- **Transformer:-**

(a) $C_p = N_p (d\phi/dt)$ and $e_s = N_s (d\phi/dt)$

(b) $e_p/e_s = N_p/N_s$

(c) As, $e_p I_p = e_s I_s$, Thus, $I_s/I_p = e_p/e_s = N_p/N_s$

(d) Step down:- $e_s < e_p$, $N_s < N_p$ and $I_s > I_p$

(e) Step up:- $e_s > e_p$, $N_s > N_p$ and $I_s < I_p$

(f) Efficiency, $\eta = e_s I_s / e_p I_p$

- **AC Generator:-**

$$e = e_0 \sin (2\pi f t)$$

Here, $e_0 = NBA\omega$